

# dsPIC33CK 入門



A Leading Provider of Smart, Connected and Secure Embedded Control Solutions



SMART | CONNECTED | SECURE

Linda Lai  
2024/3/26

# 大綱

- dsPIC33CK DSC介紹
- 開發工具介紹
- 入門程式(開發環境及硬體測試)
  - 實驗1：基礎I/O控制
  - 實驗2：透過UART顯示信息
- 內建硬體程式開發
  - 實驗3：Timer
  - 實驗4：Timer (SCCP)
  - 實驗5：Clock
  - 實驗6：Config(Special Features)

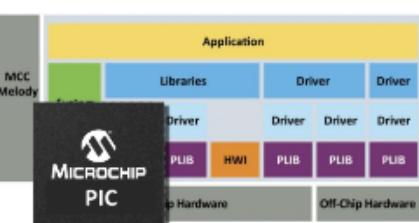
# 參考資料 – MICROCHIP UNIVERSITY



**dsPIC33C Peripheral Deep Dive**

This class presents deep-dive information on the architecture, setup, demonstration and pitfalls of the most common dsPIC33C peripherals. (Jan 2023)

83 min



**MCC Melody API Reference for PIC® MCUs**

MCC Melody components are the collective name for the provided libraries, drivers, Peripheral Libraries (PLIBs) and Hardware Initializers (HWIs). For select components, the MCC Melody API references now include a "How to use the ..." sections, which are a series of use cases. (Jan 2023)

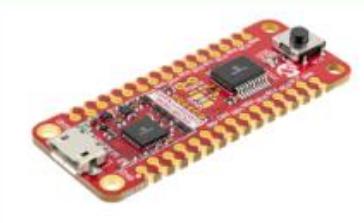
67 min



**使用 Curiosity Nano 平台進行快速產品原型製作**

本課程將幫助您充分利用 Curiosity Nano 開發平台。

57 min



**Rapid Prototyping with the Curiosity Nano Platform**

This course will help you to get the most out of the Curiosity Nano development platform. (Nov 2021)

57 min

<https://mu.microchip.com>

# 參考資料 – CAE專家教室

## PIC1001課程

為基於學習 MCC(MPLAB Code Configurator) 程式庫產生器 而開發, 課程中採用 APP041 實驗板, 並引入 PIM 模組子板 概念, 使用者可以透過購買不同的PIM模組子板, 來更換所需的MCU 8/16/32-bit 微控制器.

APP041 實驗板出廠已配置了 PIC24FJ128GB106 16-bit MCU, 而本課程會再搭配 dsPIC33CK256MP506 (APP041-3 PIM模組子板) 來上課, 為學習如何使用 MCC 程式庫產生器, 提供了一個基礎且紮實的入門課程.

本課程共計 14 章節 與 17 個動手操作實驗.

## PIC1001-Melody課程 **NEW**

為基於學習 MCC(MPLAB Code Configurator) Melody 程式庫產生器 的 基礎驅動程式(Driver) 與 周邊函式庫 Peripheral Library(PLIB) 而開發, 課程中採用 APP041 實驗板, 主晶片為 dsPIC33CK 16-bit MCU, 並引入 PIM 模組子板 概念, 使用者可以透過購買不同的PIM模組子板, 來更換所需的MCU 8/16/32-bit 微控制器.

APP041 實驗板出廠已配置了 PIC24FJ128GB106 16-bit MCU, 而本課程會再搭配 dsPIC33CK256MP506 (APP041-3 PIM模組子板) 來上課, 為學習如何使用 MCC Melody 程式庫產生器, 提供了一個基礎且紮實的入門課程.

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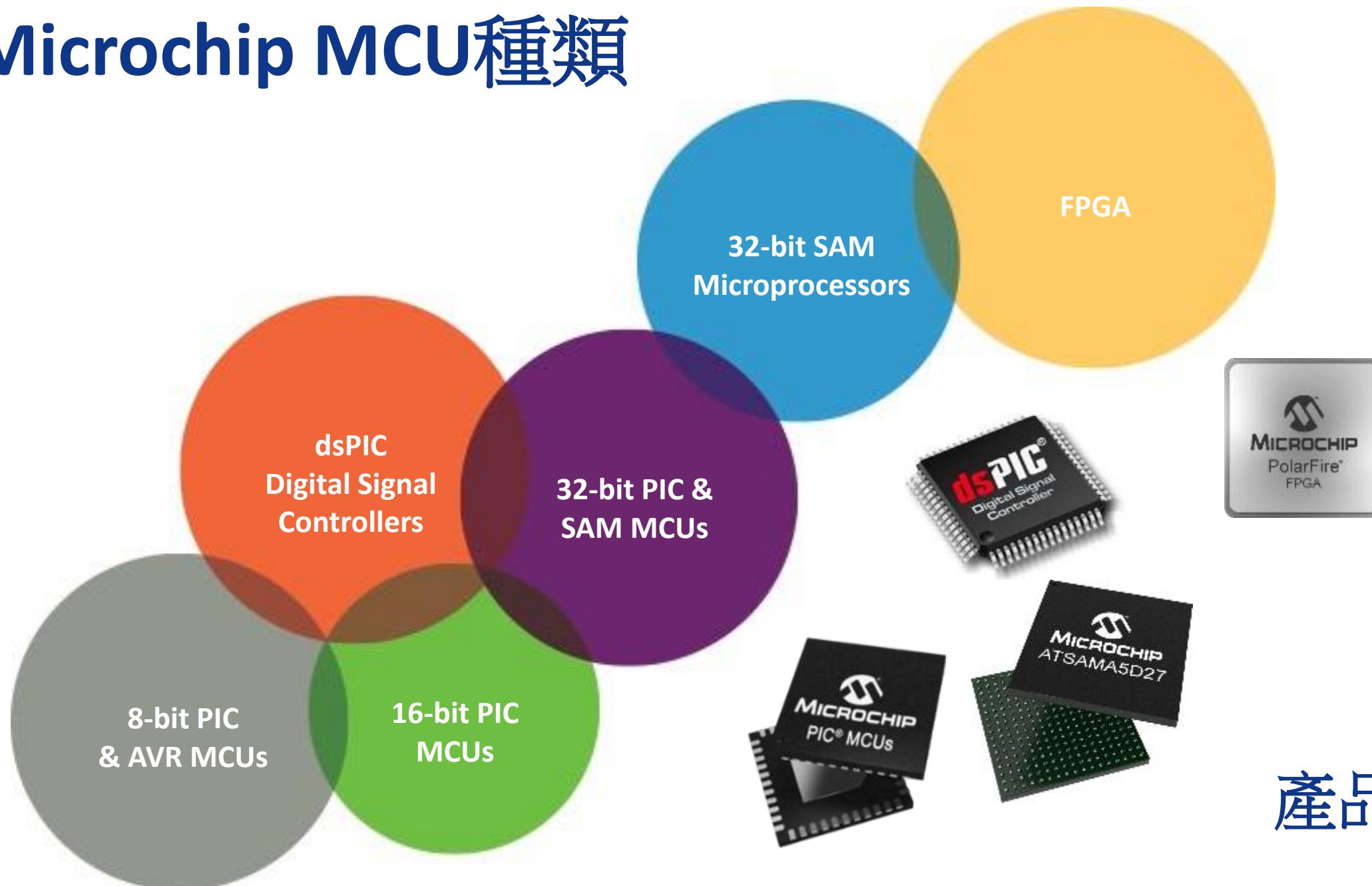
<https://www.microchip.com.tw/modules/tadnews/page.php?ncsn=2&nsn=222#PageTab8>

# dsPIC33CK - DSC

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Digital Signal Controllers

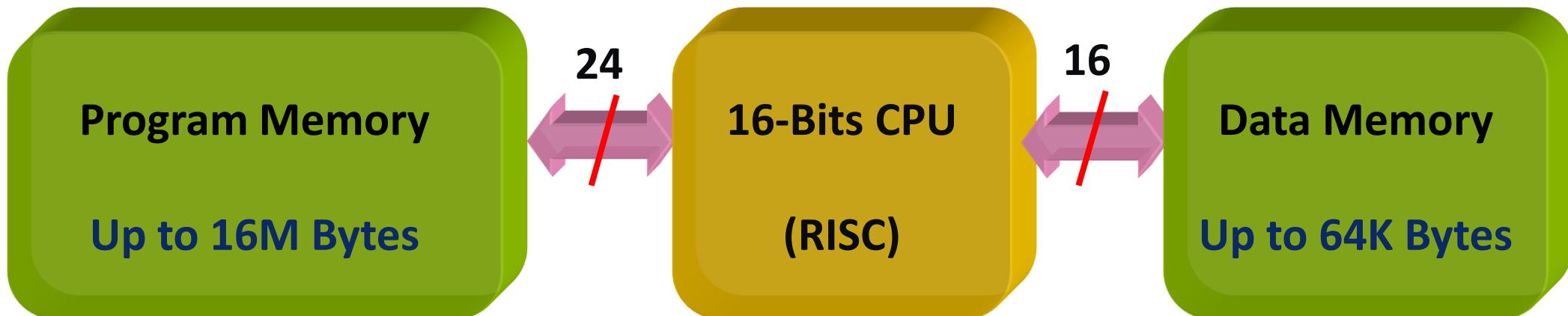
# Microchip MCU種類



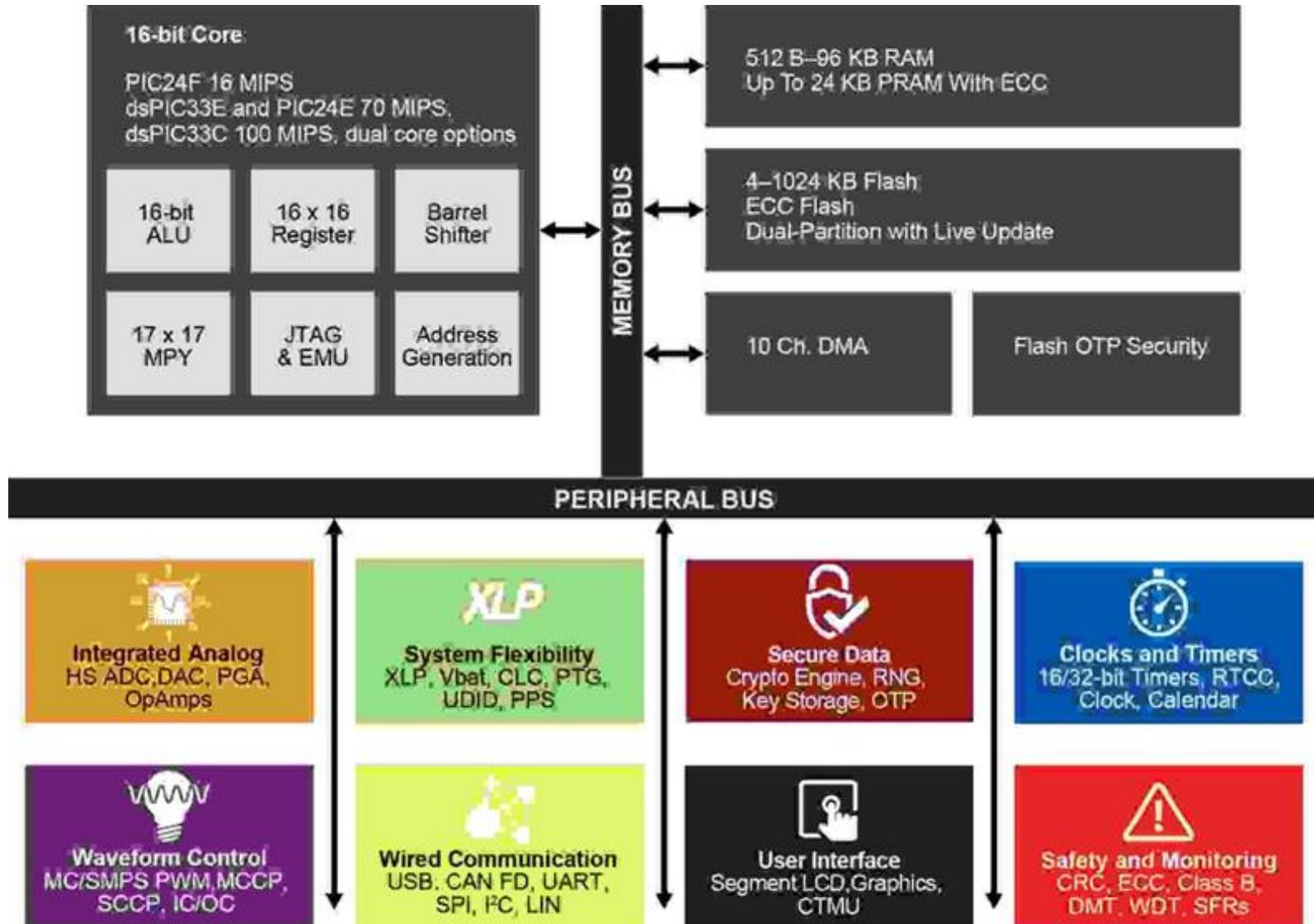
產品多樣

# 16-bits 核心架構

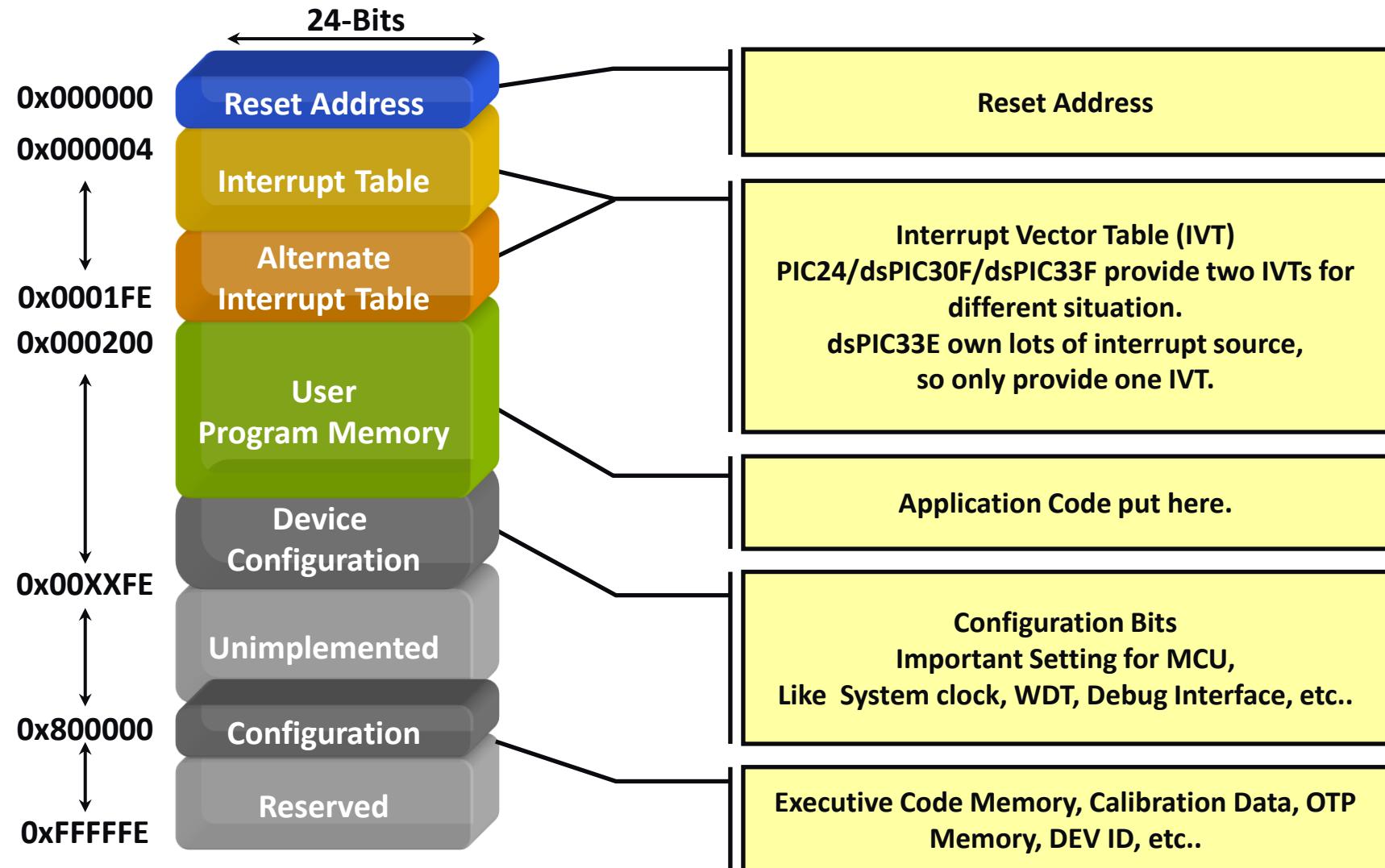
- Microchip 16-bits PIC/dsPIC® MCU 是哈佛架構 (Harvard)
  - 意思是程式記憶體跟資料記憶體各自擁有獨立的匯流排.
- 程式記憶體匯流排為24-bits, 最大到16M Bytes
- 資料記憶體匯流排為16-bits, 最大到64K Bytes



