



低功耗微控制器應用設計探討



A Leading Provider of Smart, Connected and Secure Embedded Control Solutions



SMART | CONNECTED | SECURE

May 2023

2023 May ESS Sustainability 發掘生態永續共存的商機

Agenda

- ▶ **Low Power MCU's contribution for sustainability**
- ▶ **MCU Power Consumption Fundamentals**
- ▶ **MCU Power Management**
- ▶ **Intelligent Peripherals**
- ▶ **Application System Level Considerations**
- ▶ **Power Debugger Tools**

Low Power MCU's contribution for sustainability

- **Help reduce energy usage**
 - Reduce the need for non-renewable energy sources such as fossil fuels, and reduces air pollution
- **Battery life**
 - Reduces the negative impact of waste batteries on the environment
- **IoT can help monitor and control energy usage**
 - Reduce the need for non-renewable energy sources and promotes sustainable energy use



Green Design to Save the Planet

M

請問電子產品設計時, 如果減少1mW耗電時, 可以降低多少的二氧化碳排放量? 相當於要種幾棵樹才能消耗? 假設該電子產品生產了1萬個, 每日約使用8小時, 然後產品壽命為3年。



要回答這個問題需要考慮多個因素，如產品的使用壽命、使用頻率、產品使用對象、產品生產方式、產品使用時的能源來源等等。以下提供一些大致的估算，但請注意這些數字僅供參考。

減少1mW耗電對應的碳排放減少量：

根據美國能源信息署 (EIA) 提供的資料，每千瓦時的發電在美國平均會釋放約1.22磅的二氧化碳。因此，如果減少1mW的耗電量，每個產品每天使用8小時，壽命為3年，可以減少的碳排放量約為：

$$1\text{mW} \times 8\text{小時} \times 365\text{天} \times 3\text{年} \times 1\text{萬個} \times 1.22\text{磅/千瓦時} \div 1000\text{瓦/千瓦} \approx 84.2\text{磅二氧化碳}$$

種植一棵樹可以抵銷的碳排放量因樹種、生長地點、生長年限等因素而異。一般認為，在20年左右的生長期內，一棵成年的樹可以抵銷約50磅的二氧化碳排放量。因此，減少1mW的耗電量相當於種植：

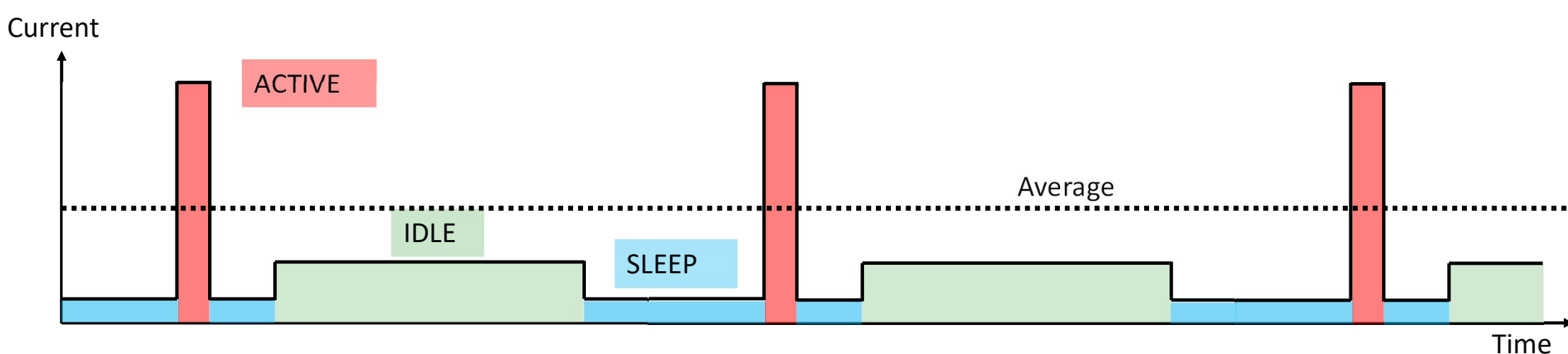
$$84.2\text{磅二氧化碳} \div 50\text{磅二氧化碳/棵} \approx 1.68\text{棵樹}$$

MCU Power Consumption Fundamentals



Instantaneous & Average Currents

- ▶ Device current is a function of both static and dynamic current
- ▶ Instantaneous – current being drawn by the MCU
- ▶ Average – weighted average of instantaneous currents
 - Weighting is based on the duty cycle of the mode of operation
 - Required quantity for calculations like “estimated battery life”



Instantaneous & Average Current cont...

► How do different currents levels affect average current?

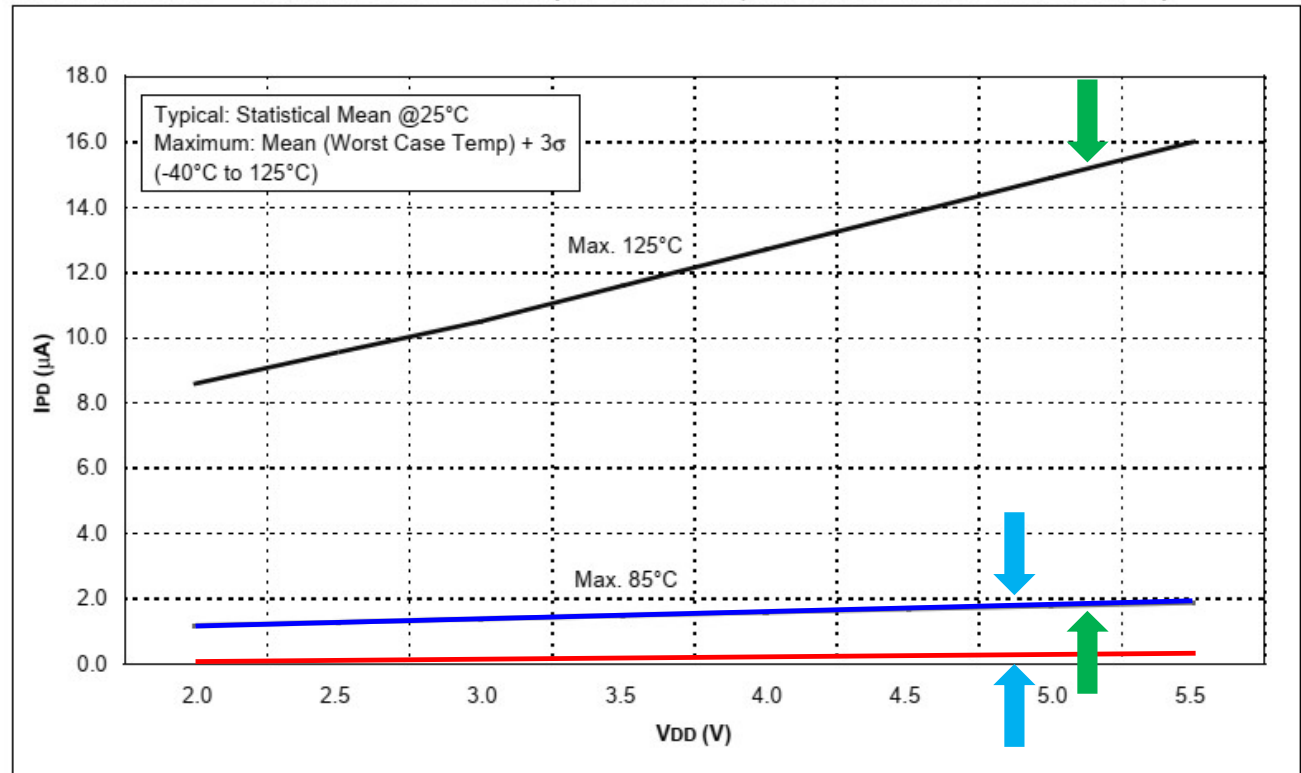
Active Current	Active Duty Cycle	Static Current	Static Duty Cycle	Average Current
5 mA	1%	10 uA	99%	59.9 uA
2.5 mA	1%	10 uA	99%	34.9 uA
50% reduction in active current; 47% reduction in average current				
2.5 mA	1%	5 uA	99%	29.95 uA
50% reduction in static current, 14% reduction in average current				

Understanding the different contributors to power consumption is key to managing power

Temperature - Static Current

- ▶ Temperature as a large effect on the static current
- ▶ PIC16F684 Quiescent current (I_{PD}) shown
 - 1st current delta is $\sim 2\mu A$ over 60C
 - 2nd current delta is $\sim 13\mu A$ over 40C

FIGURE 16-14: MAXIMUM I_{PD} vs. V_{DD} (SLEEP MODE, ALL PERIPHERALS DISABLED)



MCU Power Management



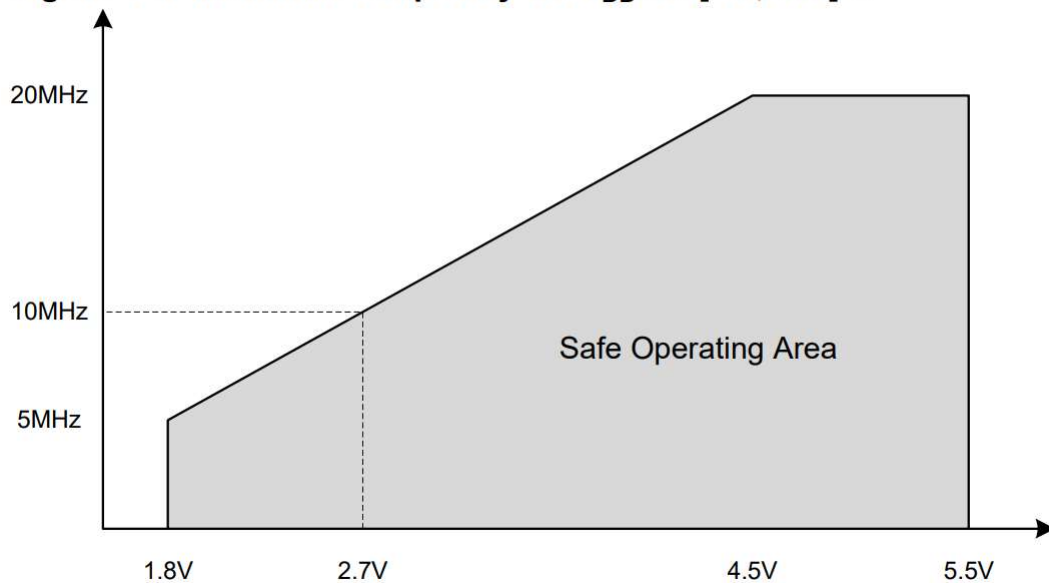
Voltage

Voltage Considerations

- ▶ Performance can scale with supply voltage

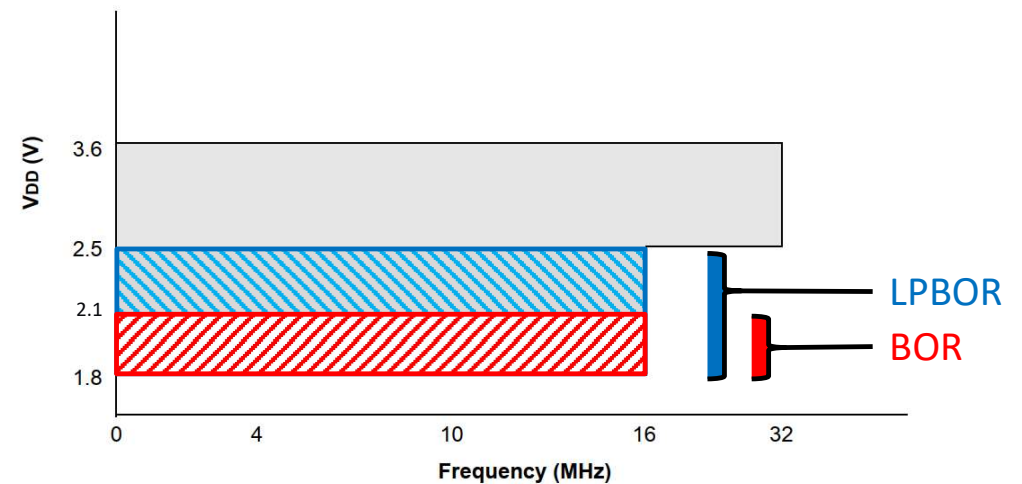
ATmega4809

Figure 4-1. Maximum Frequency vs. V_{DD} for $[-40, 105]^{\circ}\text{C}$



- Supervisors can affect minimum voltage requirements

PIC16LF18325



Note 1: The shaded region indicates the permissible combinations of voltage and frequency.
Note 2: Refer to Table 35-7 for each Oscillator mode's supported frequencies.

Regulated Devices

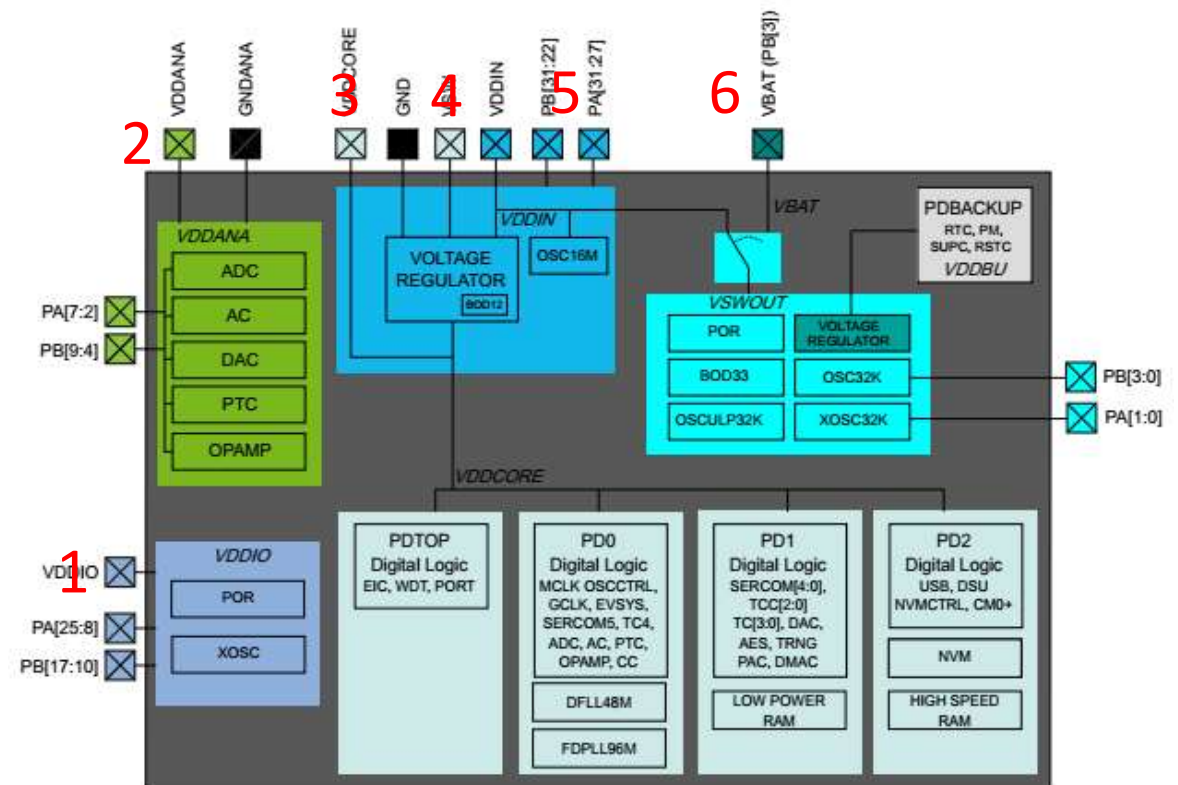
► How many voltage domains of the device?