# 16-bits MCU方塊圖



# 程式記憶體規劃

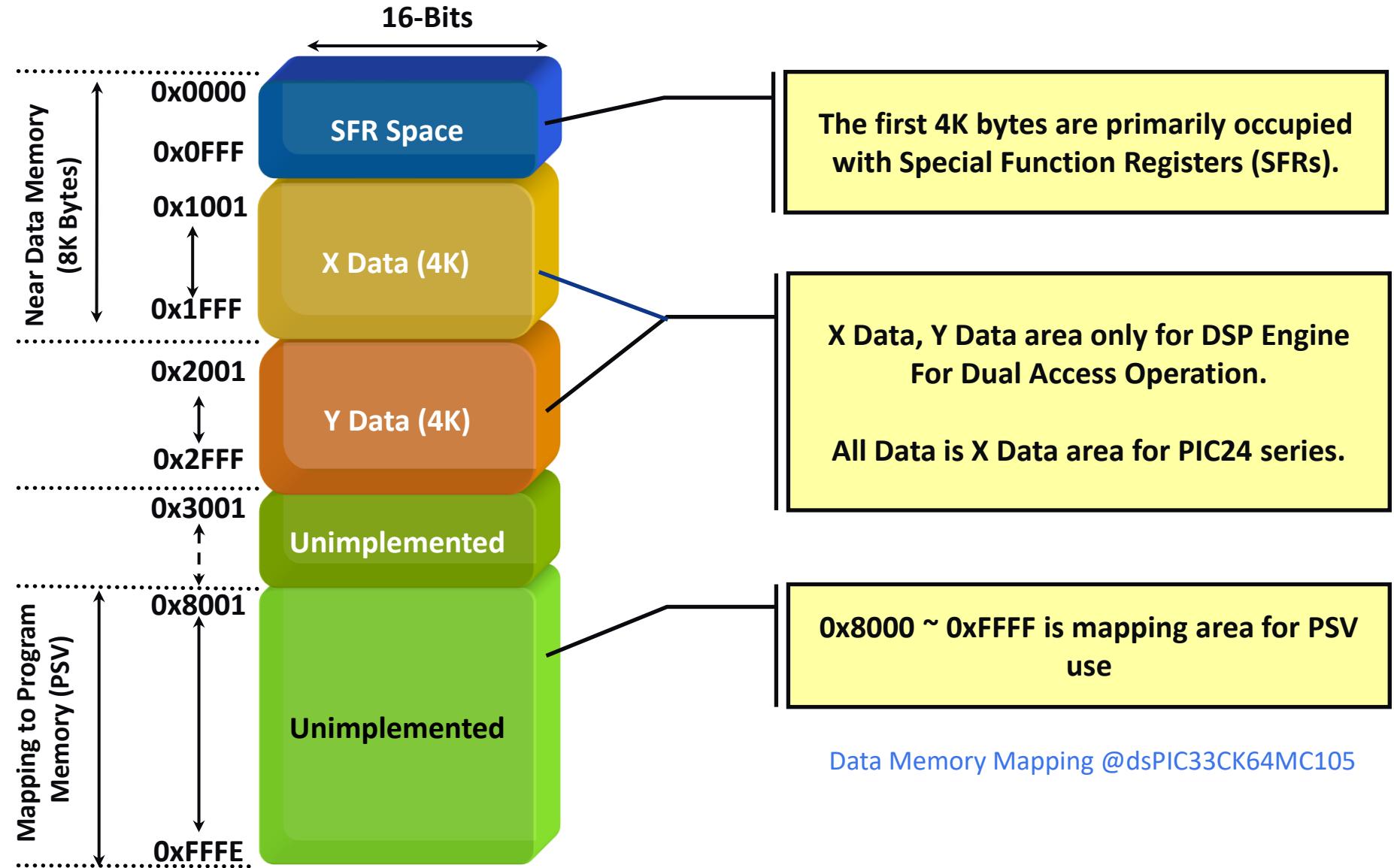


Program Memory Mapping @dsPIC33CK64MC105

# 資料記憶體規劃

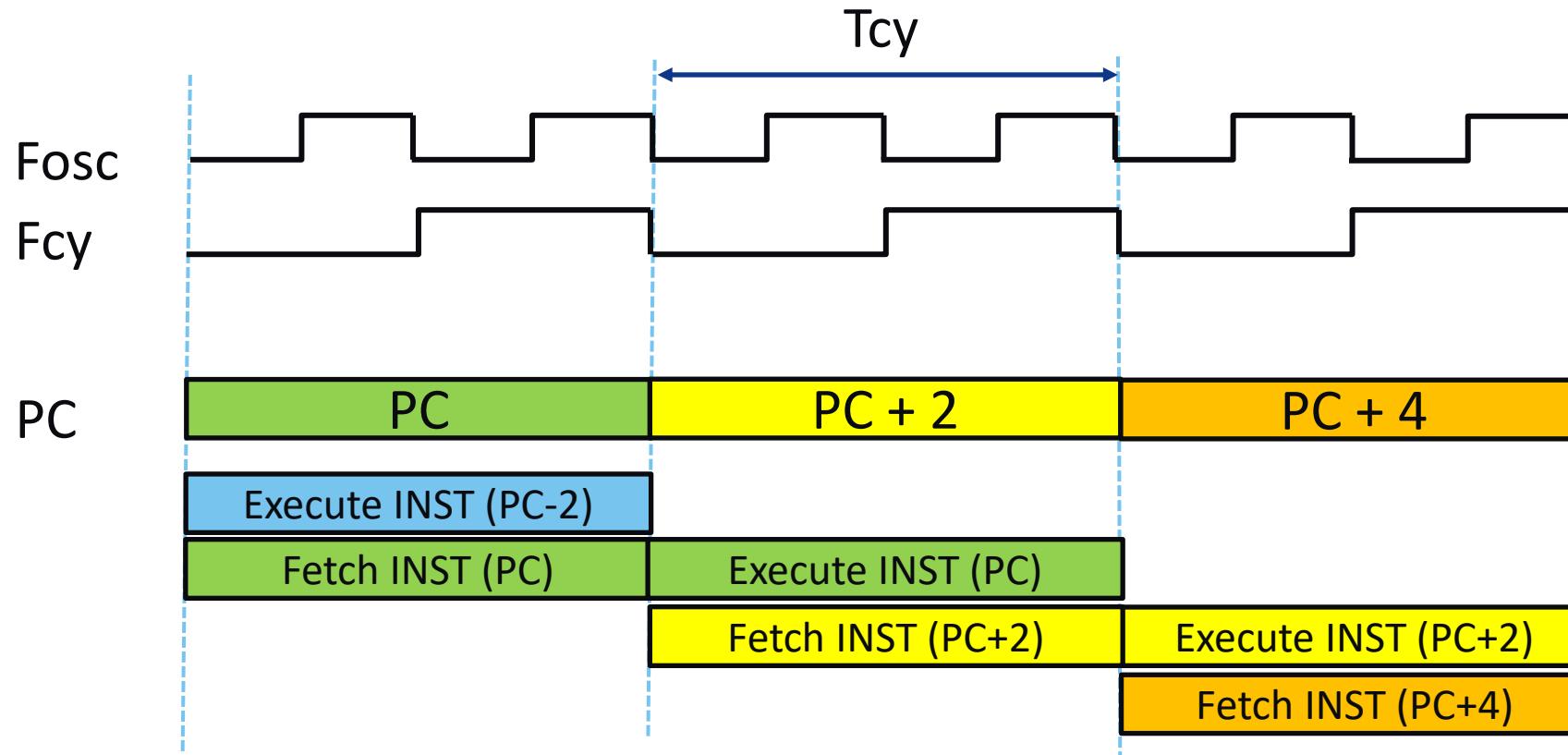
The **8K** byte area is referred as the **near** data space.

The **64K** byte area is referred as the **far** data space.

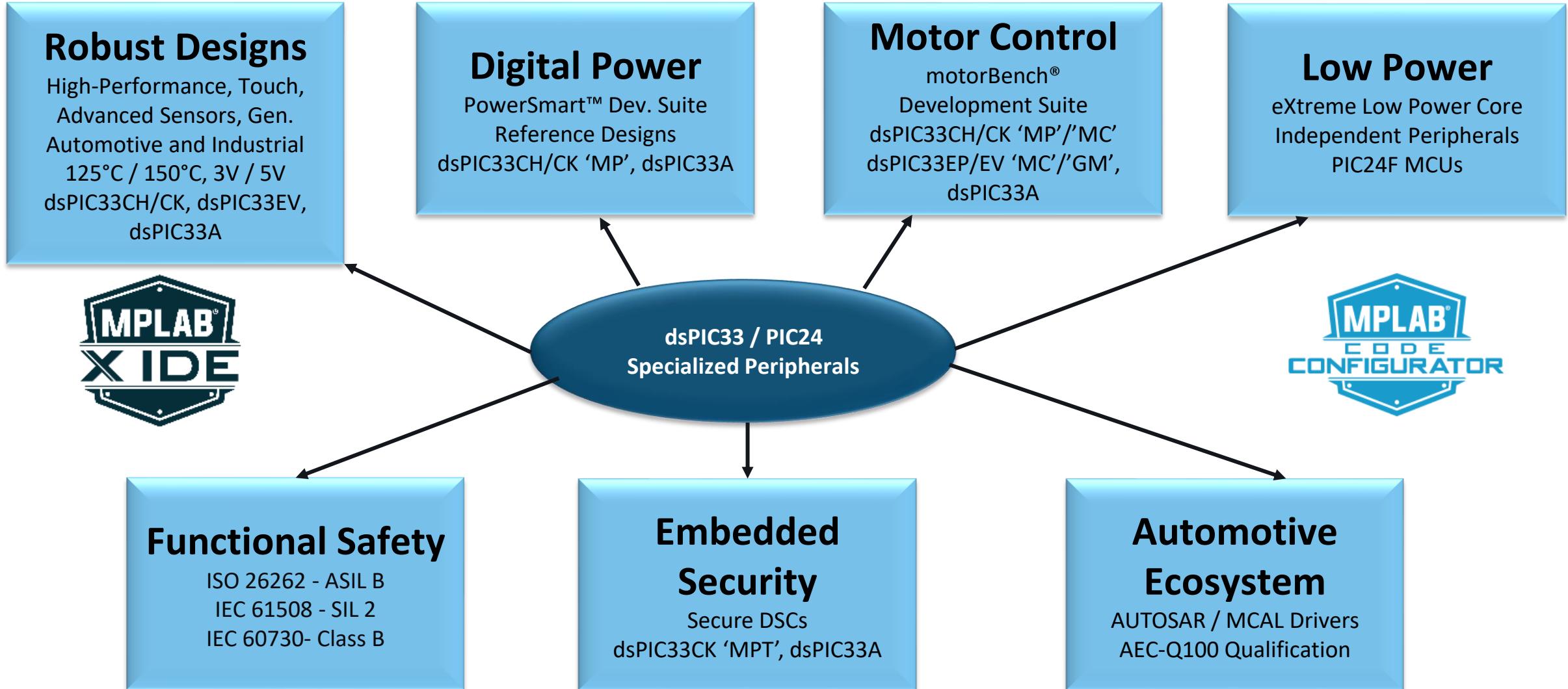


# dsPIC33C 指令執行流程

兩個震盪器的Clock 完成一個指令週期

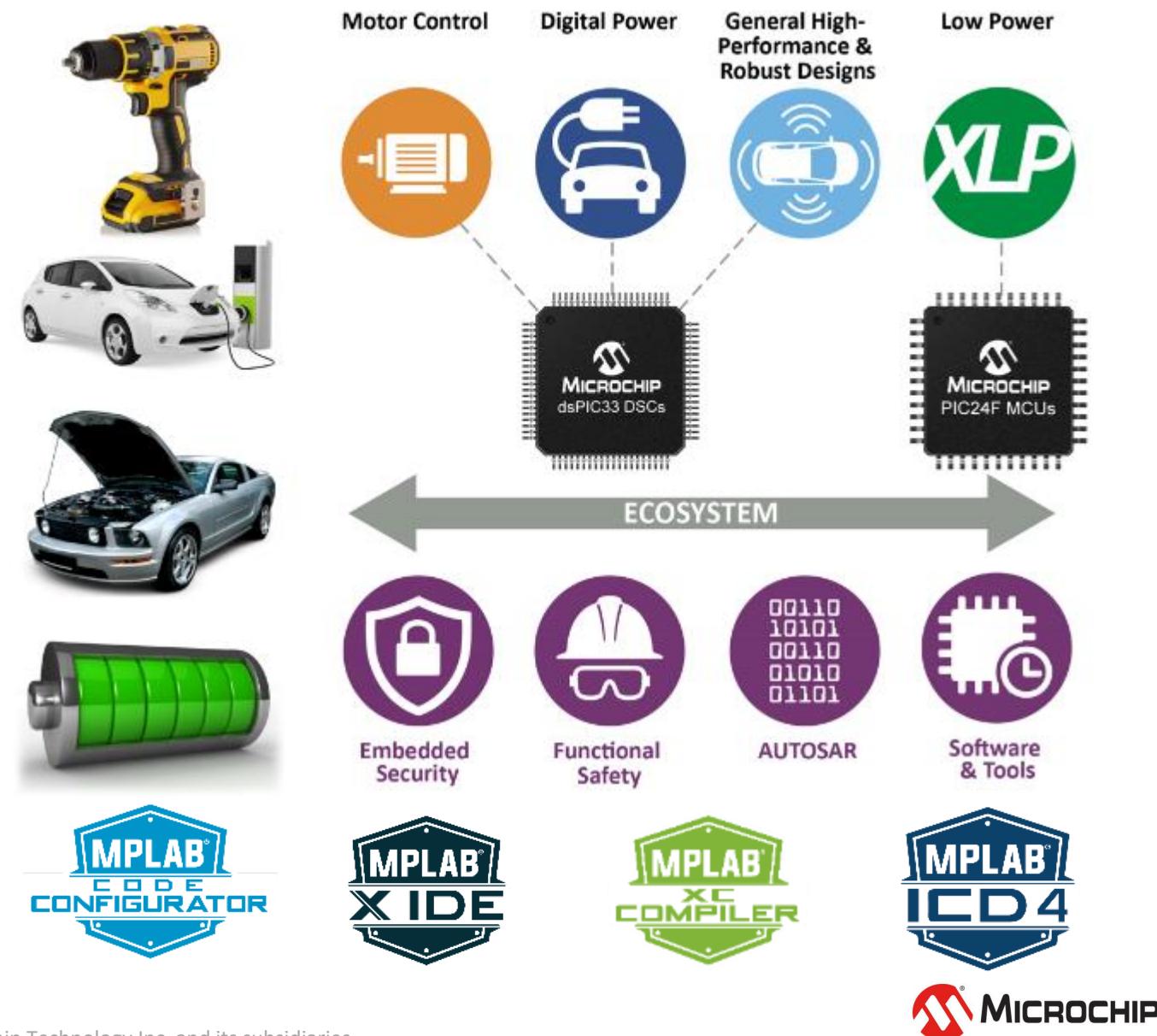


# dsPIC33 DSCs and PIC24 MCUs – 強項



# dsPIC33 DSCs / PIC24 MCUs - 強項

- dsPIC33 = High-Performance, Real-Time Control**
  - Robust and General High-Performance Embedded Designs**
    - Reliable operations in extreme conditions (150°C), AEC Q100 Grade 0
    - Advanced sensor interfacing, real-time control, touch and general high-performance designs in automotive and industrial
  - Motor Control**
    - Market leader in high efficiency and performance motor control
    - Simplifying motor control with motorBench® Development Suite
  - Digital Power**
    - Market leader in >300W power supplies
    - Automotive expansion in DC/DC, OBC, wireless power, USB PD
    - Large momentum for wireless power: automotive, appliance, tools
    - Simplifying digital power with PowerSmart™ Development Suite
- PIC24F = Low Cost, Low Power, High Memory**
  - Low-cost, low-power families with more memory and faster peripherals
  - Stay in the PIC® ecosystem! - Easy migration from 8-bit PIC MCUs
- Functional Safety with dsPIC33 DSCs and PIC24 MCUs**
  - Certified Functional Safety Solution for ISO 26262, IEC 61508, IEC 60730
- Embedded Security with dsPIC33 DSCs and PIC24 MCUs**
  - dsPIC33C MPT Secure DSCs and dsPIC33A DSCs with integrated subsystem
  - Robust security together with ATECC608/TA100
- Automotive Ecosystem for dsPIC33C DSCs**
  - AUTOSAR, MCAL Drivers and Tools



# dsPIC33 DSC 的發展

*Increasing Performance and Integration with each generation*

## dsPIC33F

- 40 MHz
- Single core
- Flexible PWMs
- Multiple S/H 10-bit ADC
- 16 – 256 KB Flash

## dsPIC33E

- 70 MHz
- Single core
- Improved PWMs
- 12-bit ADC
- Integrated Op-Amps
- 32 – 512 KB Flash
- 5x5 mm package

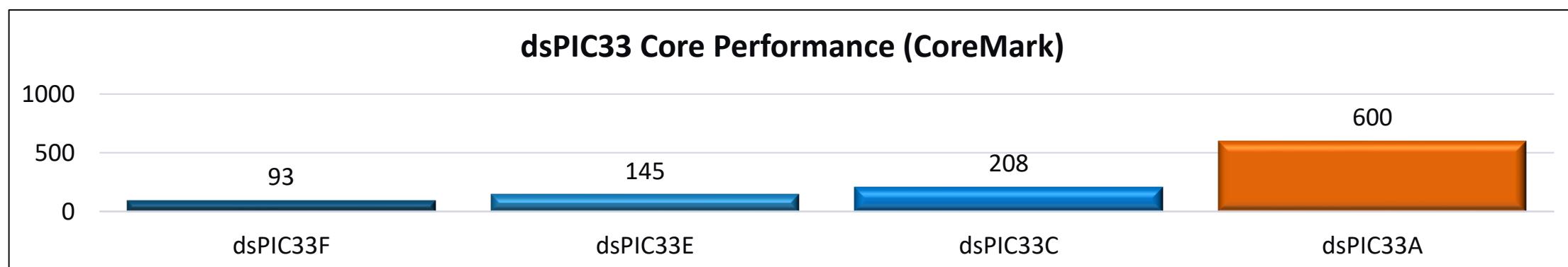
## dsPIC33C

- 100 MHz
- Single/dual cores
- Improved PWMs
- 3.5 Msps ADCs
- Integrated PGAs
- Functional safety
- 4x4 mm package

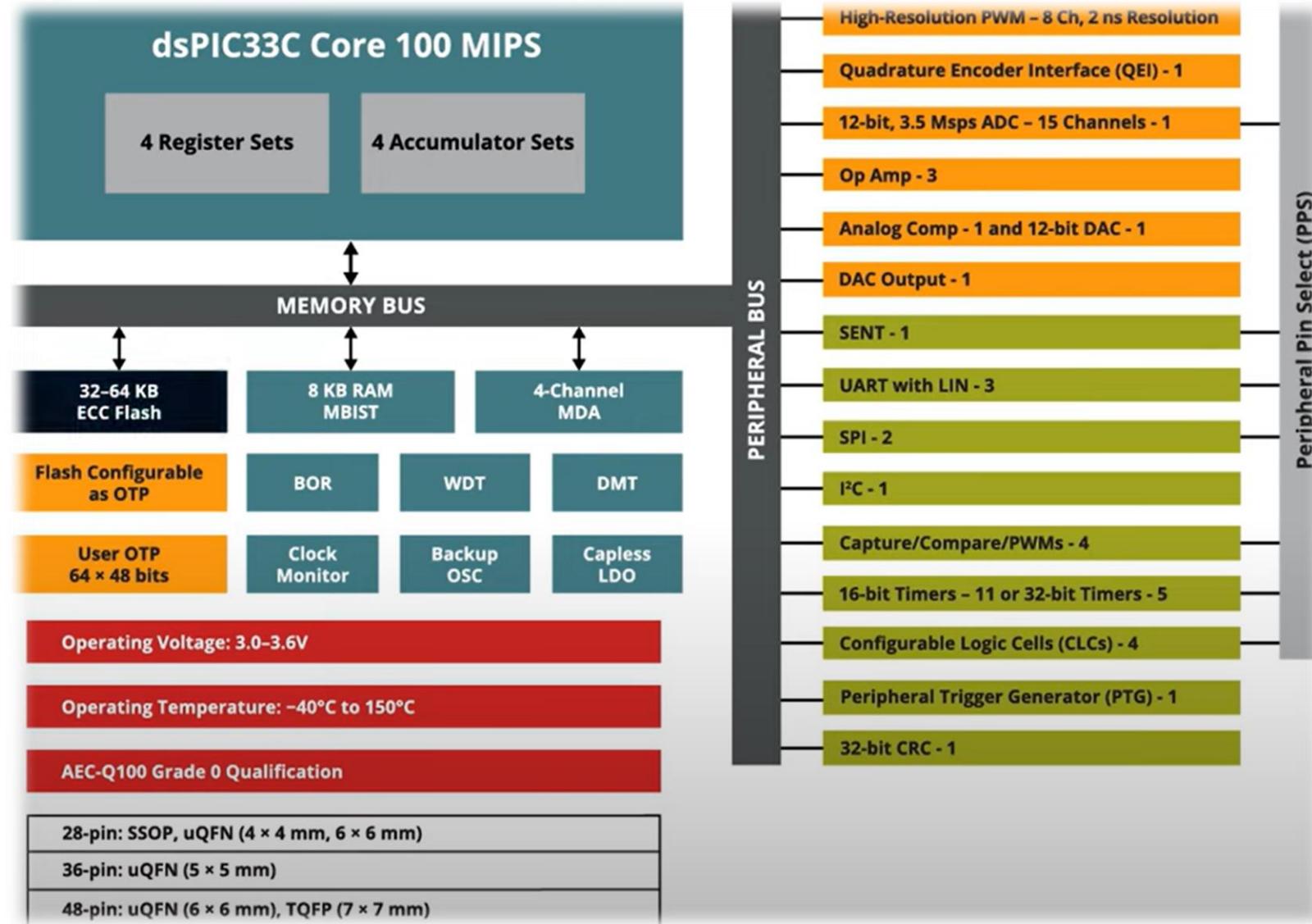
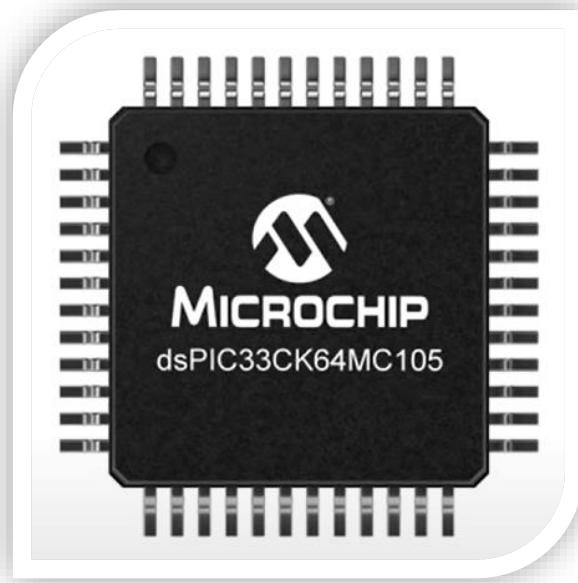
## dsPIC33A

- 200+ MHz
- Single/dual cores
- 32-bit math operations, DP-FPU
- Faster ADCs & Op-Amp
- Functional Safety and Security
- Step up from dsPIC33C/E
- Backwards compatibility

*As performance requirements increase, dsPIC33A DSCs provide a next step up in performance while preserving legacy code and ecosystem. The dsPIC33A DSCs offer common peripherals and look and feel to the older dsPIC33 generations and provide an easy migration path forward and still maintain low latency real-time control*



# 本課程用的MCU - dsPIC33CK64MC105



# 開發工具介紹

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X IDE,XC,MCC及相關硬體

# Microchip 開發工具



## DISCOVER

Feature Application Software



## CONFIGURE

System Init.  
Device Init.  
Peripheral Init.



## DEVELOP

IDEs, Compilers  
Example Code  
Software Stacks



## DEBUG

Evaluation Boards  
Debuggers  
Data Visualizer



## QUALIFY

Functional Safety  
Code Profiling  
Code Coverage  
MISRA Check



## PRODUCTION

Programmers  
Prog. Center  
Third Party



<https://www.microchip.com/en-us/tools-resources>

# Microchip 開發工具

## 從首頁進入方式

The screenshot shows the Microchip Tools and Resources homepage. A yellow box labeled '1' highlights the search bar. A yellow box labeled '2' highlights the 'TOOLS AND RESOURCES' menu item, which is also outlined with an orange box.

Log in to myMicrochip to access tools and benefits. Sign up in just one minute.

MICROCHIP

All Enter keyword, item, model or part #

1

2

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Reference Designs

Search and Discover

Configure

Develop

Debug

Evaluation Boards

Qualify

Production

Documentation

Archives

Last Chance Deals

FIGURE DEVELOP DEBUG QUALIFY PRODUCTION

IDEs, Compilers Example Code Software Stacks

Evaluation Boards Debuggers Data Visualizer

Functional Safety Code Profiling Code Coverage MISRA Check

Programmers Prog. Center Third Party

IDEs

MPLAB X IDE MPLAB Xpress Studio

TUV SUD Softing Systems

<https://www.microchip.com/en-us/tools-resources/all>

# 應用軟體架構



MPLAB® X / MPLAB Xpress IDE



MPLAB® XC Compilers



MPLAB Code Configurator (MCC)

MCC  
Melody

MCC  
Classic

MPLAB  
Harmony

IDE 用於產生專案及除錯

MCC 透過圖形化界面規劃後，產生周邊硬體驅動程式及程式碼到IDE中

XC 根據所載入的程式碼編譯成HEX

各項目錄  
支援軟硬體規劃設定，並根據用戶規劃產生程式碼

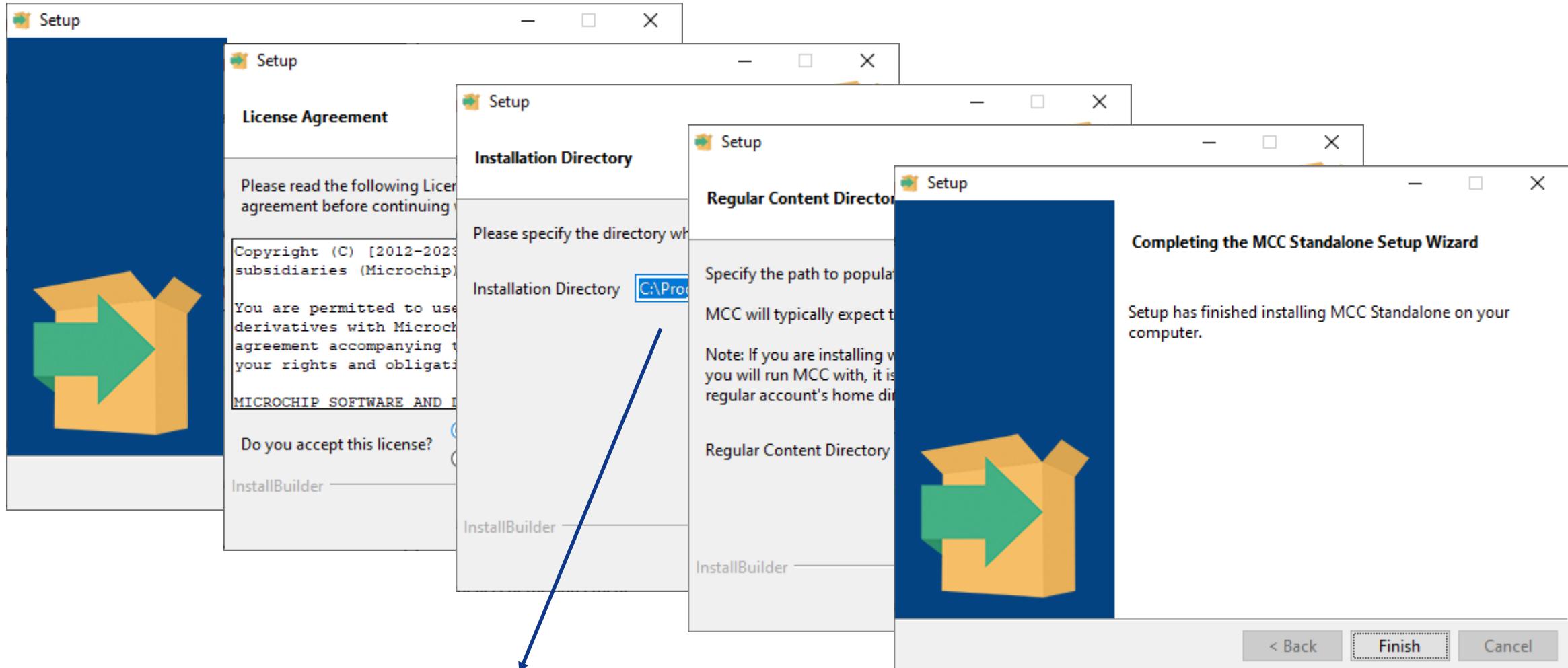
# 課程使用軟體



- **MPLAB X IDE v6.20** <https://www.microchip.com/mplab/mplab-x-ide>
- **MPLAB XC16 v2.10** <https://www.microchip.com/mplab/compilers>
- 在IDE界面中下載
  - **MPLAB® MCC v5.5.0**  
<https://ww1.microchip.com/downloads/aemDocuments/documents/DEV/ProductDocuments/SupportingCollateral/mcc-installer-5.5.0-windows.exe>
  - **MPLAB® MCC Melody Libraries**
  - **dsPIC33CK-MP DFP v1.11.346. (Device Family Pack)**

舊版軟體下載連結 <https://www.microchip.com/en-us/tools-resources/archives/mplab-ecosystem>

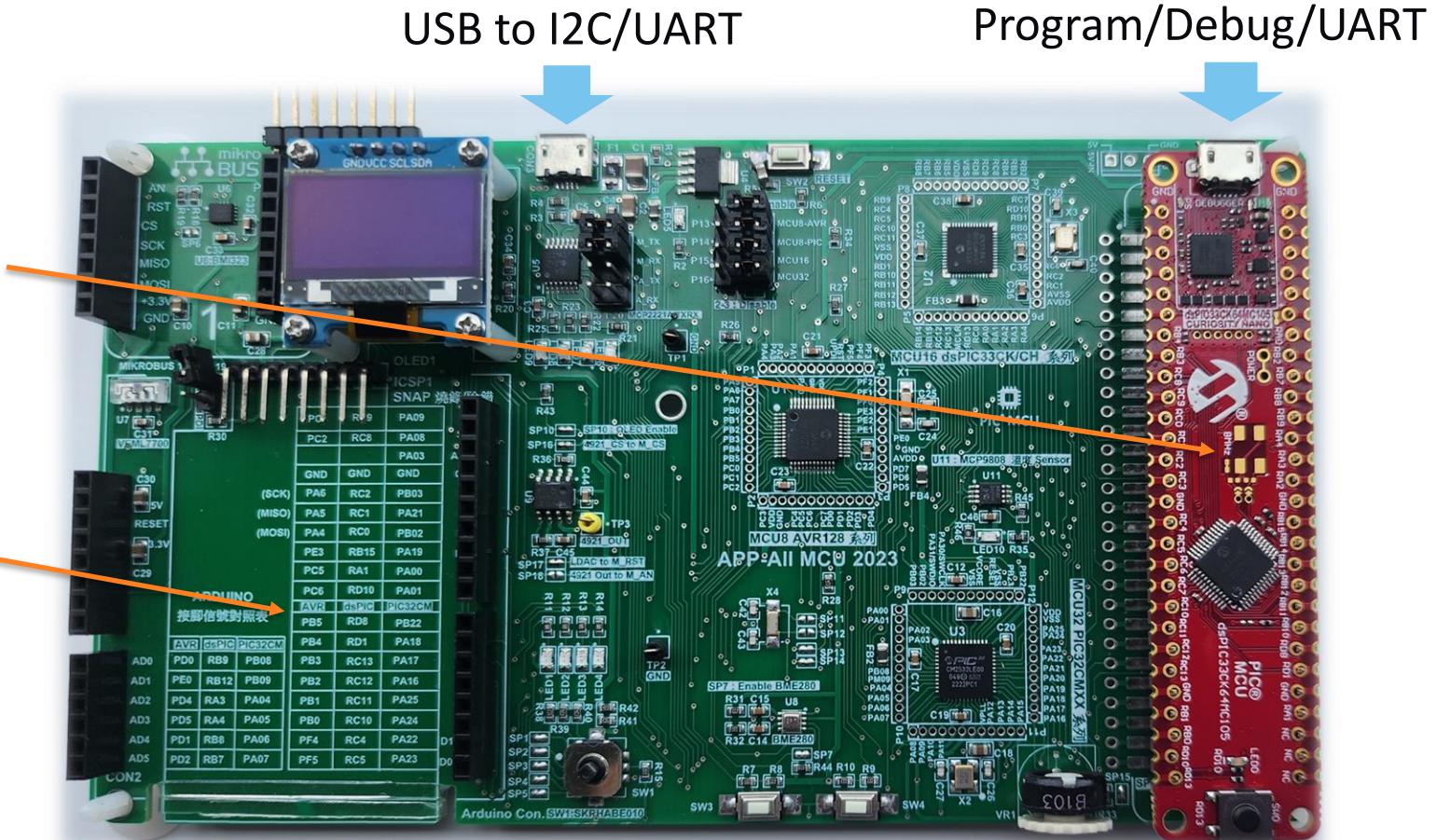
# MCC 離線版安裝



- C:\Program Files\Microchip\mcc\MccStandalone-5.5.0

# 課程使用實驗板

- dsPIC33CK Curiosity Nano
- APP-AII MCU 2023

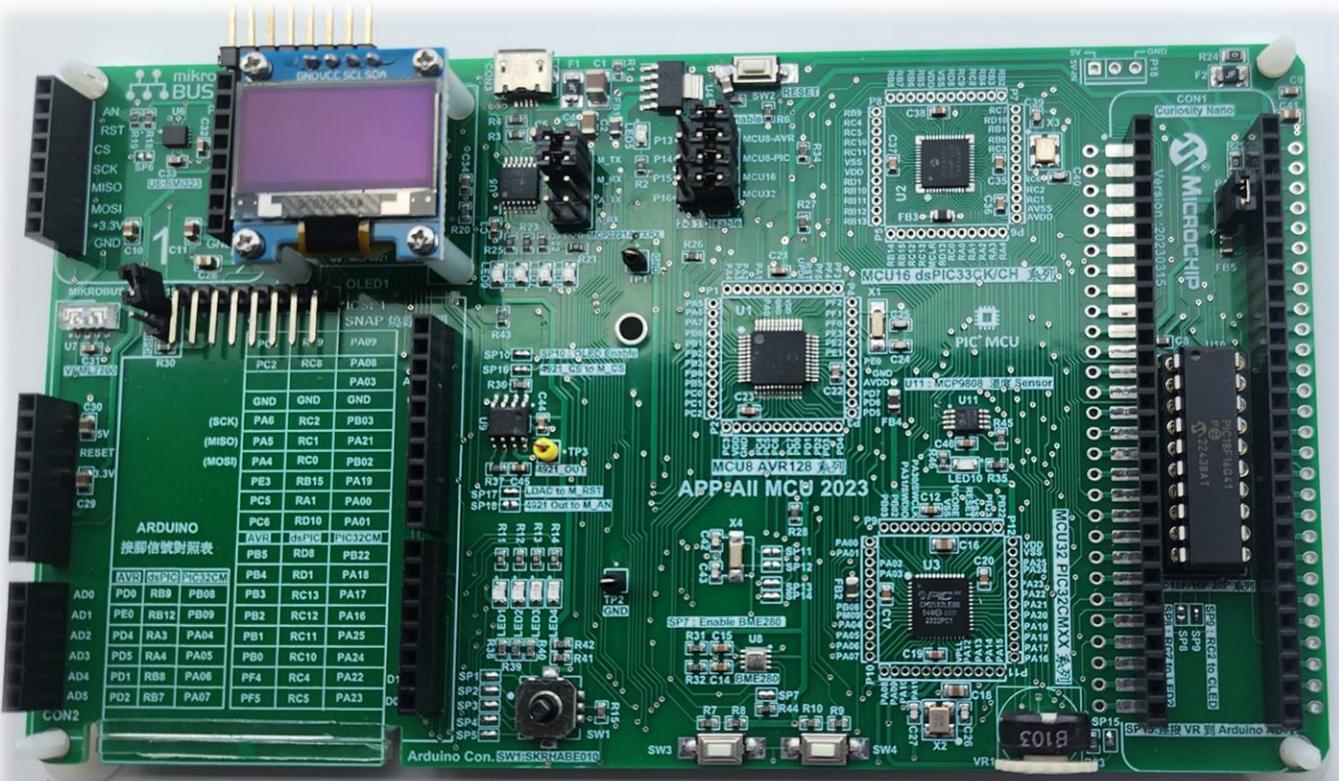


# dsPIC33CK Curiosity Nano 特色

- 內建Debugger
  - 板子資訊已內建到MPLAB X IDE中
  - 支援燒錄及除錯
  - 電源/狀態指示燈(綠色)
  - 一個邏輯分析腳 (DGI GPIO)
  - 虛擬COM port (CDC)
- USB 供電
  - 電源可調
  - MIC5353 LDO由Debugger控制
  - 1.8-3.6v 輸出電壓
  - 最大輸出電流500 mA (受環境溫度和輸出電壓限制)
- 使用dsPIC33CK64MC105
  - The High Performance 100 MHz
  - 64KB of ECC Flash and 8KB of RAM
  - 一個LED (黃色)
  - 一個按鍵

# APP-AII MCU 2023 內建的周邊

- I2C 介面的
  - 六軸 IMU - BOSCH BMI323
  - Lighting Sensor – Vishay 的VEML7700-TT
  - Humidity sensor - BOSCH BME280
  - 溫度 Sensor – Microchip MCP9808
  - OLED Display - 單色128 \* 64
- SPI 介面的
  - DAC – Microchip MCP4921
  - 2個 WS2812B One-Wire Color LED
  - 1個 MCP2221A 作實驗板上的UART 以及 I2C 介面轉換至 USB 的介面 IC
  - 1個 ALPS 的SKRHABE010 五向開關



# 實驗一

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基礎I/O控制

# 入門實驗

## 實驗一：基礎I/O控制

- 本實驗目的：

- 確認開發環境設定完成
  - 驗證電腦安裝的軟體X IDE,XC,MCC正常運作
  - 紅板上內建的燒錄及除錯可正常運行
  - MCU可以受所撰寫的程式控制IO

- 結果呈現：

- 黃色LED一秒閃一次

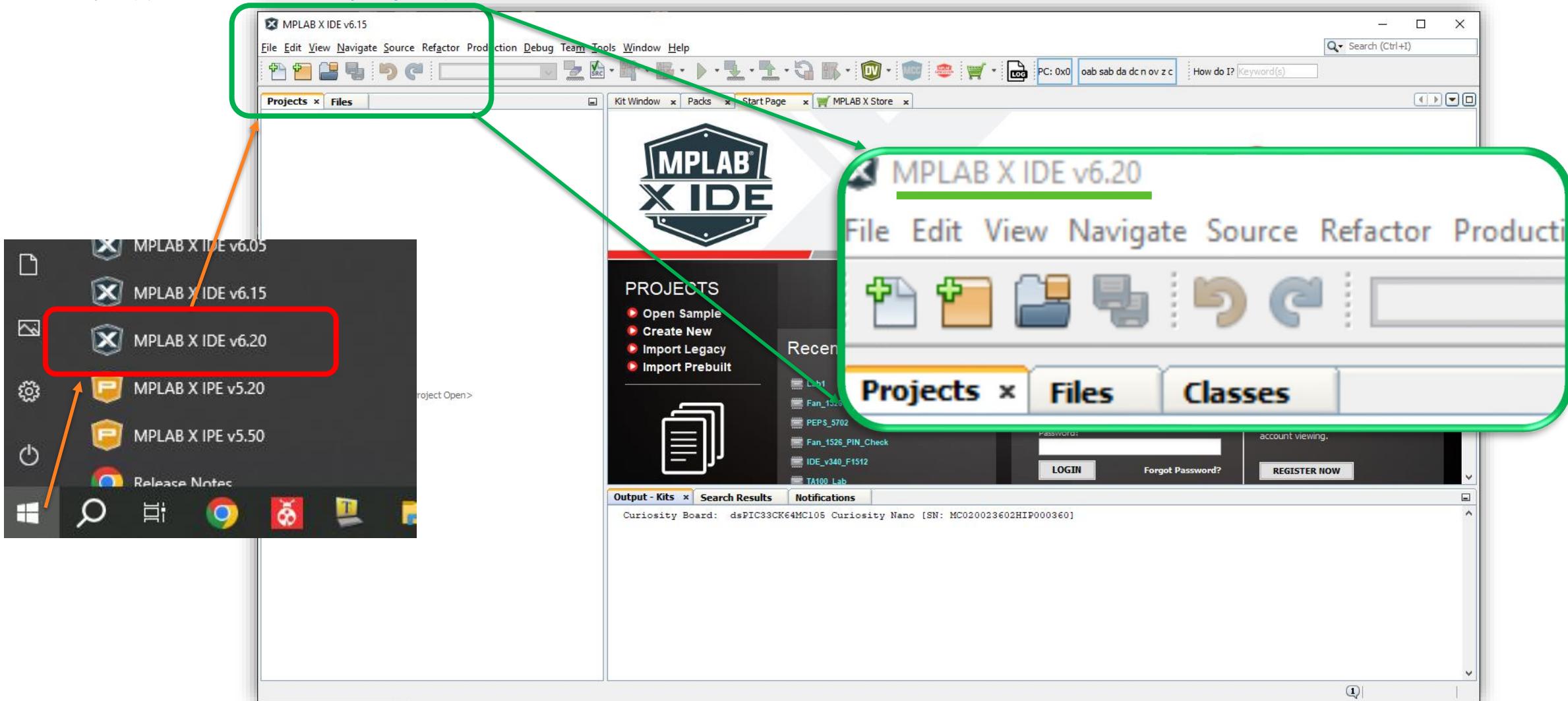
# 前置作業

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確認軟體IDE、XC、MCC  
確認硬體EVB、USB