- May have unregulated (HV) and regulated sections (LV)
- May have multiple domains for analog, USB regulator and xcvr

► Which modules are on which domain?

► What is the power supply for each domain?

Power Domain Overview

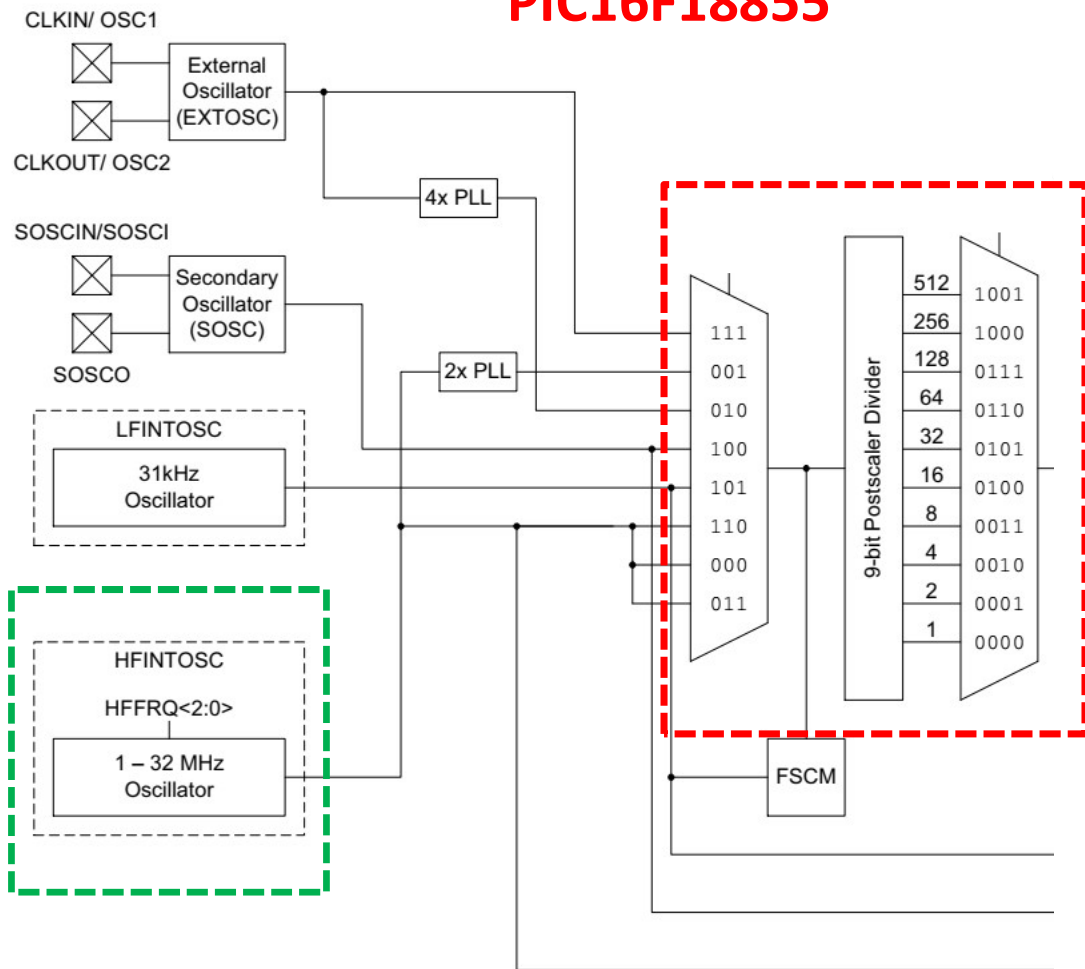


ATSAML21

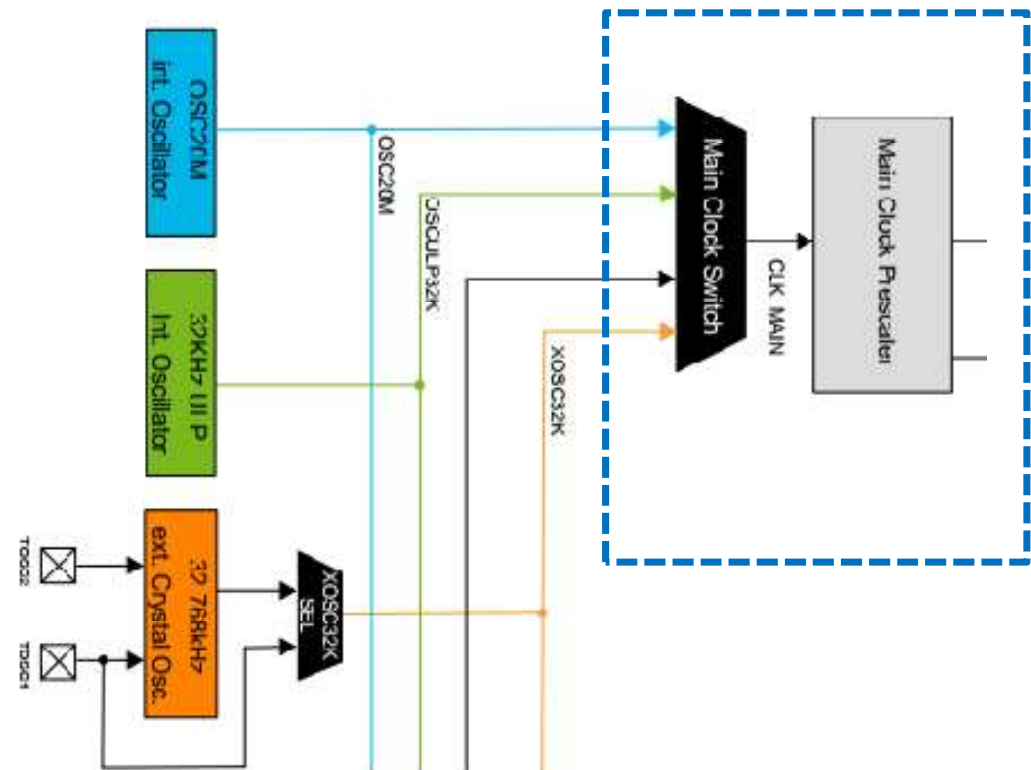
Clocks

Clock Generation - PIC and AVR devices

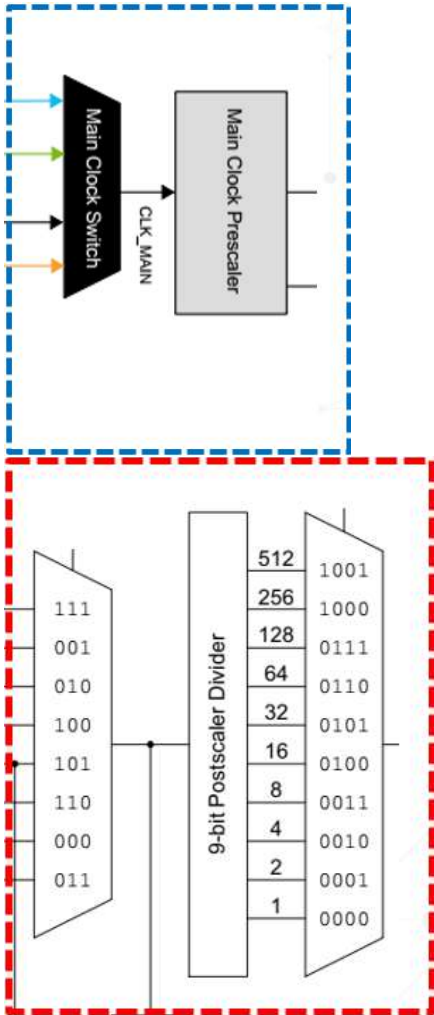
PIC16F18855



ATTiny817



Clock Switching - PIC and AVR devices



► Main Clock Switch Mux

- Allows software control over desired clock source
- Choose lowest power clock source needed