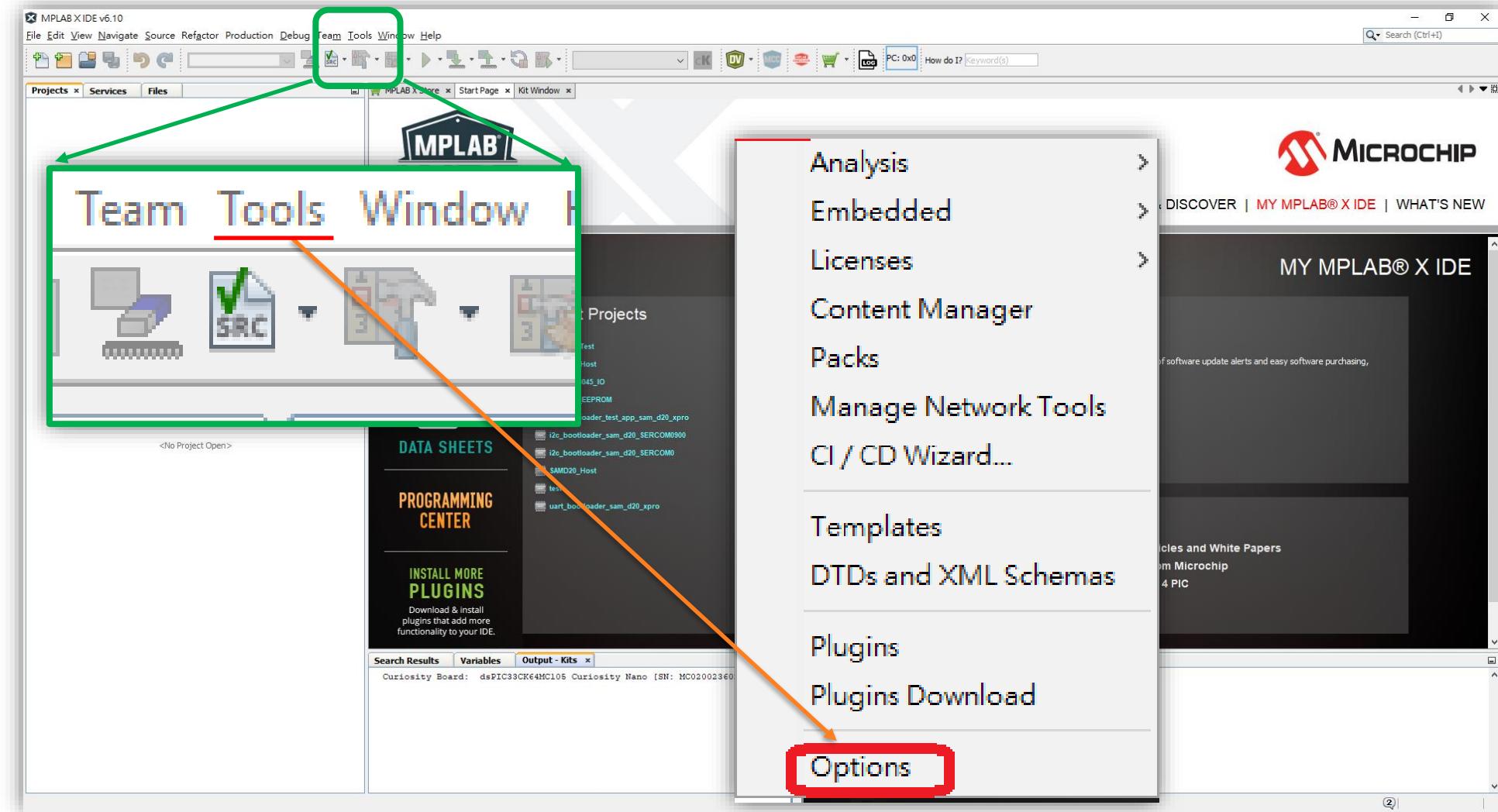
# 1. 開啟MPLAB X IDE

點選開始  --> 找到MPLAB X IDE v6.20點選



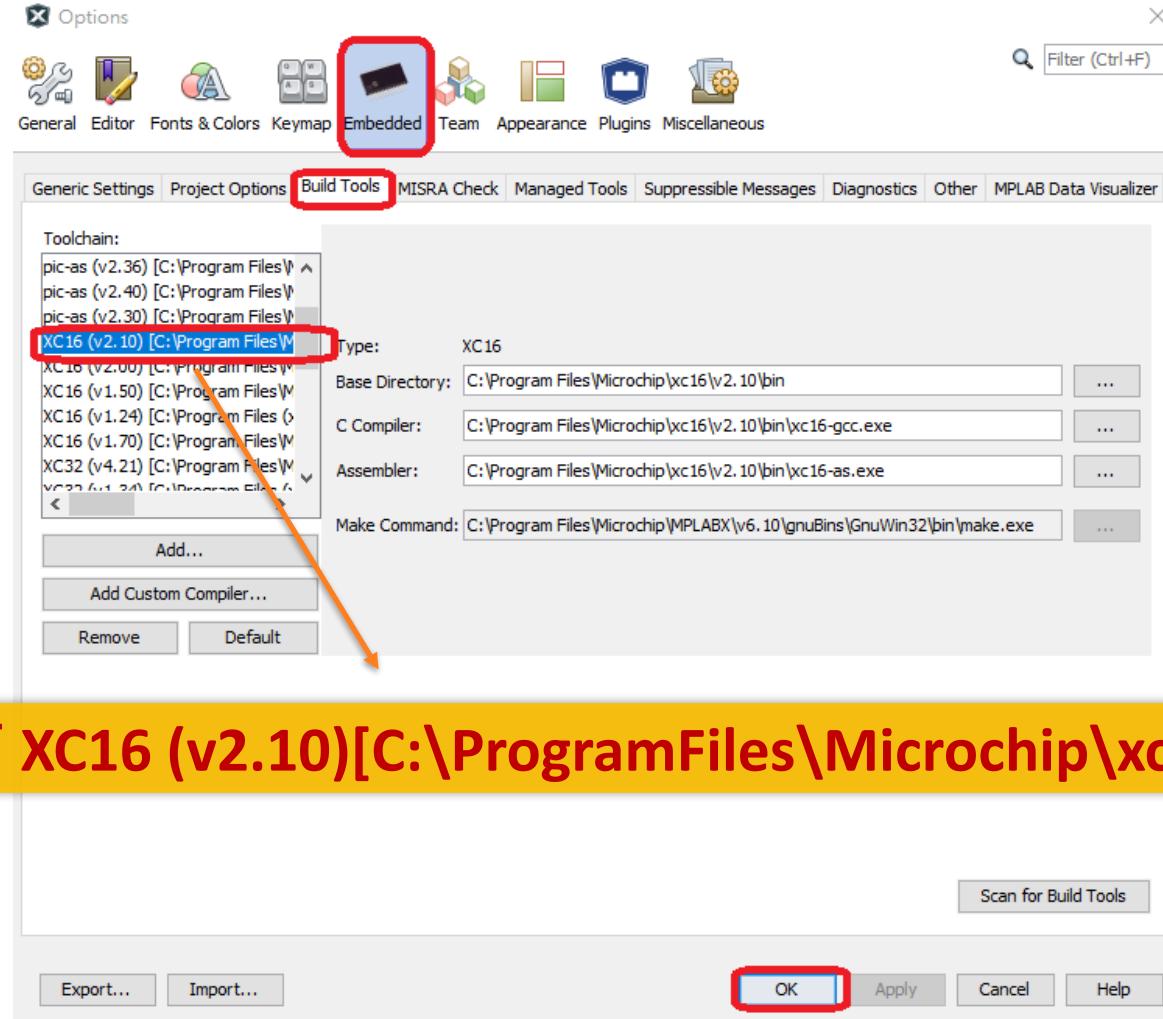
## 2. 確認XC16已安裝

選Tools --> Options



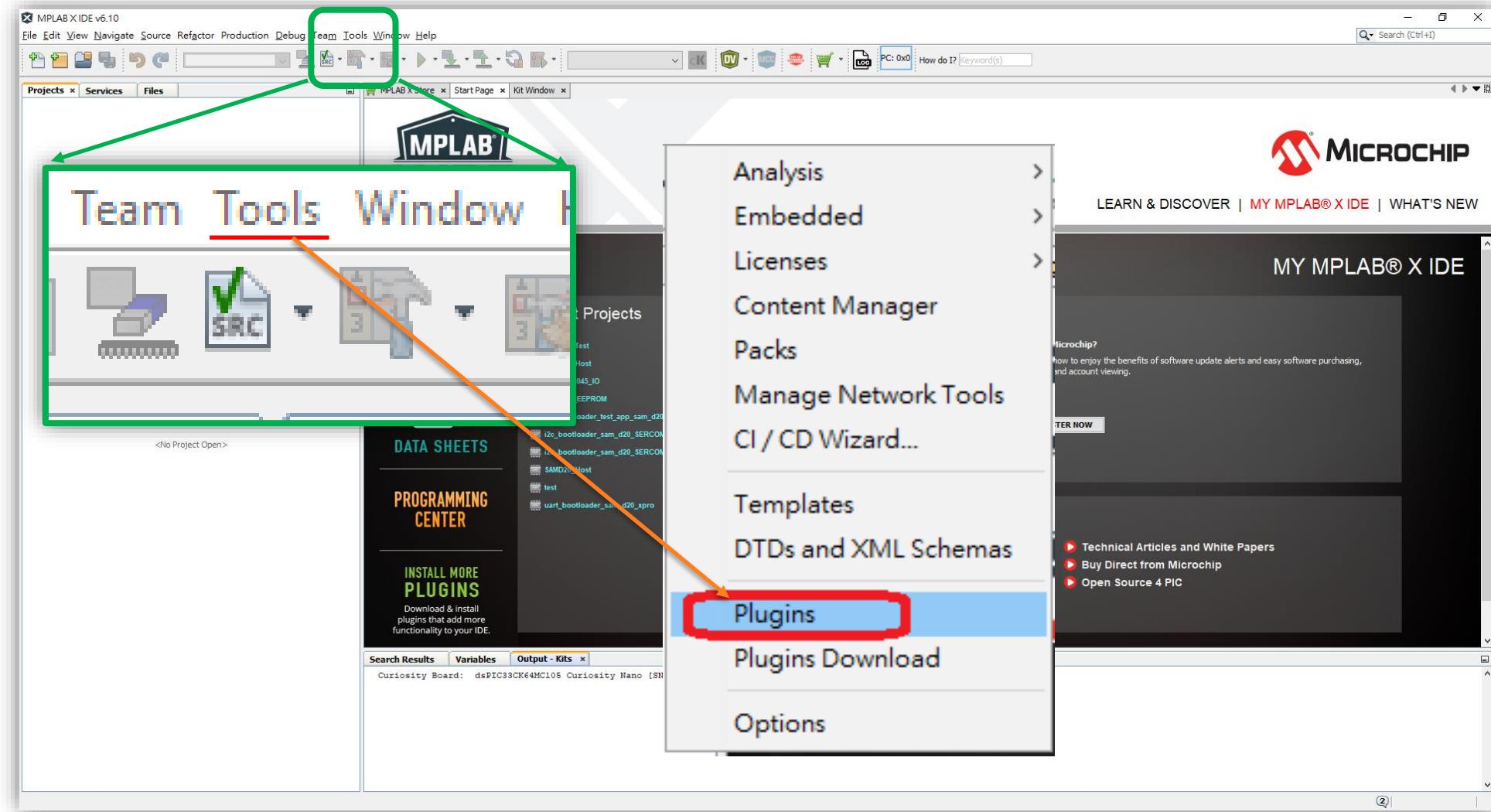
# 2.1確認XC16已安裝

## 確認XC16 v2.1已安裝



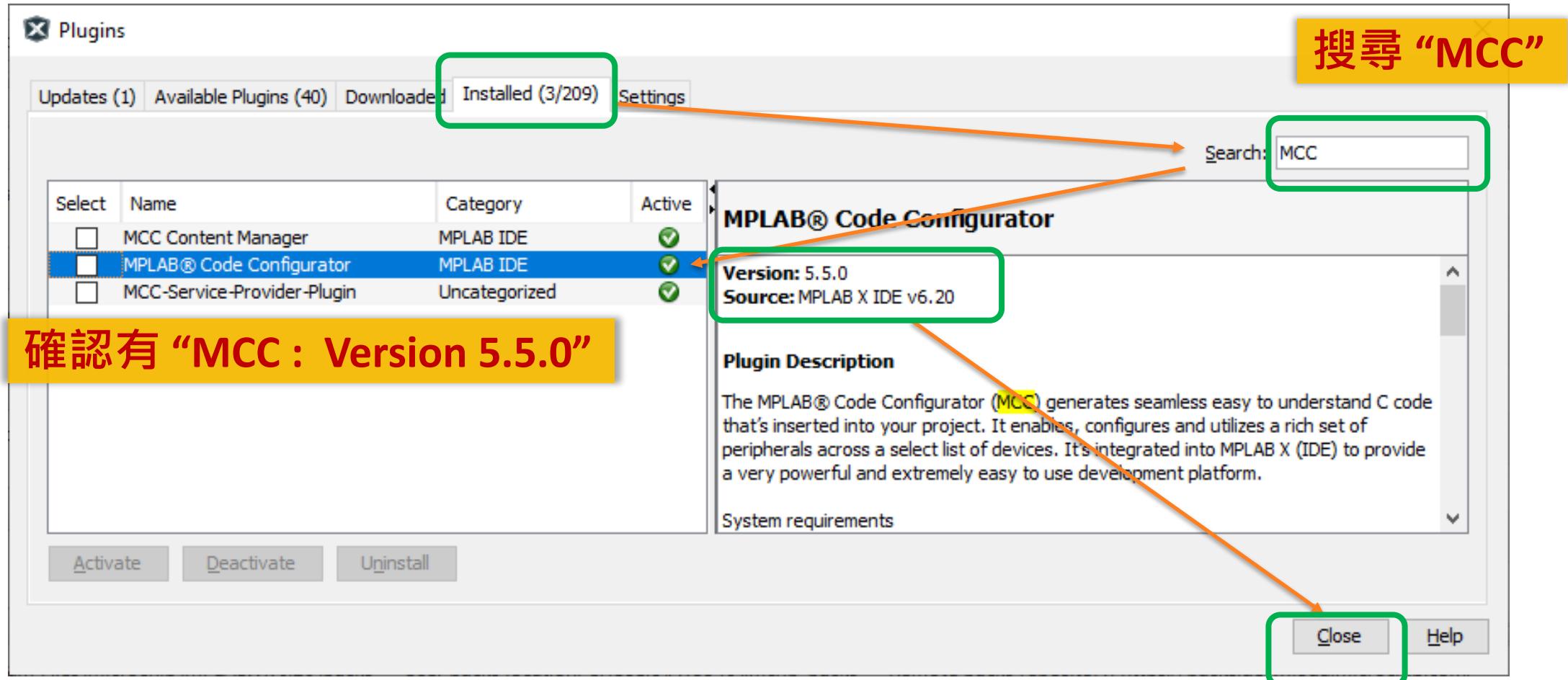
### 3. 確認MCC已安裝

選Tools --> Plugins



# 3.1確認MCC已安裝

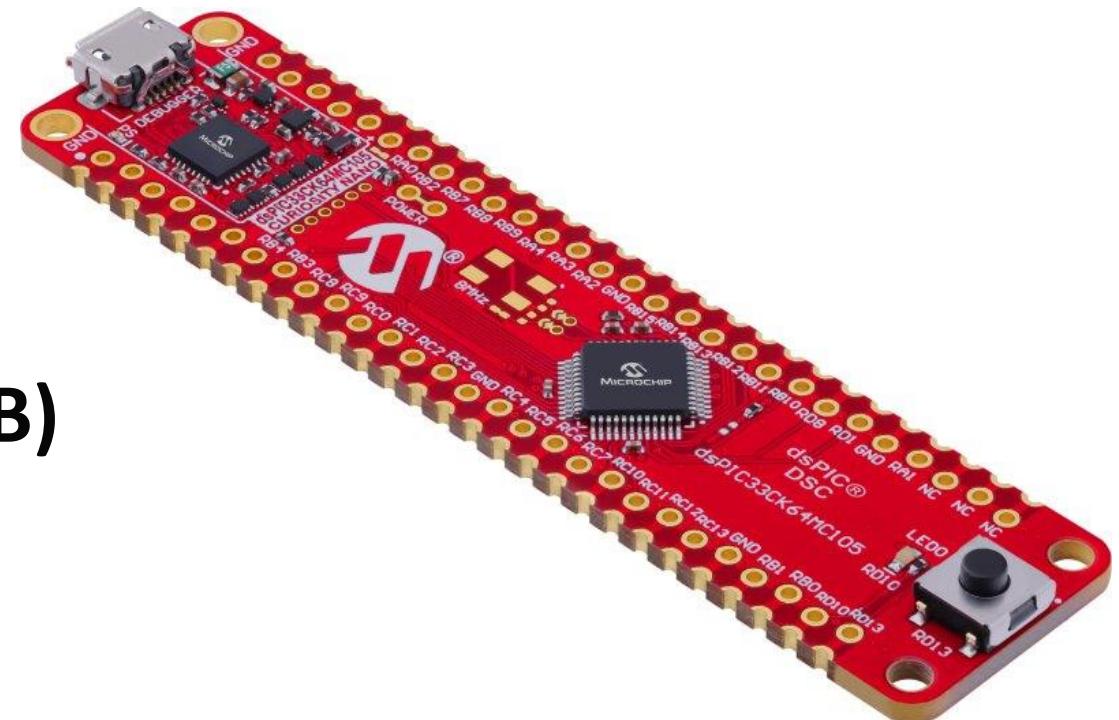
## 確認MCC v5.3.7已啟動(Active)



## 4. 確認硬體

# 入門實驗，一塊板子、一條USB線

- dsPIC33CK Curiosity Nano



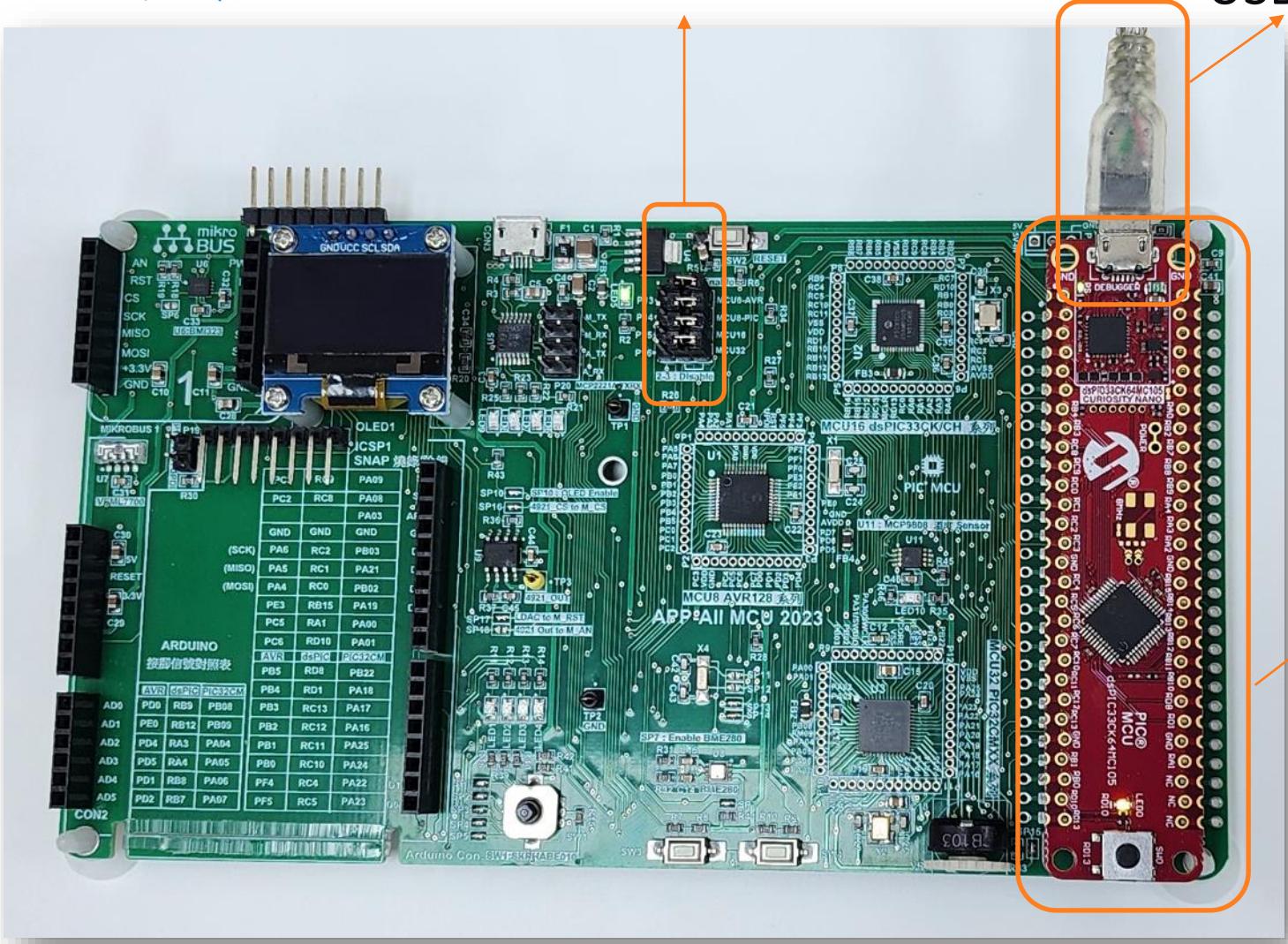
# 4.1 確認硬體

## 周邊實驗，組合完成

RESET板上四顆MCU

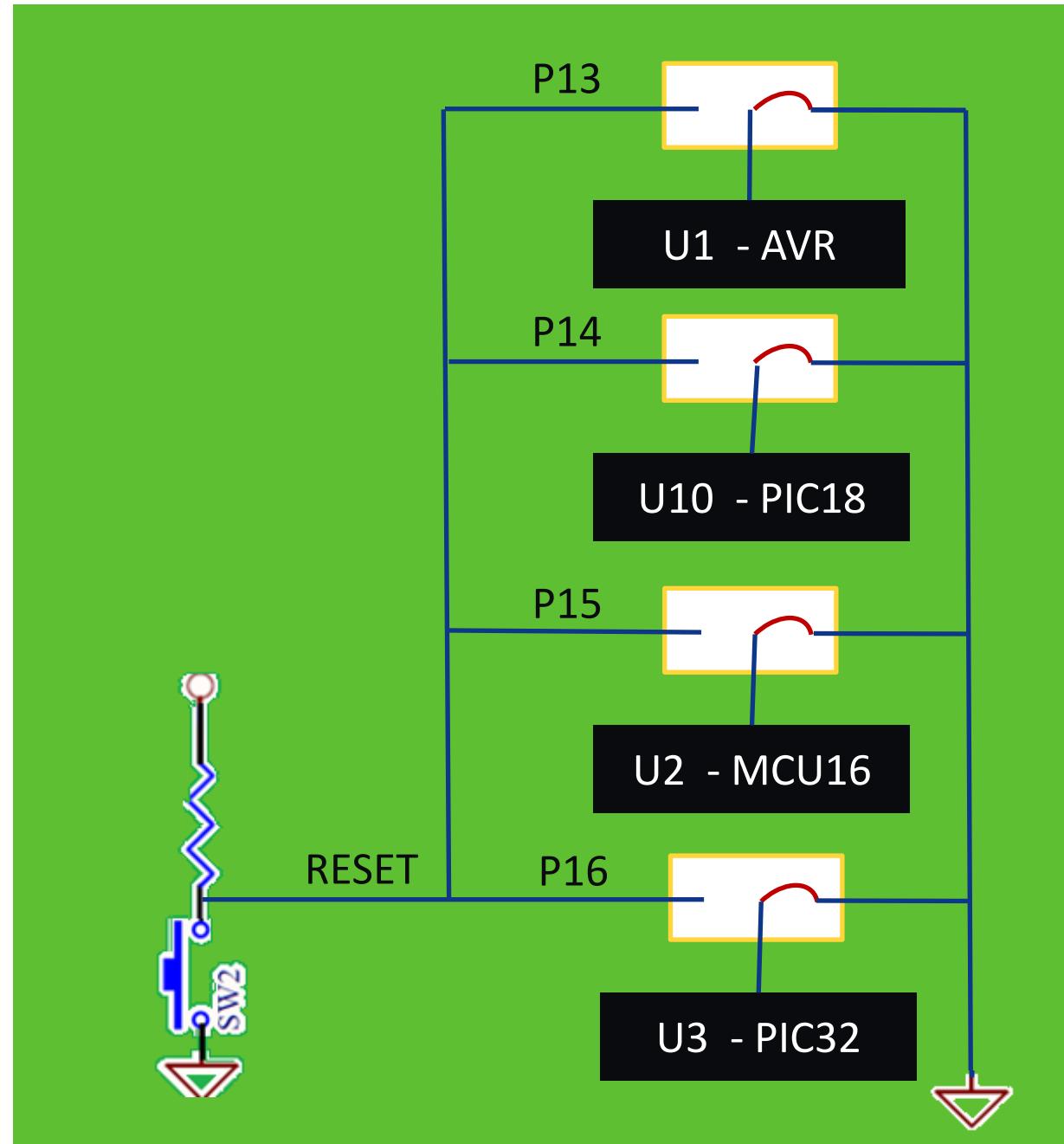
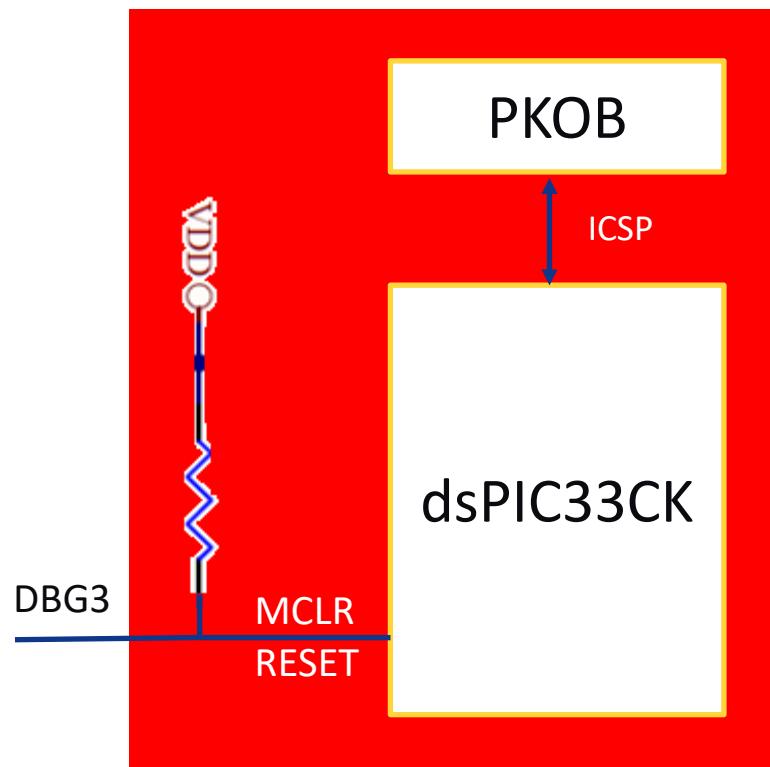
USB接到電腦

接到載板上→  
連接板上的  
LED等...



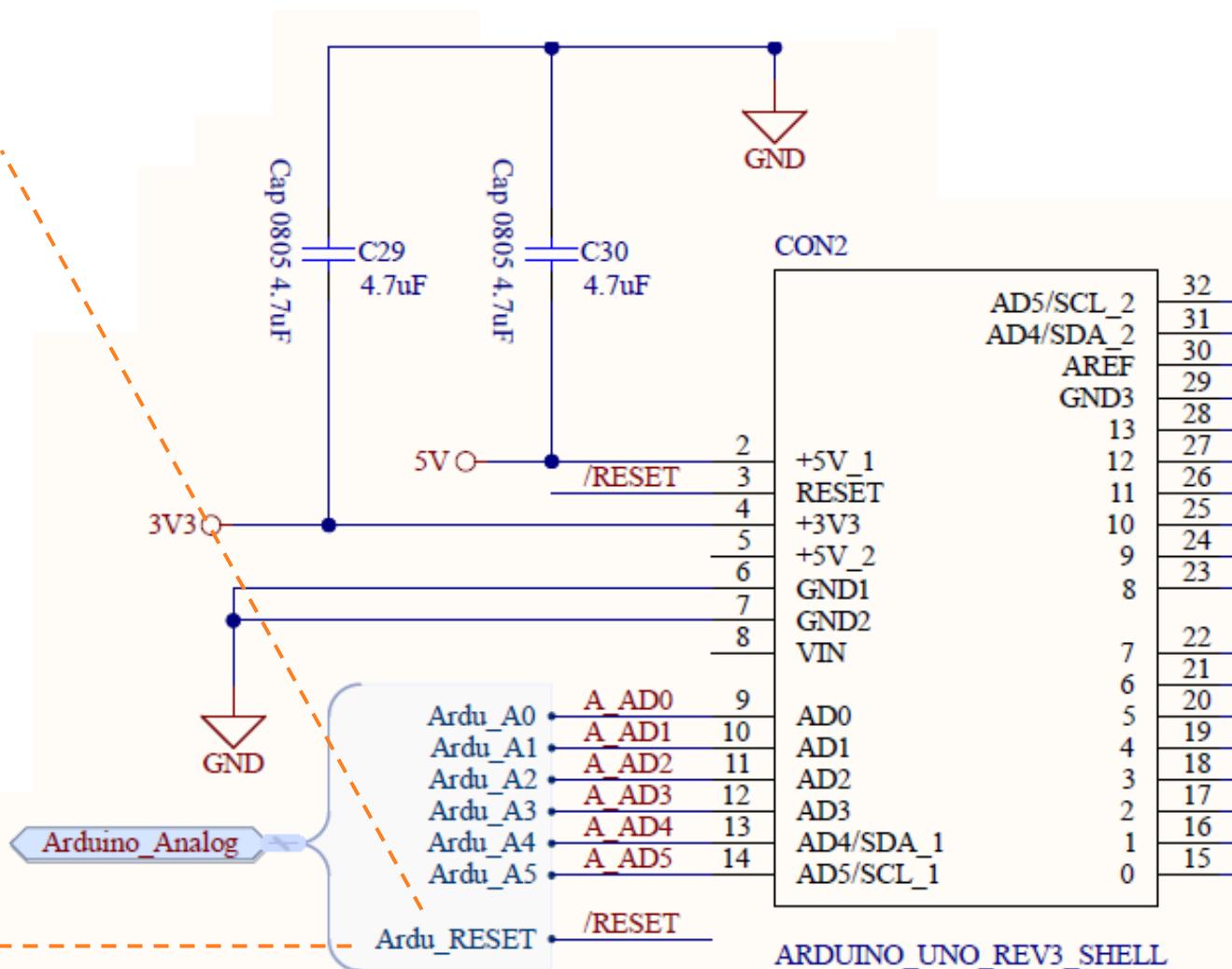
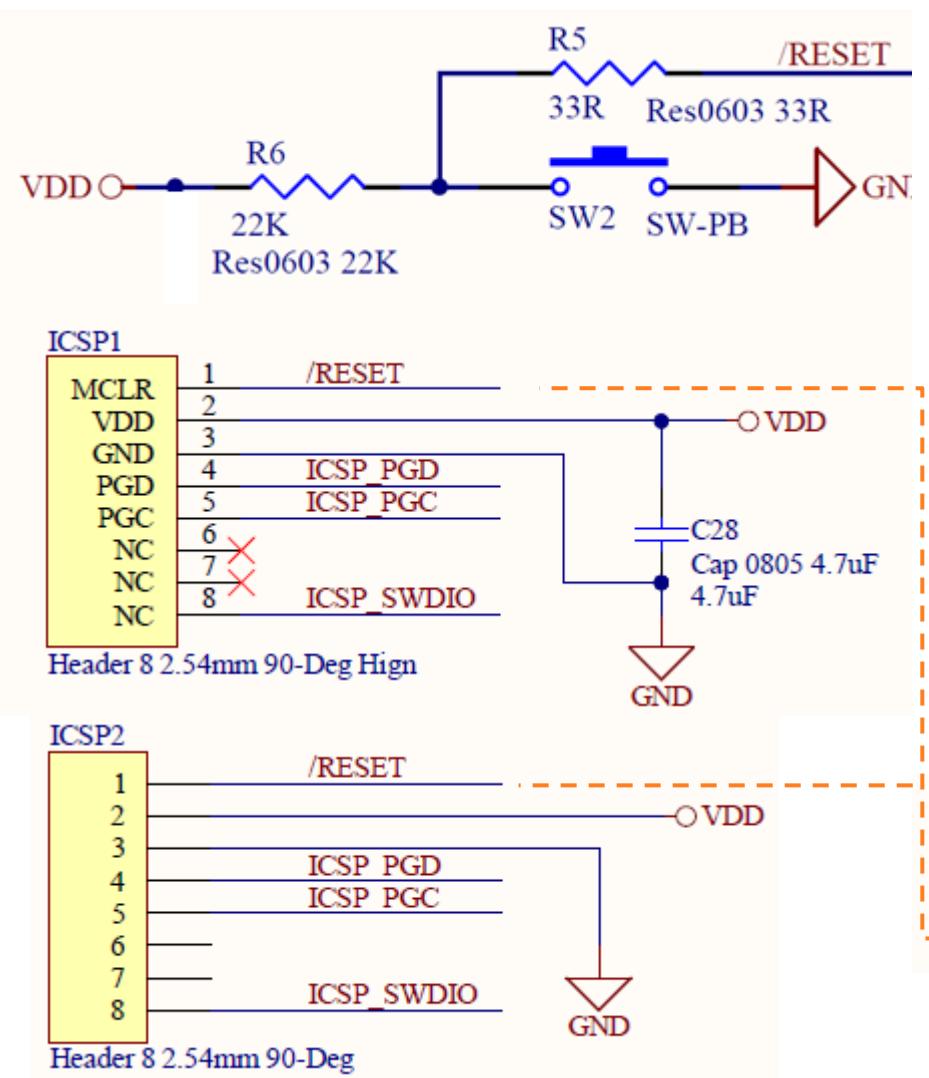
## 4.2 RESET架構圖