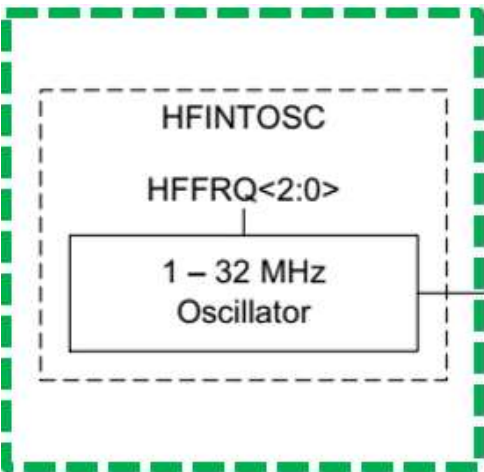
► Clock Post-scaler

- Allows clock source to be divided up to 1:512
- Select lowest available frequency needed
- Does not alter power consumption of the clock source, only the clock consumers

► Issues to be aware of:

- Changing CPU clock frequency also changes peripheral frequency for those on the same clock
 - Baud rate generator
 - PWM output

Clock Switching - PIC and AVR devices cont...



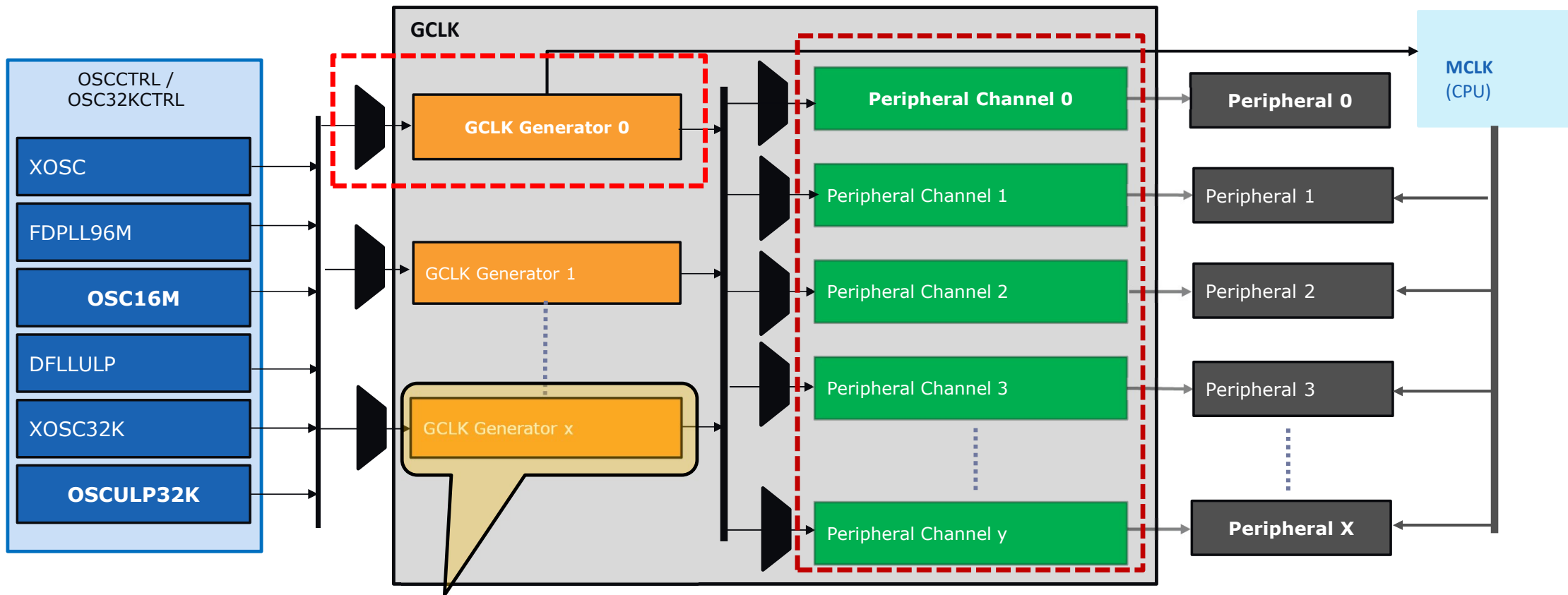
► Oscillator Frequency Selection

- Allows the base frequency of the oscillator to be altered.
 - Changes the current consumption of the clock source
- E.g. on the PIC16F18855, frequency options are:
 - 1, 2, 4, 8, 12, 16, 32 MHz

► Issues to be aware of:

- Frequency accuracy can degrade at lower frequencies
- Same warning as clock switching about new target frequency
 - Now affects modules that have selected the internal oscillator as a clock source

Clock Generation - SAM devices



Clock Generator isolates peripherals from their sources for frequency generation

SAM Clock Control

► Clock Generator (GCLK)

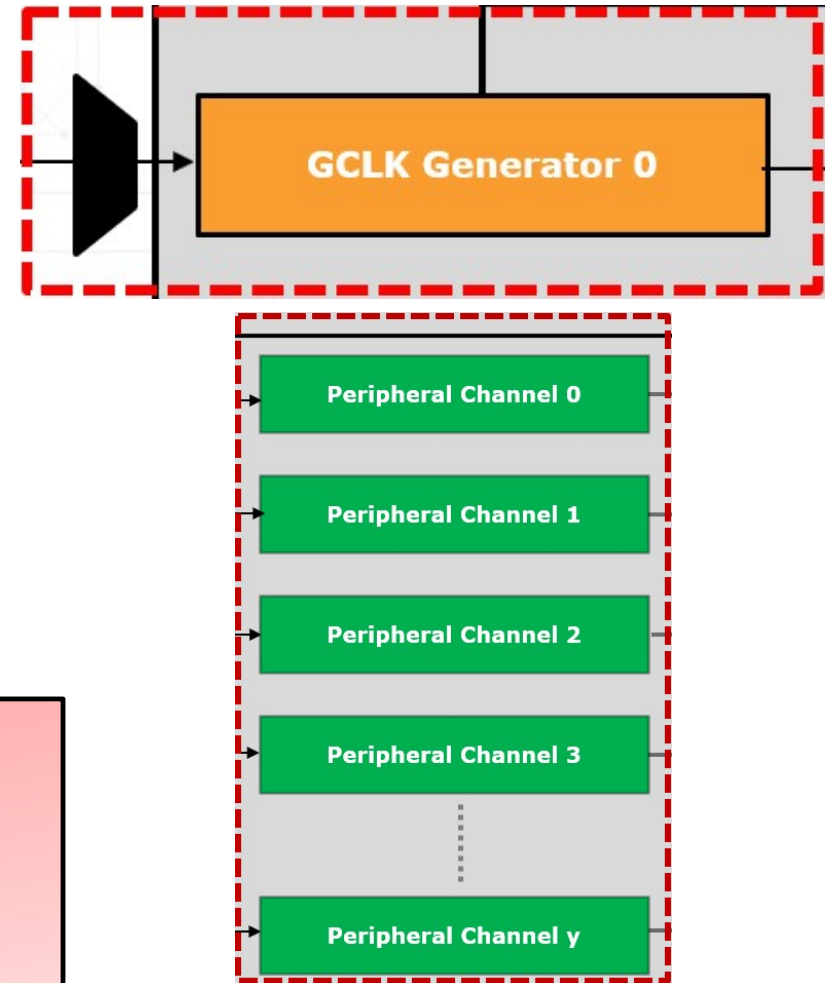
- Input Mux provides clock switching
- Clock Generator provide clock divider