### RESET 相關連線



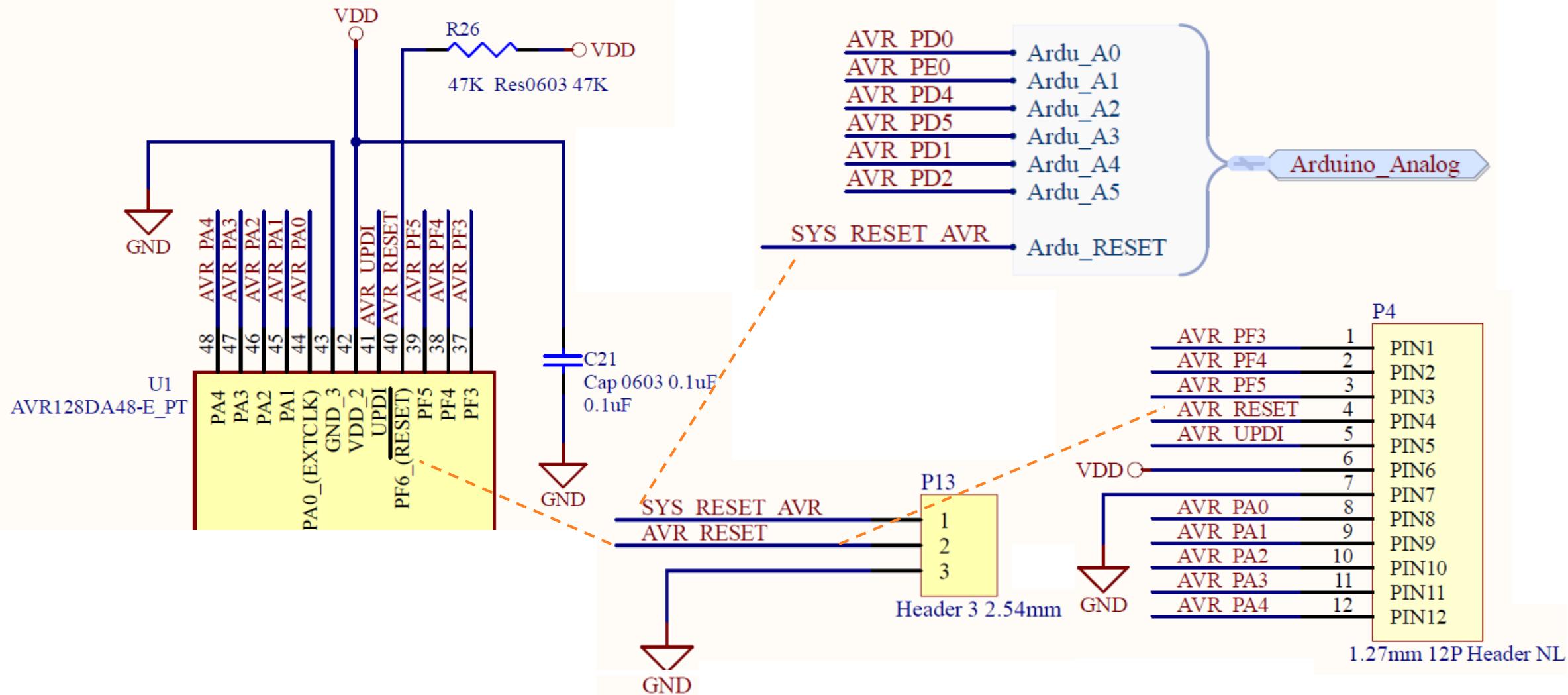
## 4.3 RESET相關電路

# SW2 - /RESET



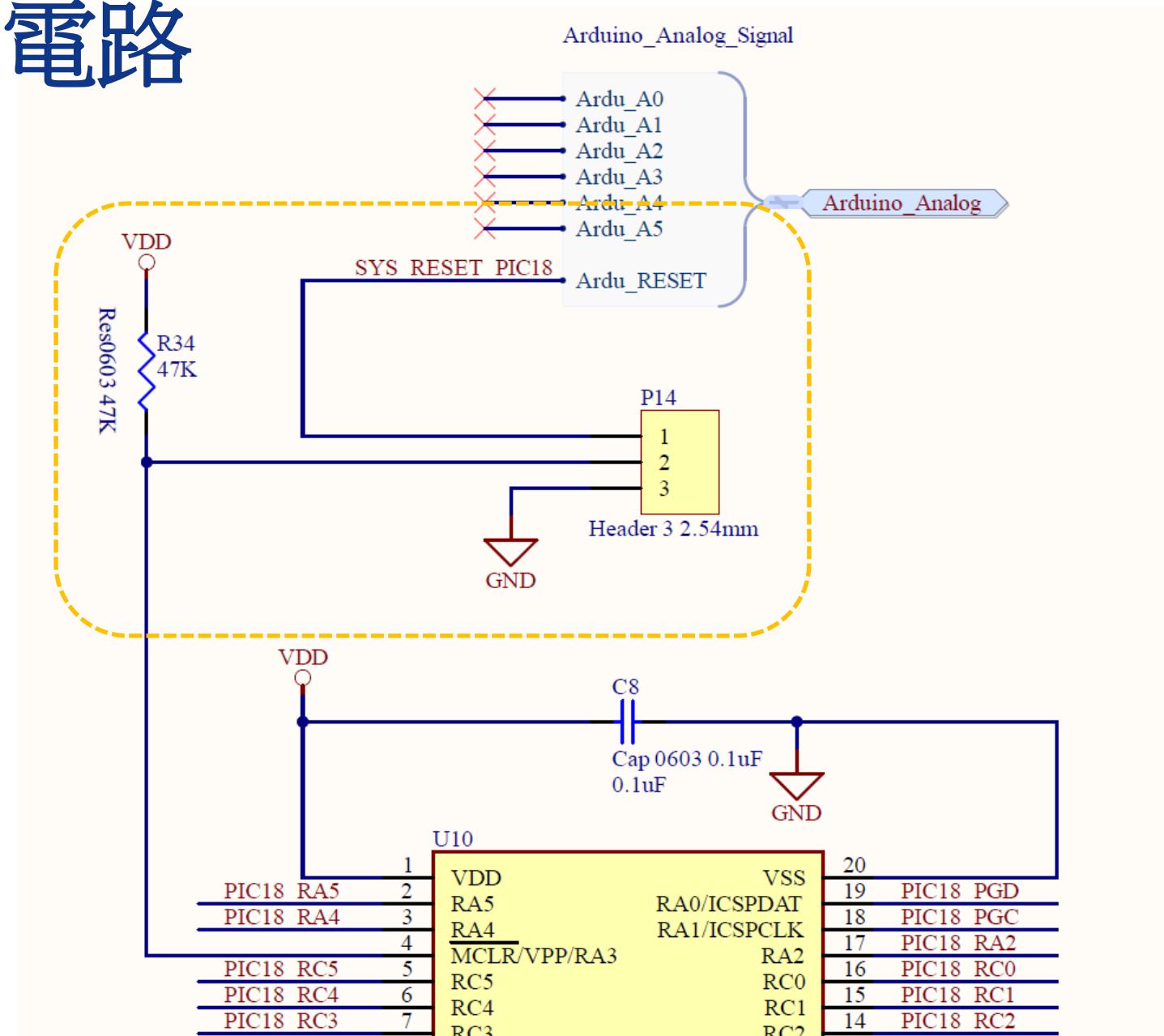
# 4.4 RESET相關電路

## P13 - AVR RESET



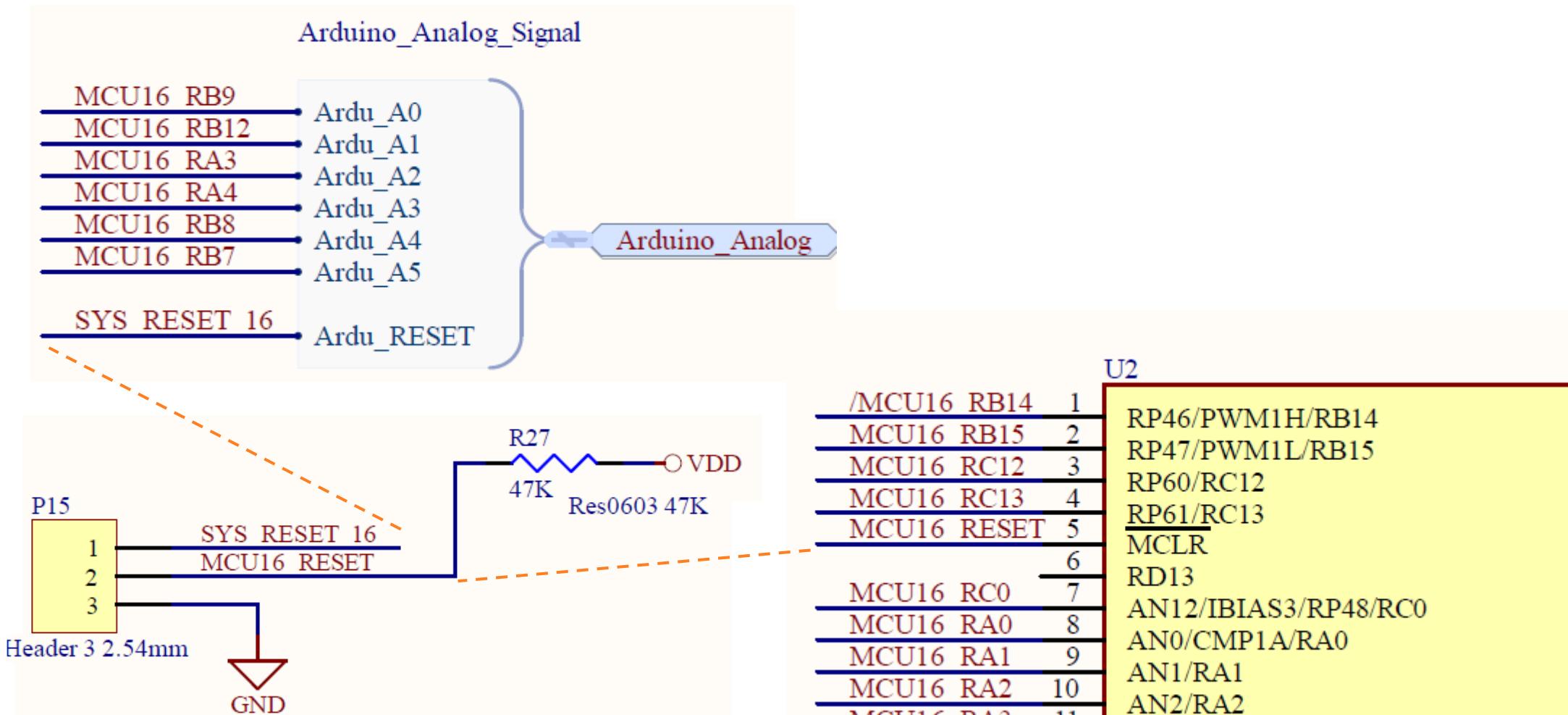
# 4.5 RESET相關電路

## P14 - PIC18 RESET



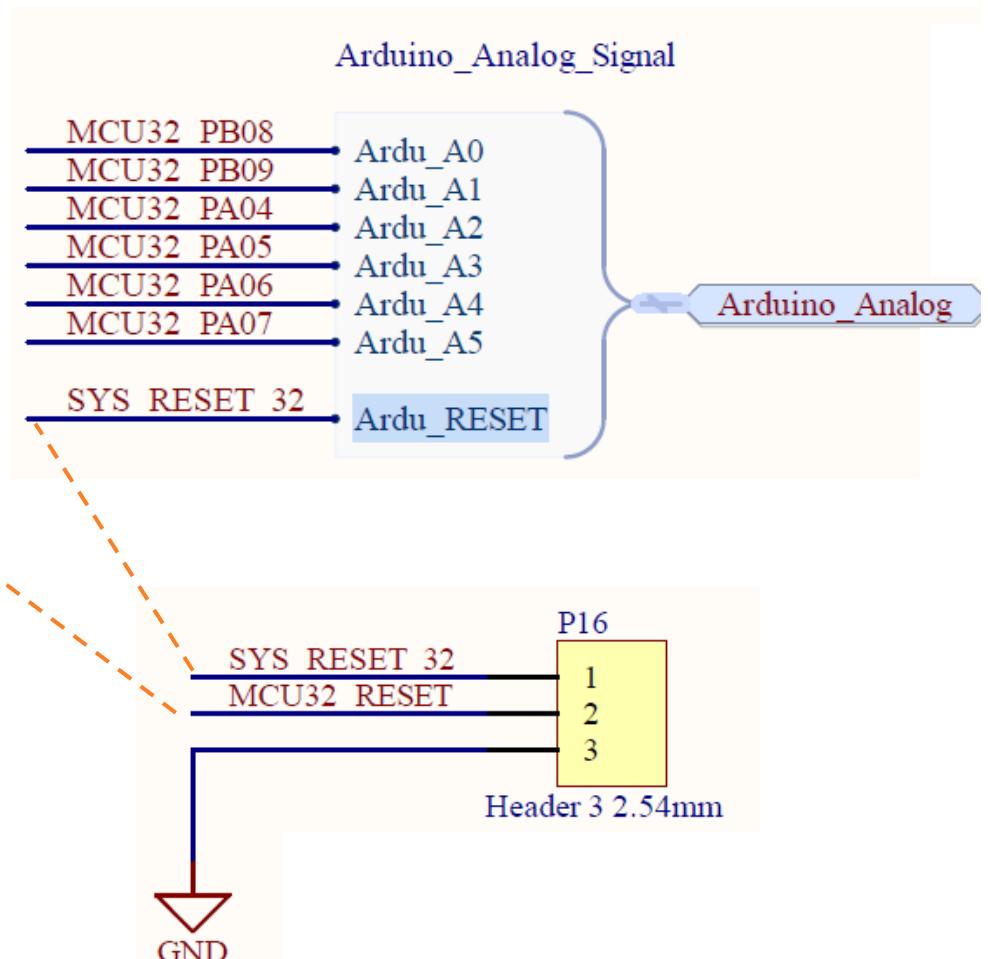
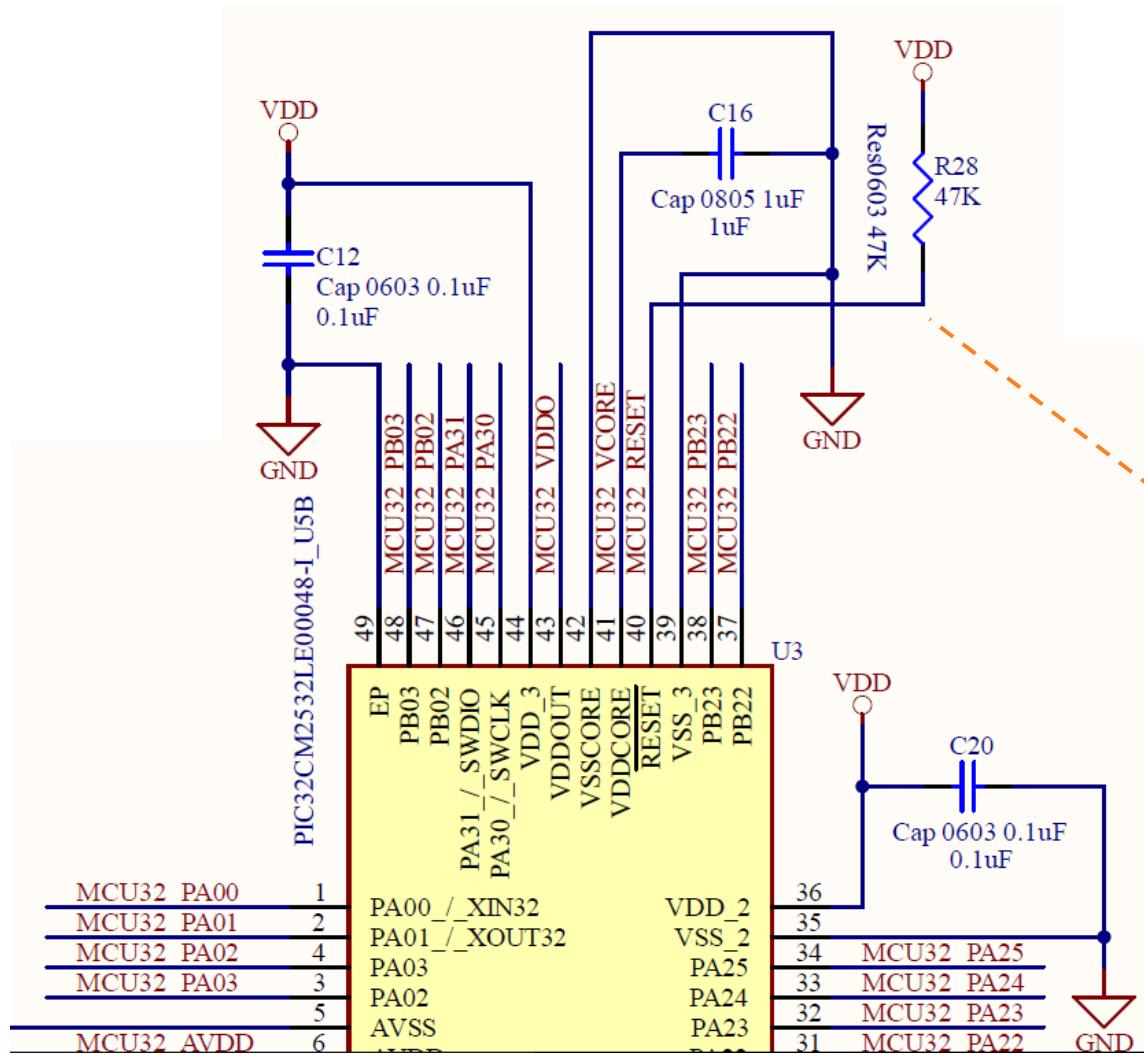
# 4.6 RESET相關電路

## P15 – MCU16 RESET



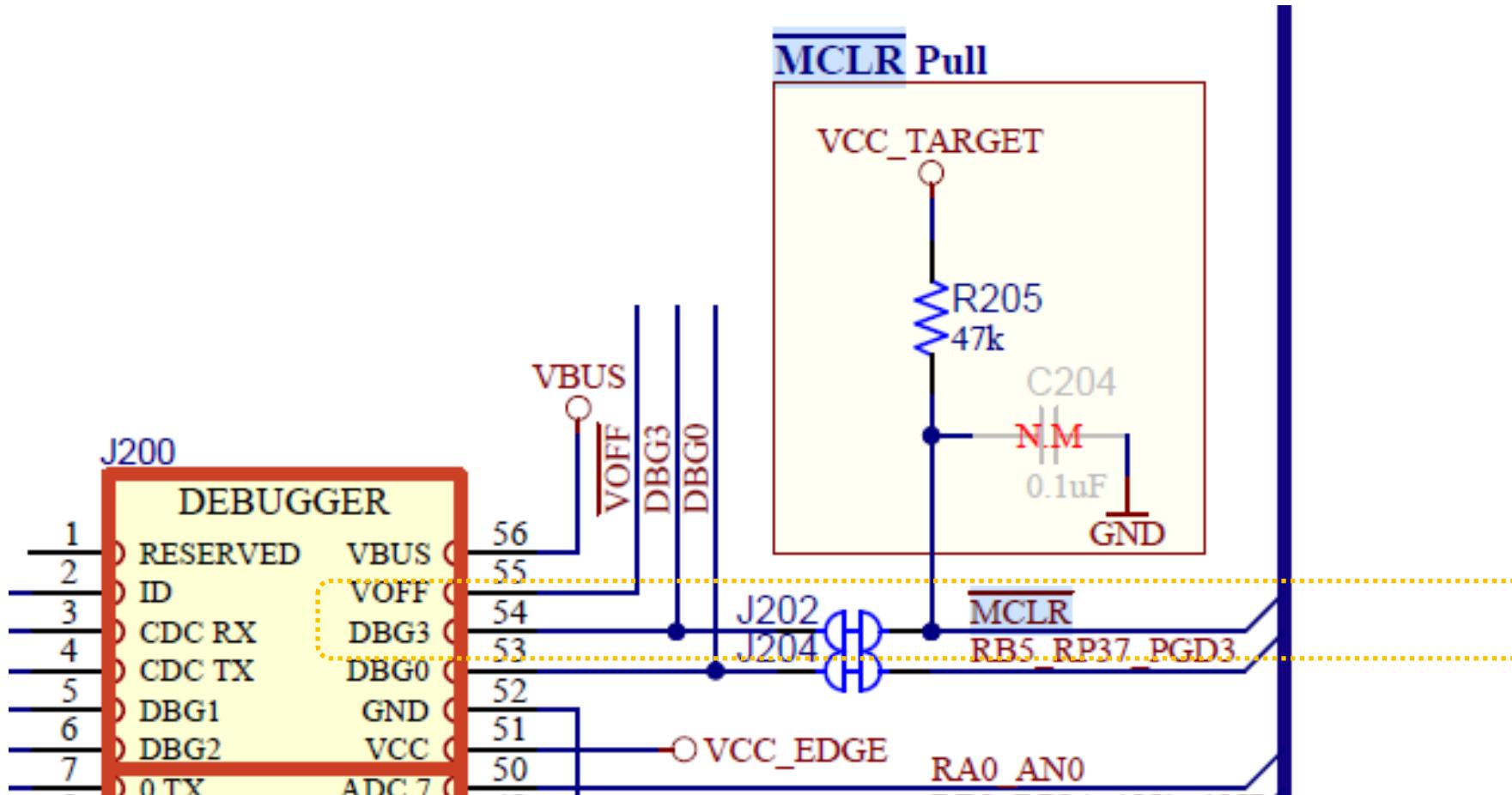
# 4.7 RESET相關電路

## P17 - PIC32 RESET



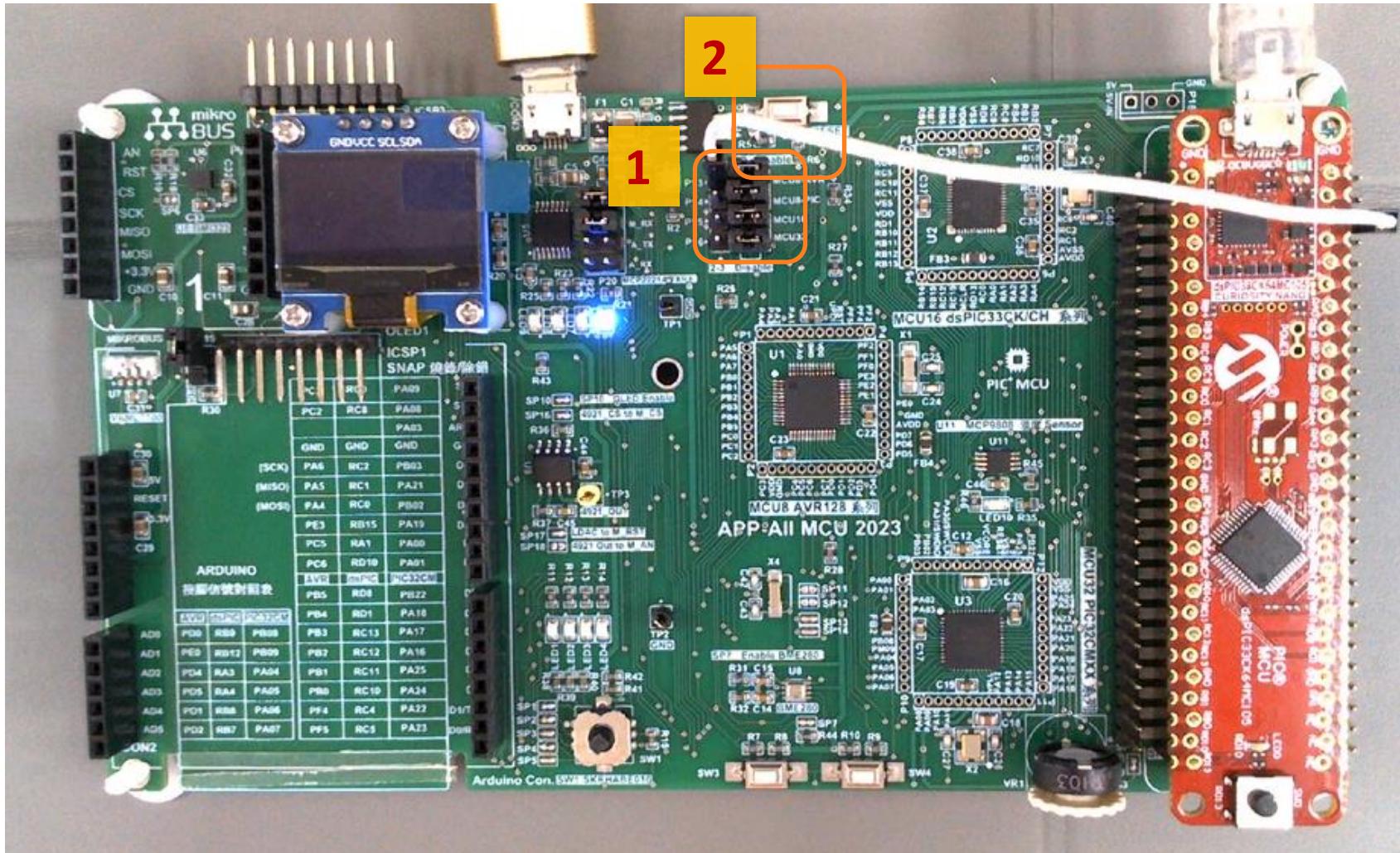
# 4.8 RESET相關電路

## 小板(dsPIC33CK) RESET

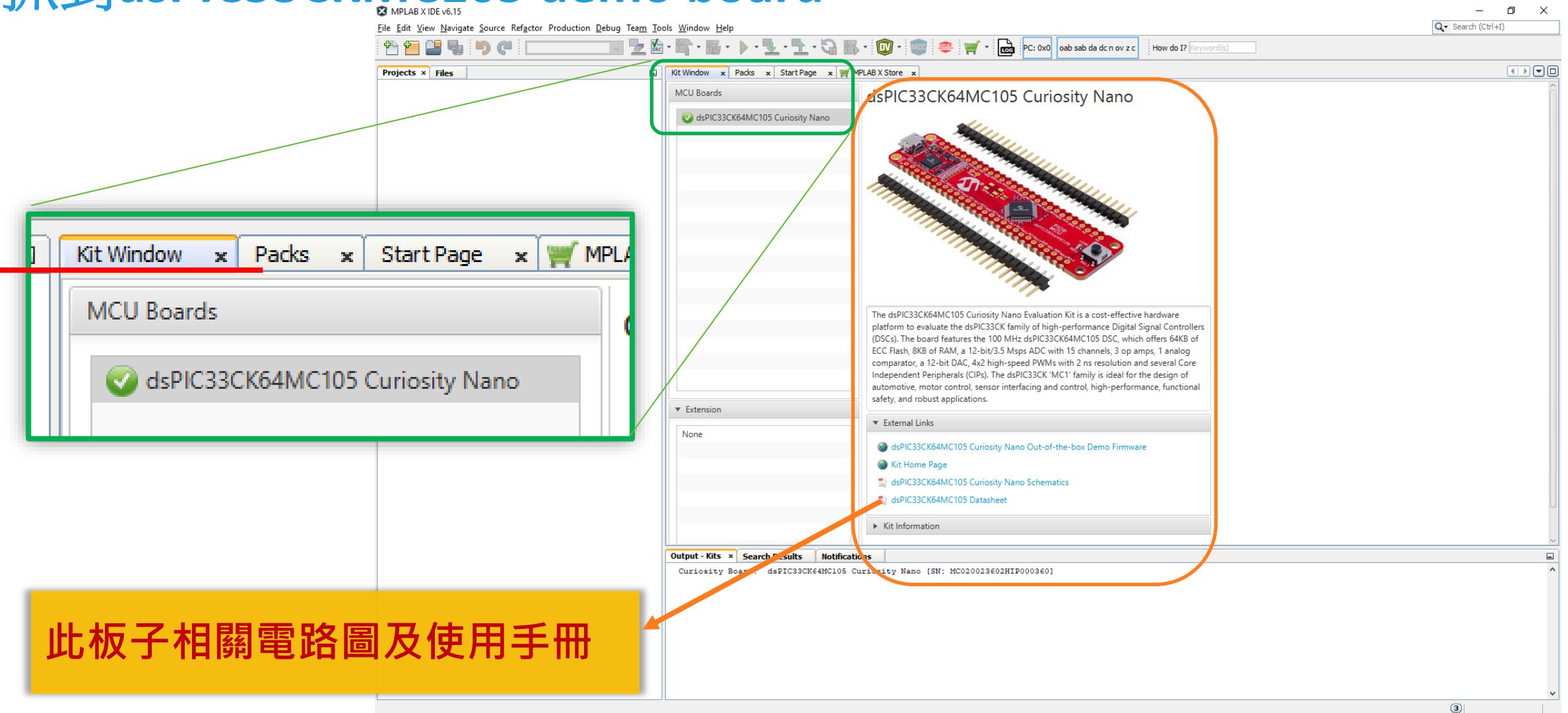


# 4.9 RESET相關線路

1. RESET板上四顆MCU  
P13~15  
pin2-3短路
2. 接上白線  
讓SW2控制  
dsPIC33CK  
的 MCLR  
(可不接)



# 5. 開啟MPLAB X IDE 抓到dsPIC33CKMC105 demo board



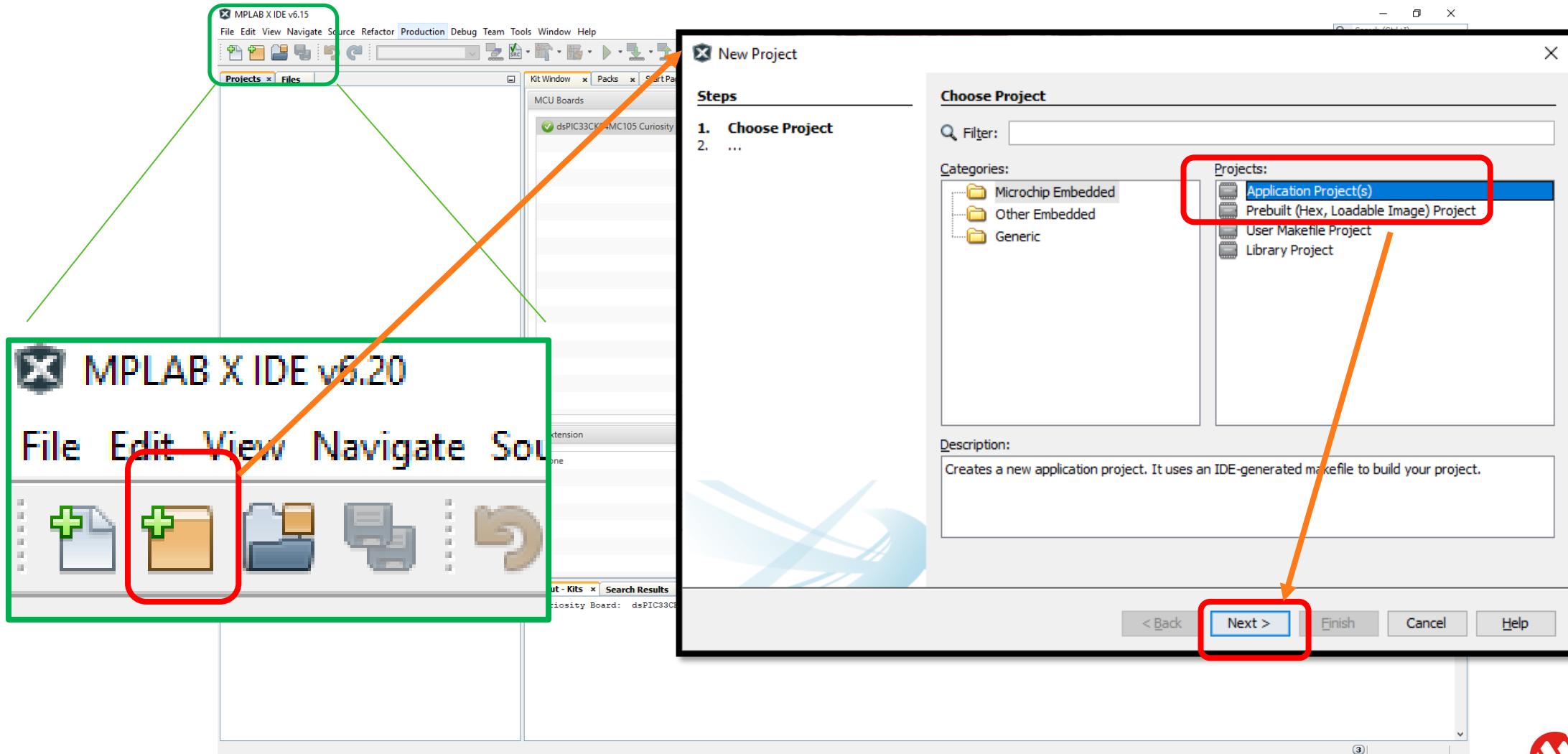
# 實驗步驟

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實驗一

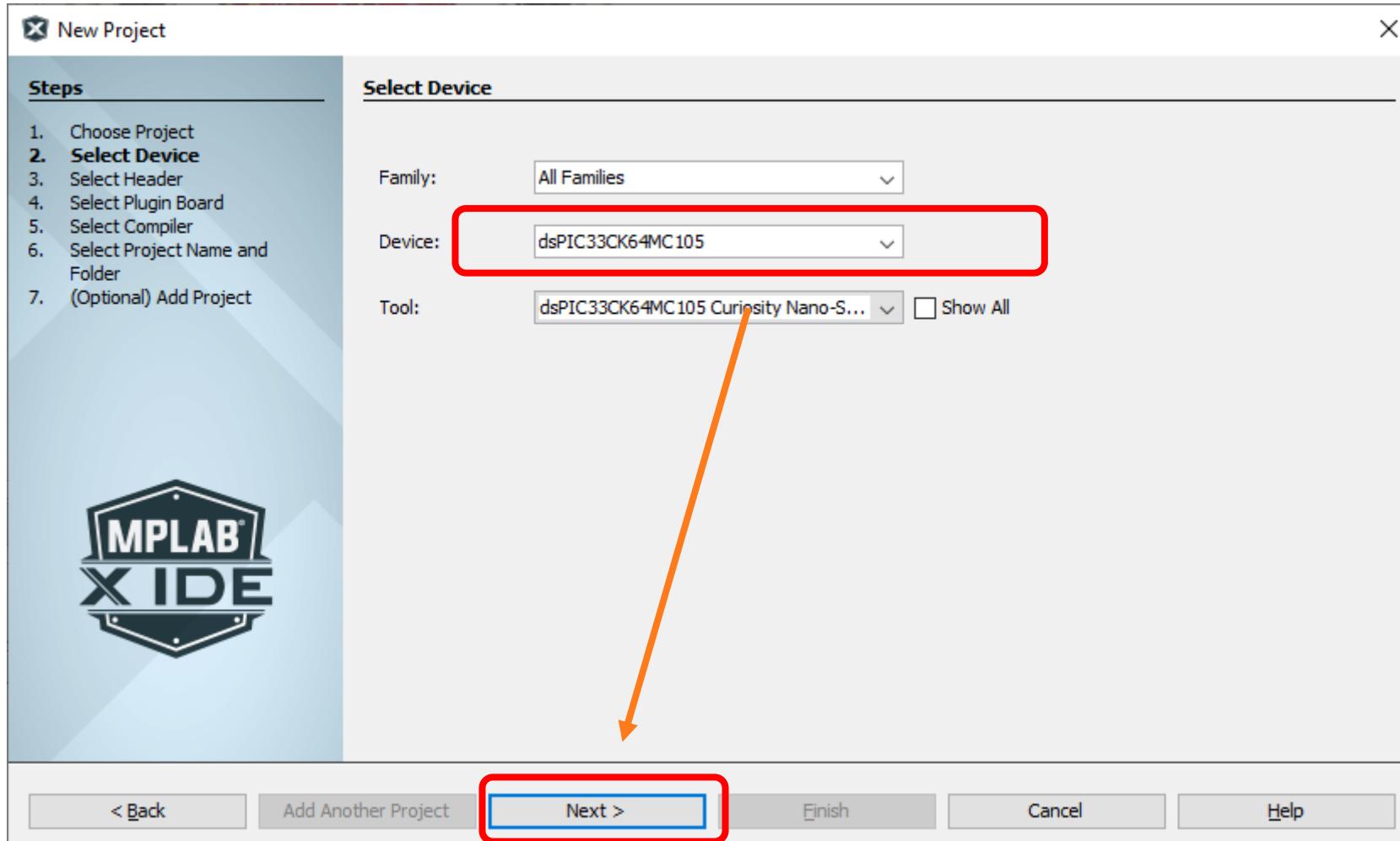
# 1. 開一個新的專案

點選  啟動Project精靈，選Application Project(s)