► Peripheral Channel Enables

- Select GCLK source
- Enables clocks to module

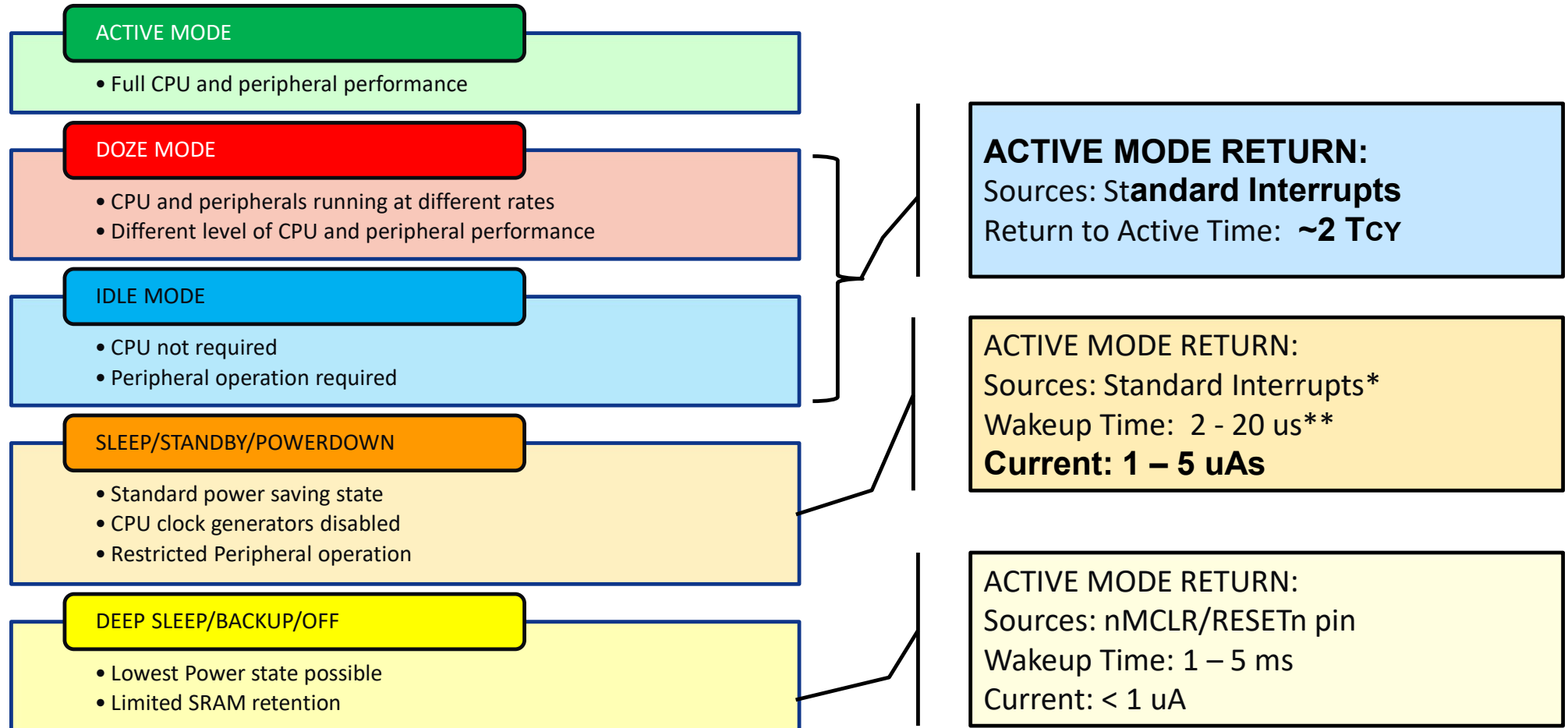
► Peripheral Module Disable (PMD)

- PIC based peripheral clock management tool
- PMD disables the clock interface to a peripheral module



Power Modes

Power Modes



Intelligent Peripherals

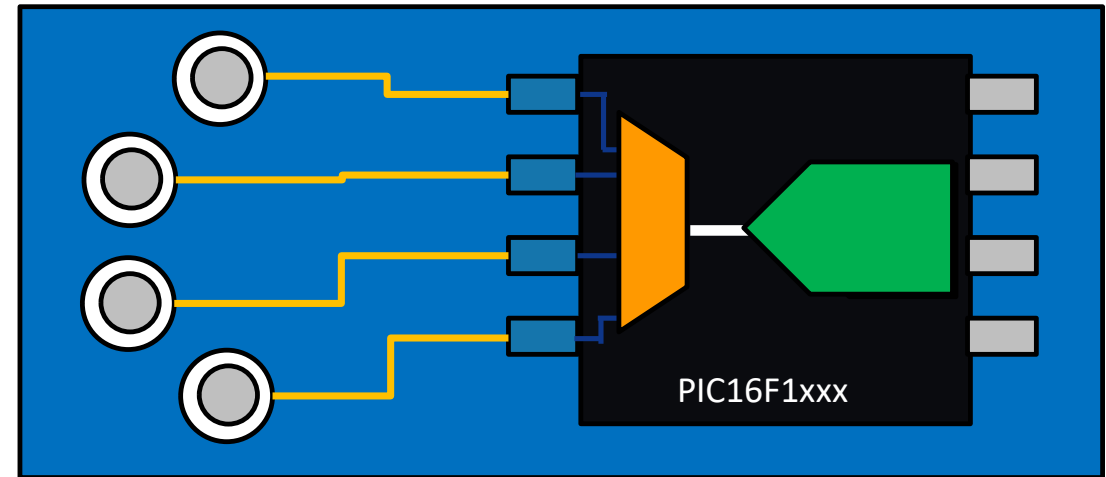
Intelligent Peripherals

- ▶ **The less the CPU is required to manage the overall operation of an MCU, the lower the power consumption of that MCU.**
- ▶ **Intelligent Peripherals can reduce the CPU load in an application**
 - a.k.a. Core Independent Peripherals (C.I.P.s)
 - Classic example?
- ▶ **Principal can be extended to any peripheral**

C.I.P. Examples - Touch

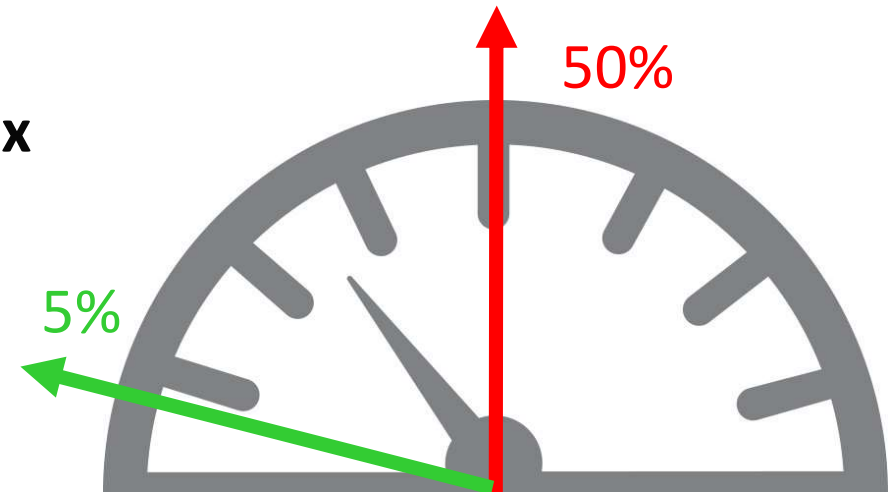
► Initial mTouch[®] algorithm

- 4 buttons
- **ADC** only
 - No hardware acceleration
- High frequency (8MHz) to make timing
- Blocking operation



► **ADCC** reduced CPU load by a factor of 10x

- Automated signal acquisition
- Interrupt (non-blocking) behavior



C.I.P. Examples - Touch cont...

Peripheral Touch Controller (PTC)

► Mutual and Self-Capacitive Touch

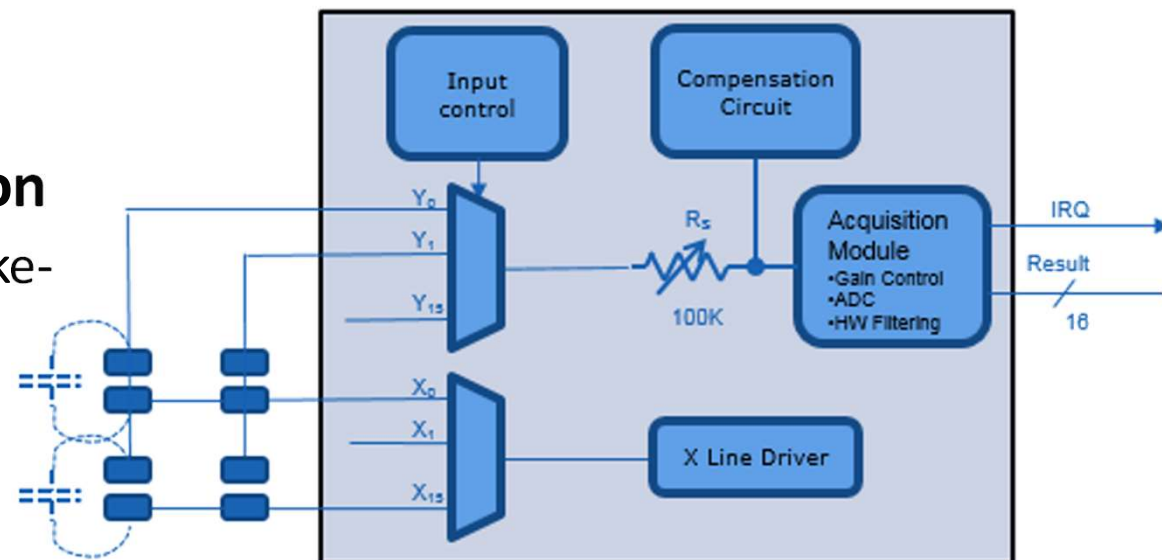
- Can run both methods at the same time
- No tuning needed
- No external components needed

► Lowest Standby Power Consumption

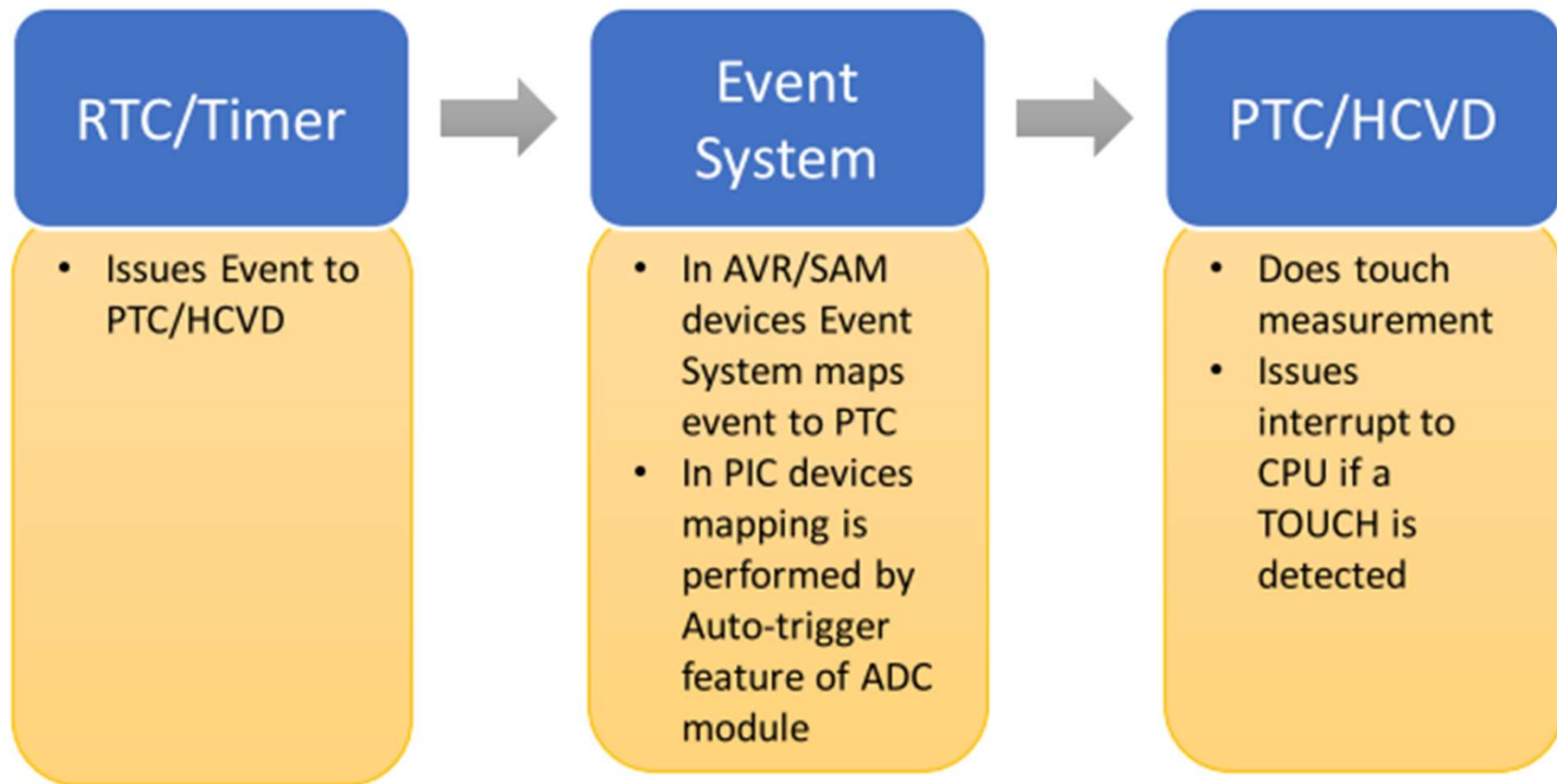
- 4 μ A standby with multi-button with wake-up on touch

► Low CPU Utilization

- Autonomous operation
- Non blocking interrupt behavior



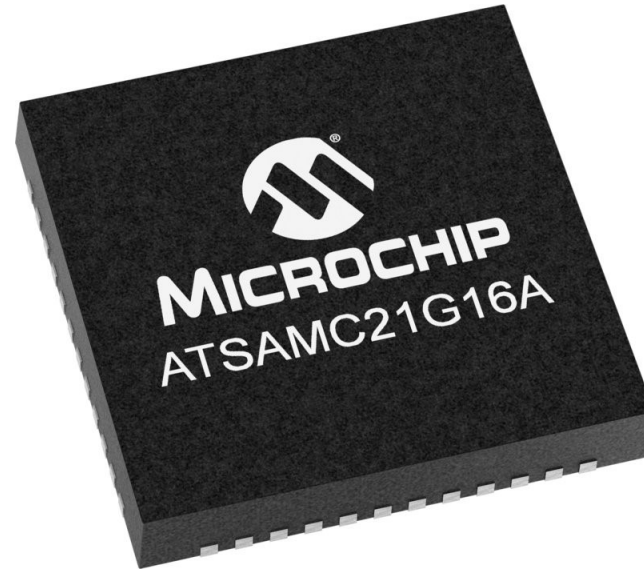
C.I.P. Examples - Touch cont...



C.I.P. Examples - Touch cont...

► Without PTC

- ADC only
- 7 or 8 cap buttons



- Cortex M0+
- 48 MHz operation
- Lots of FLASH
- Lots of RAM

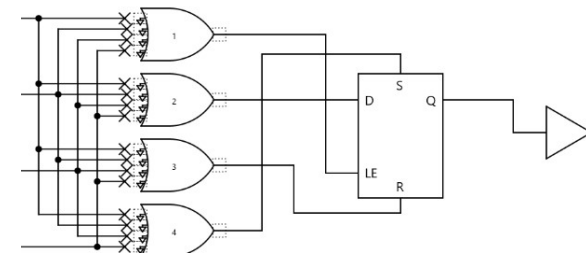
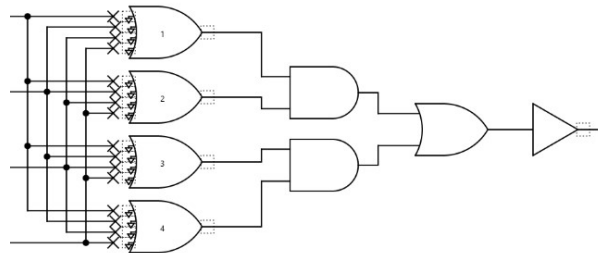
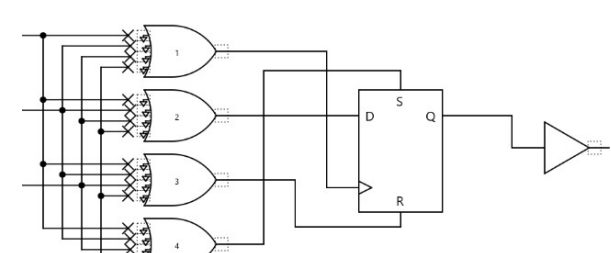
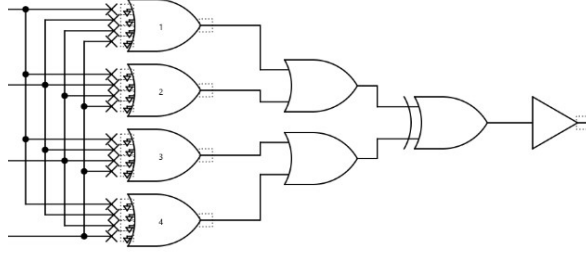
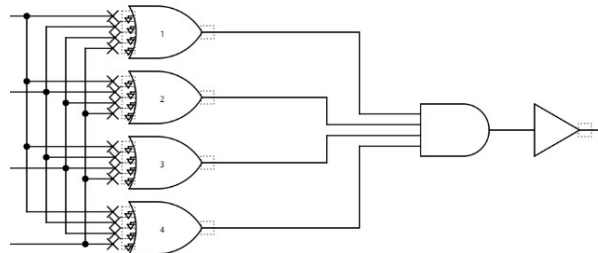
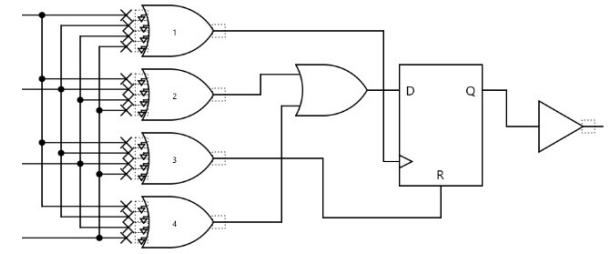
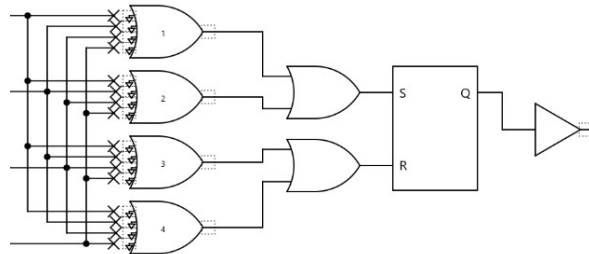
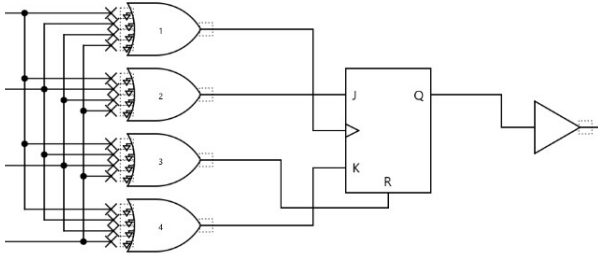
• With PTC

- 4" PCAP Touch screen



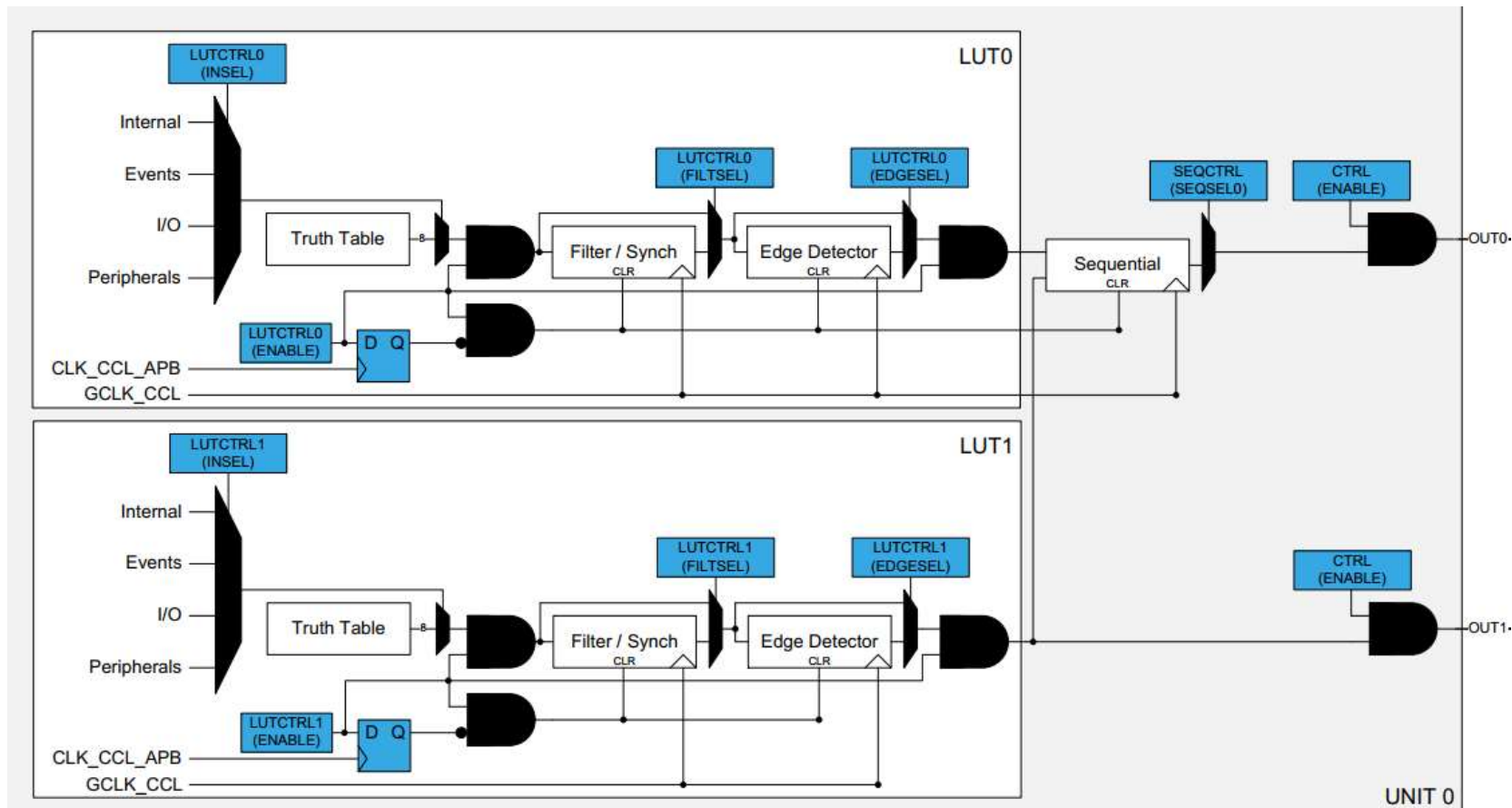
C.I.P. Examples - Logic

► Configurable Logic Cell



C.I.P. Examples - Logic cont...

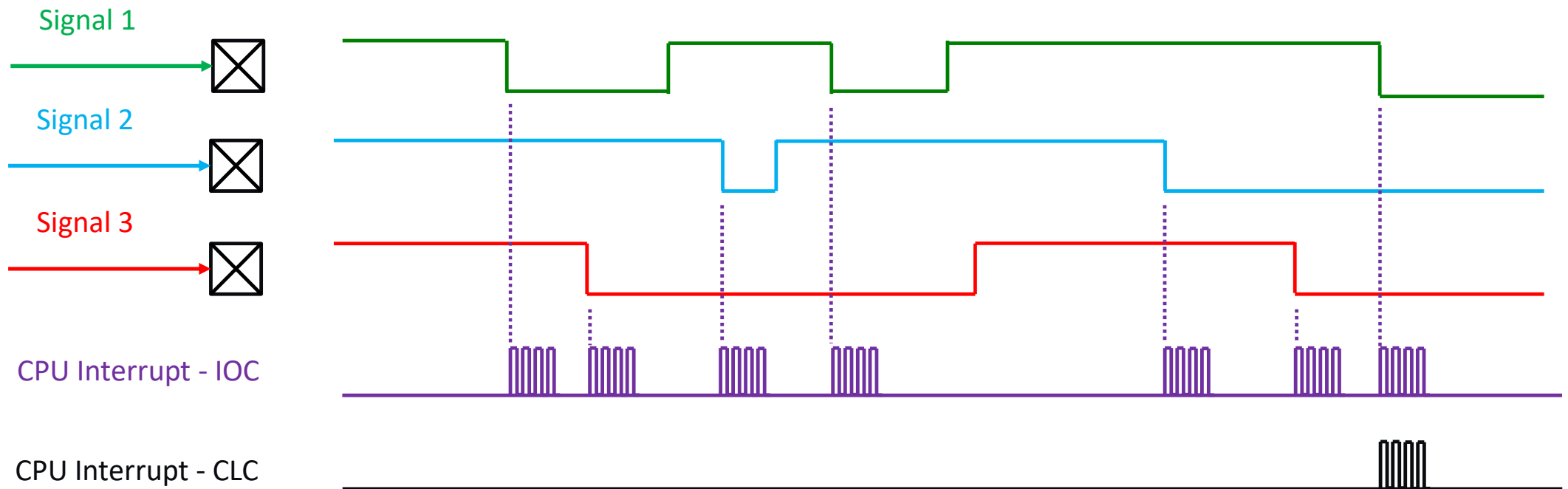
► Configurable Custom Logic



C.I.P. Examples - Logic cont...

► Low Power Multi-signal detection

- Detect when 3 external pins have gone low at the same time



Peripheral Interconnect

▶ Peripheral Events would need to be passed via the CPU

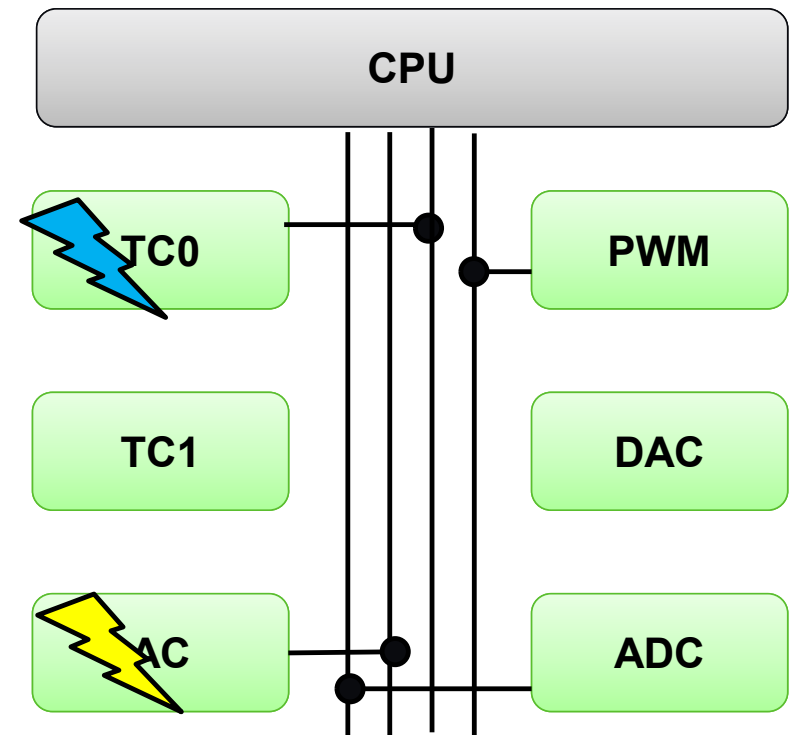
- Using Interrupts

▶ Delayed event reaction time

- Interrupt latency becomes an issue
- Non-deterministic reaction time

▶ Disadvantages

- Increased CPU overhead
- Increased Power Consumption



Interconnect - Event System

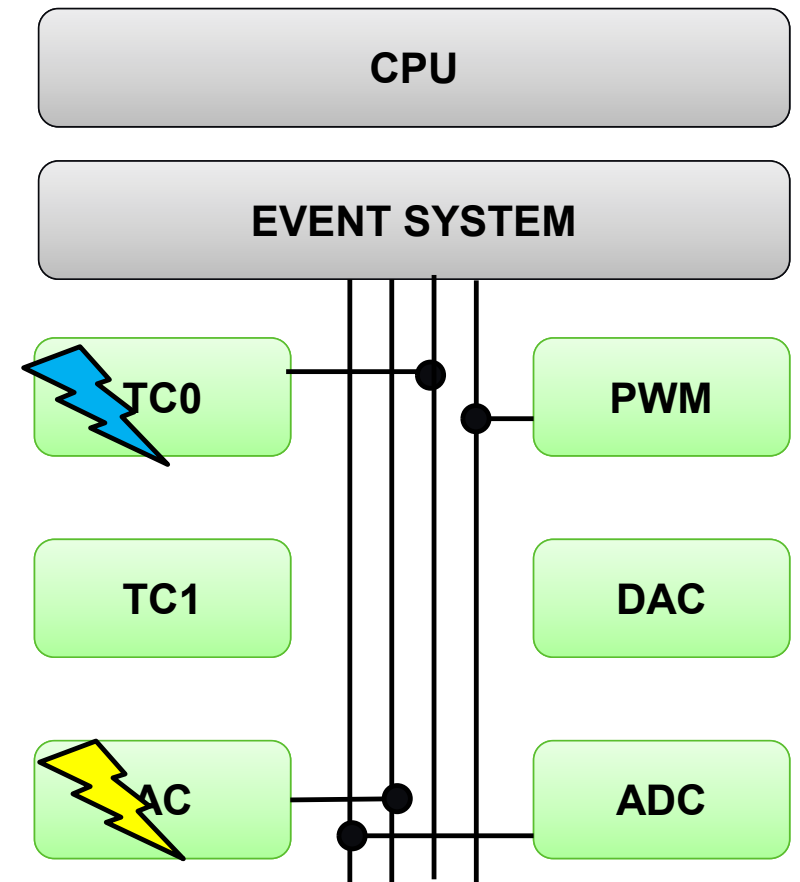
► **Event System allows communication between peripherals without CPU intervention**

► **Latency free event handling**

- Safe fault protection
- Deterministic reaction time

► **Advantages**

- Reduced CPU overhead
- Reduce Power Consumption



Peripheral Interconnect - PTG

▶ Peripheral Trigger Generator

- Complex input sequencer that can coordinate operation of peripherals

▶ Command based sequencer

- 8-bit commands
- 32-byte command queue
- Command queue is reprogrammable

▶ Multiple Input and Output sources

- Safe fault protection
- Predictable reaction time