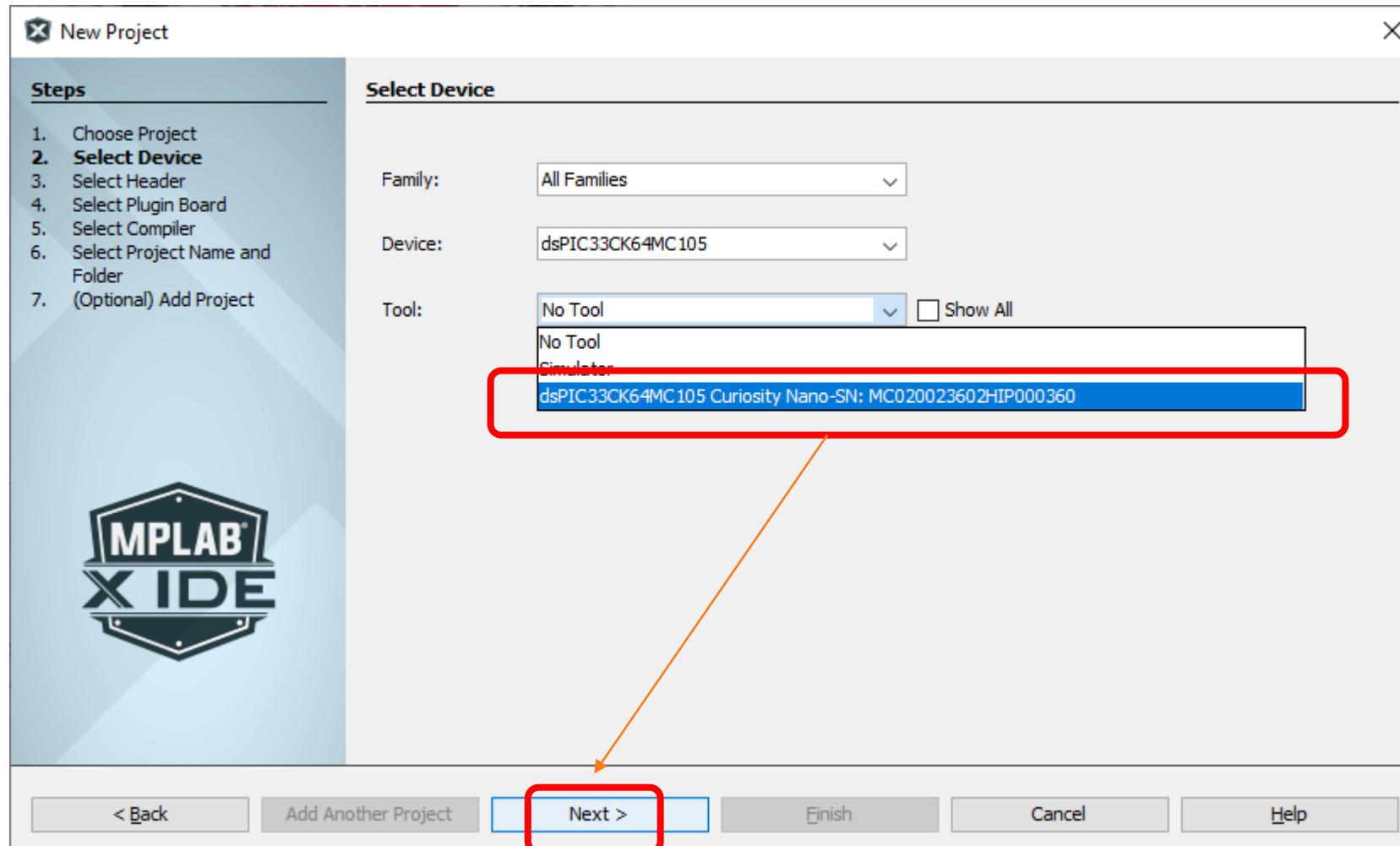
## 2. 選IC型號

dsPIC33CK64MC105

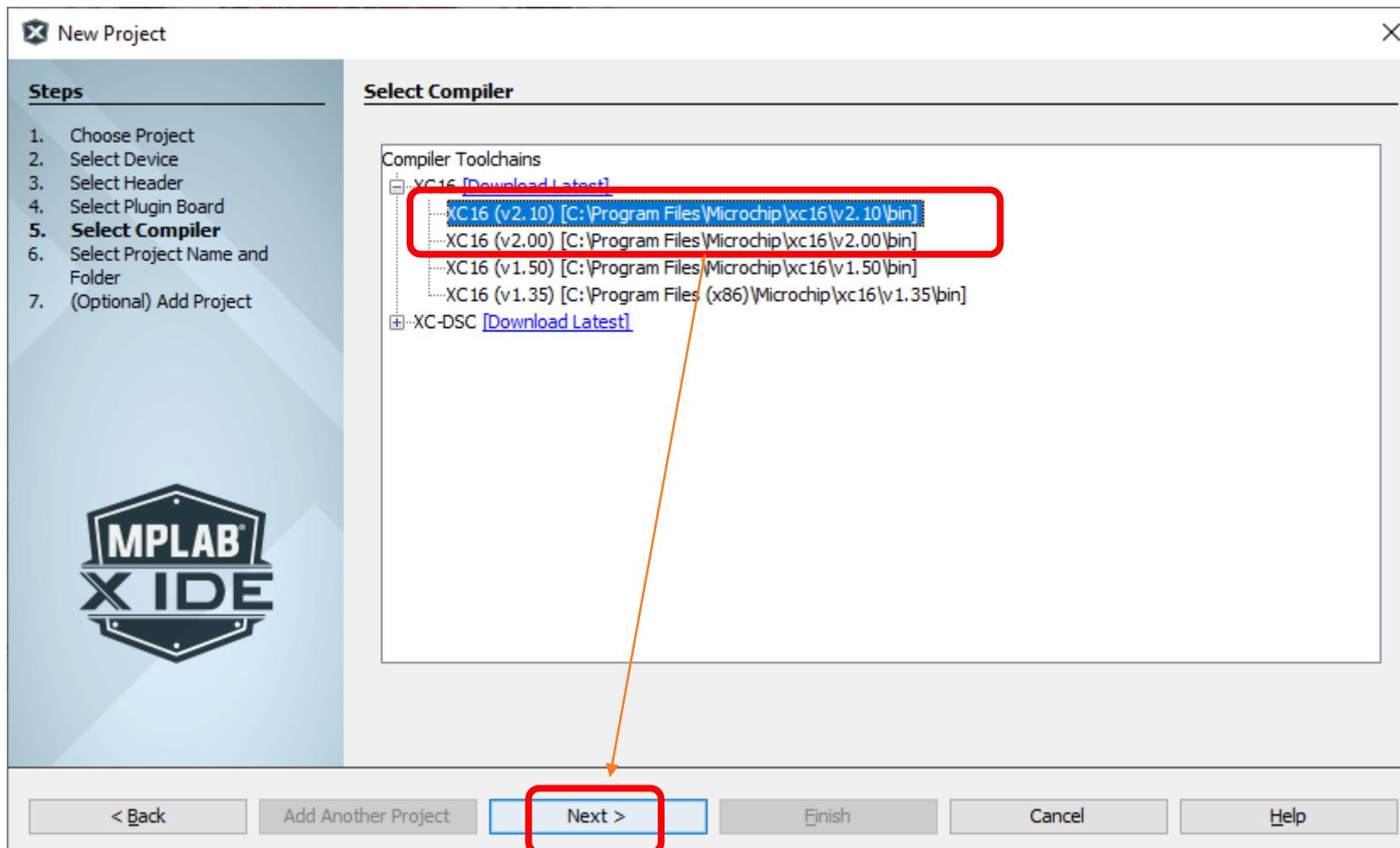


### 3. 選燒錄器(Tool)

dsPIC33CK64MC105 Curiosity Nano-SN:xxxx



# 4. 選編輯軟體 XC16 (v2.10)



# 5. 設定專案名稱

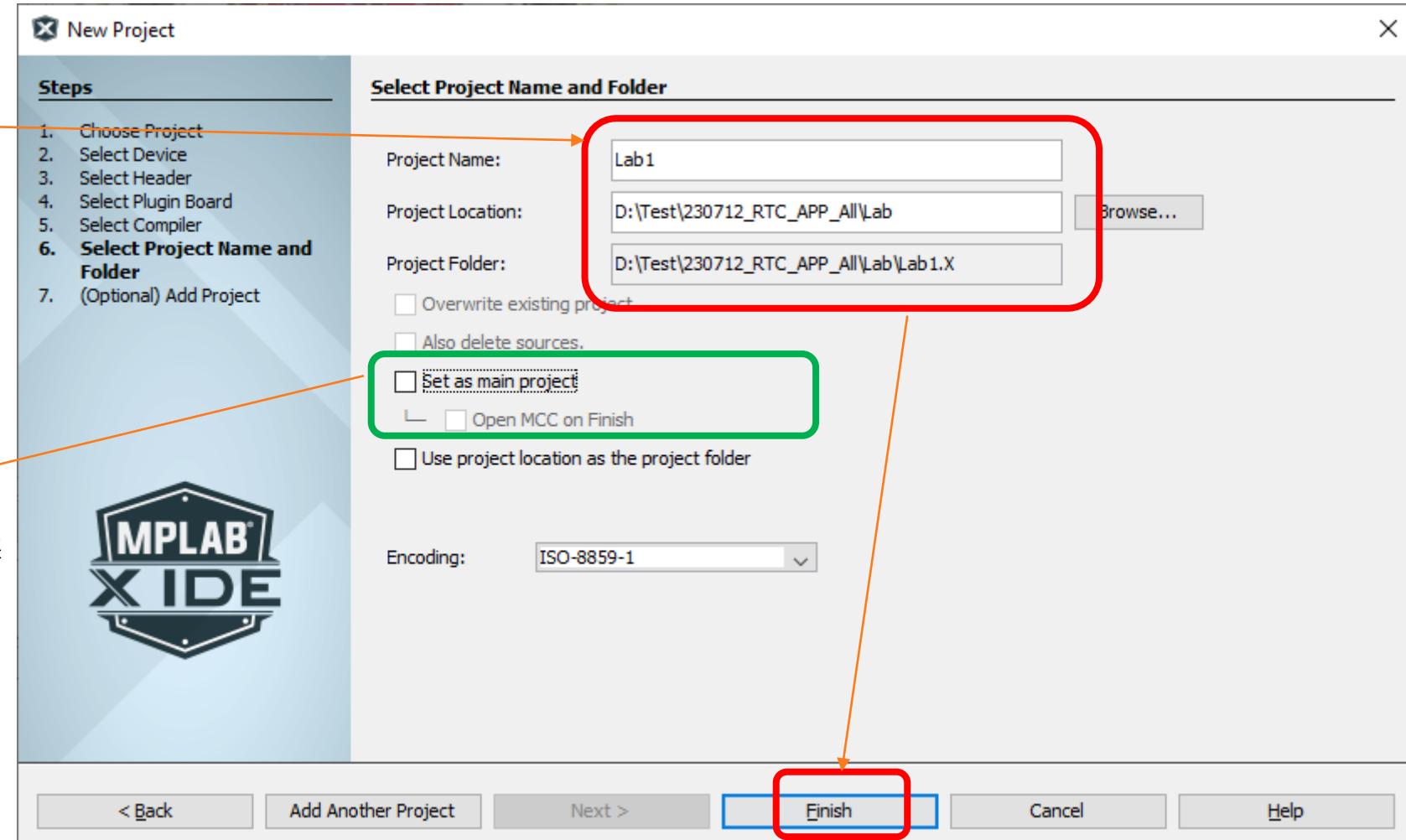
Lab1

- **Lab1**

- 此專案名字可自訂
- 但不能太長
- 不要中文或特殊符號

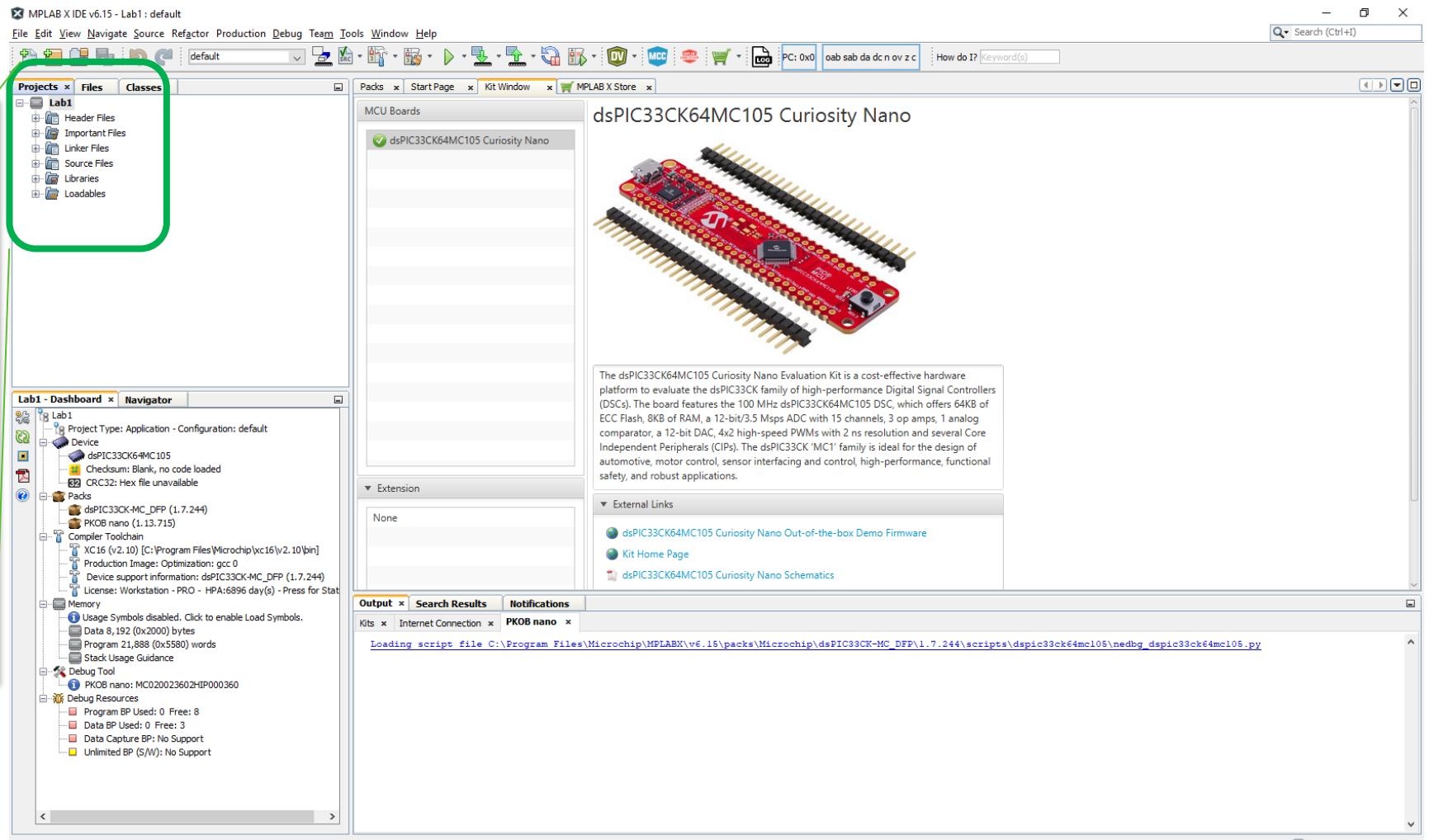
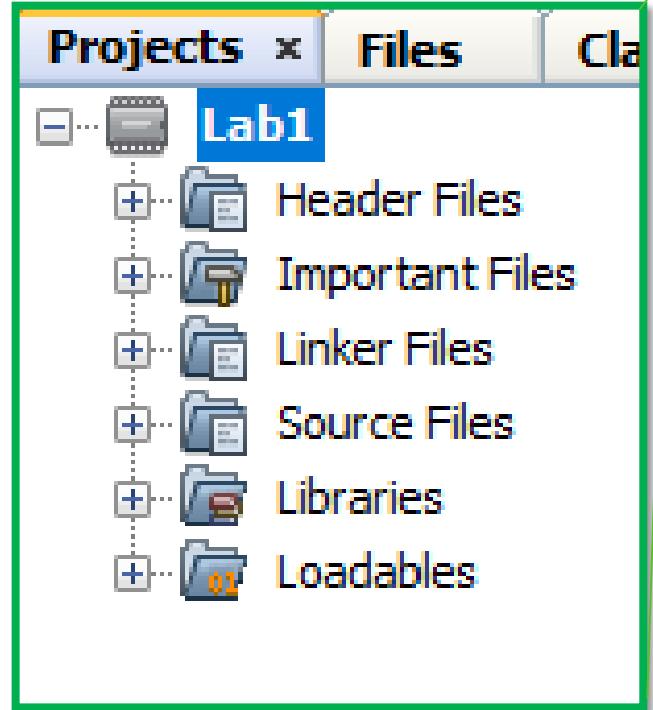
- **Set as main project**

- Open MCC on Finish
- 取消打勾，就不會直接開MCC



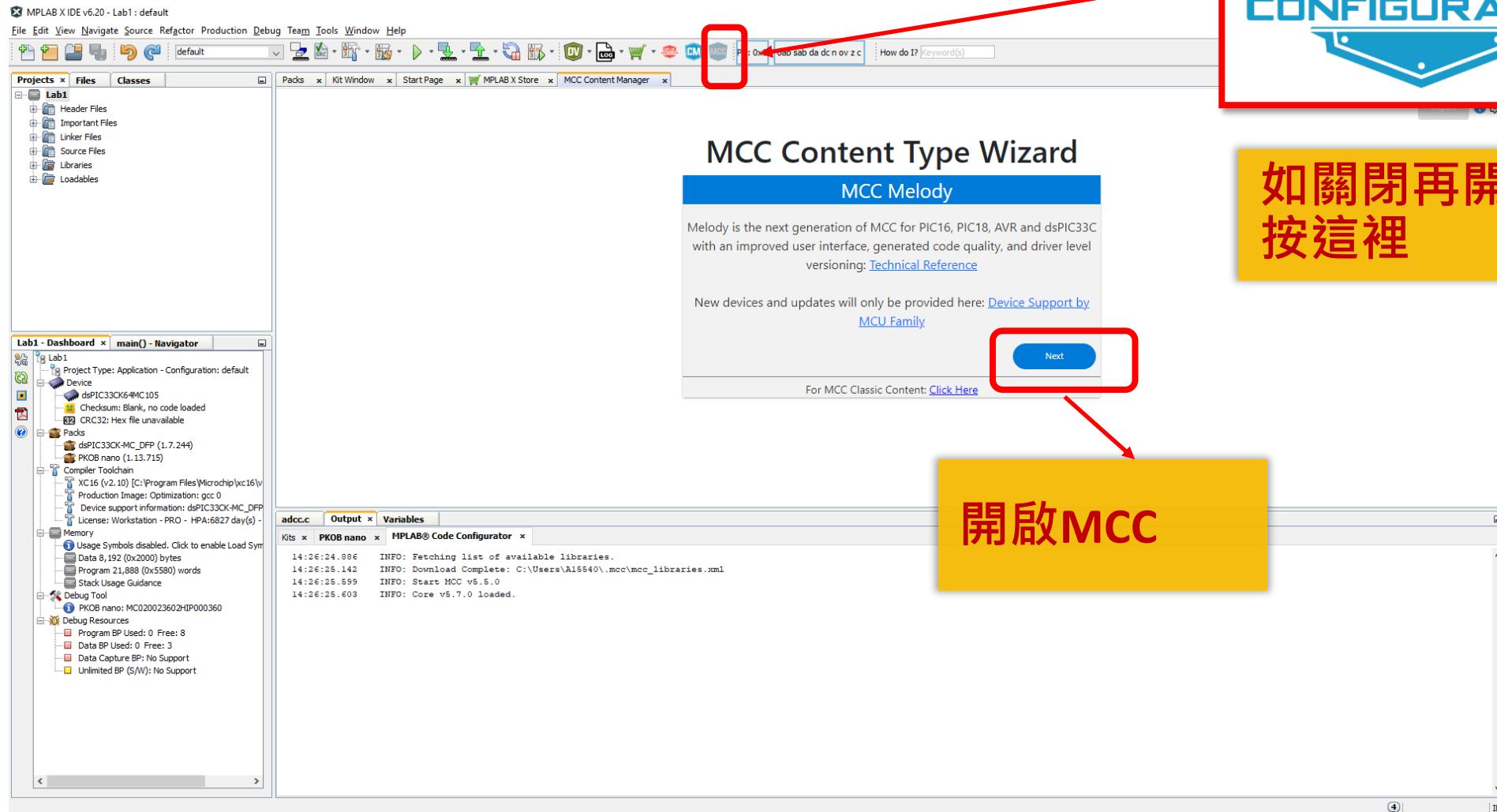
# 6. 專案框架完成

此時資料夾是空的



# 7. 開啟MCC Melody

點選 **NEXT**



如關閉再開  
按這裡

# 8. 選用MCC

## MPLAB IDE v6.20默認開啟Melody

要用Classic要選

### MCC Content Type Wizard

#### MCC Melody

Melody is the next generation of MCC for PIC16, PIC18, AVR and dsPIC33C with an improved user interface, generated code quality, and driver level versioning: [Technical Reference](#)

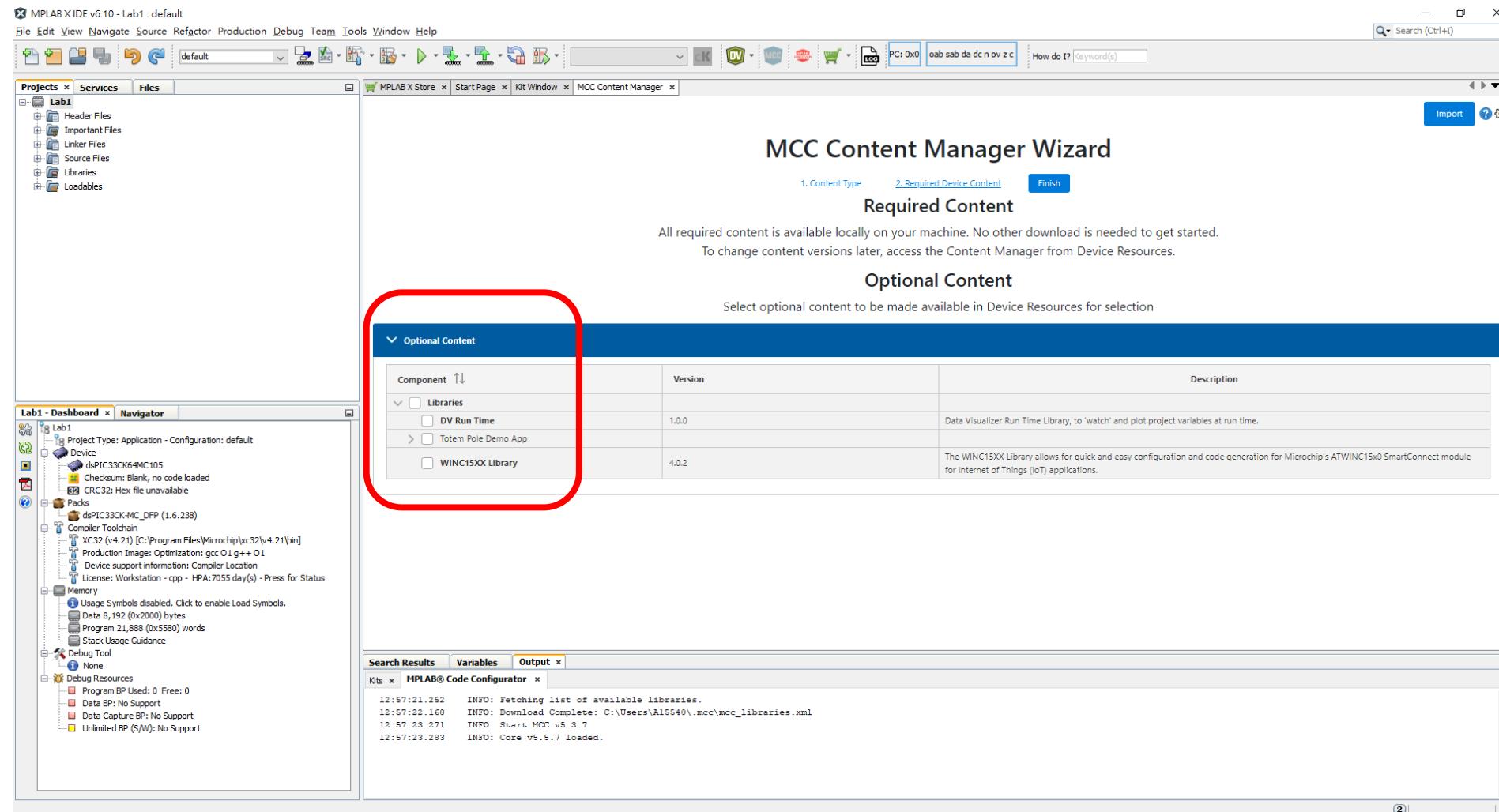
New devices and updates will only be provided here: [Device Support by MCU Family](#)

Next

For MCC Classic Content: [Click Here](#)

# 9. 選所需程式庫

根據專案需求選程式庫，可以不選



# 10. MCC GUI

## 開啟

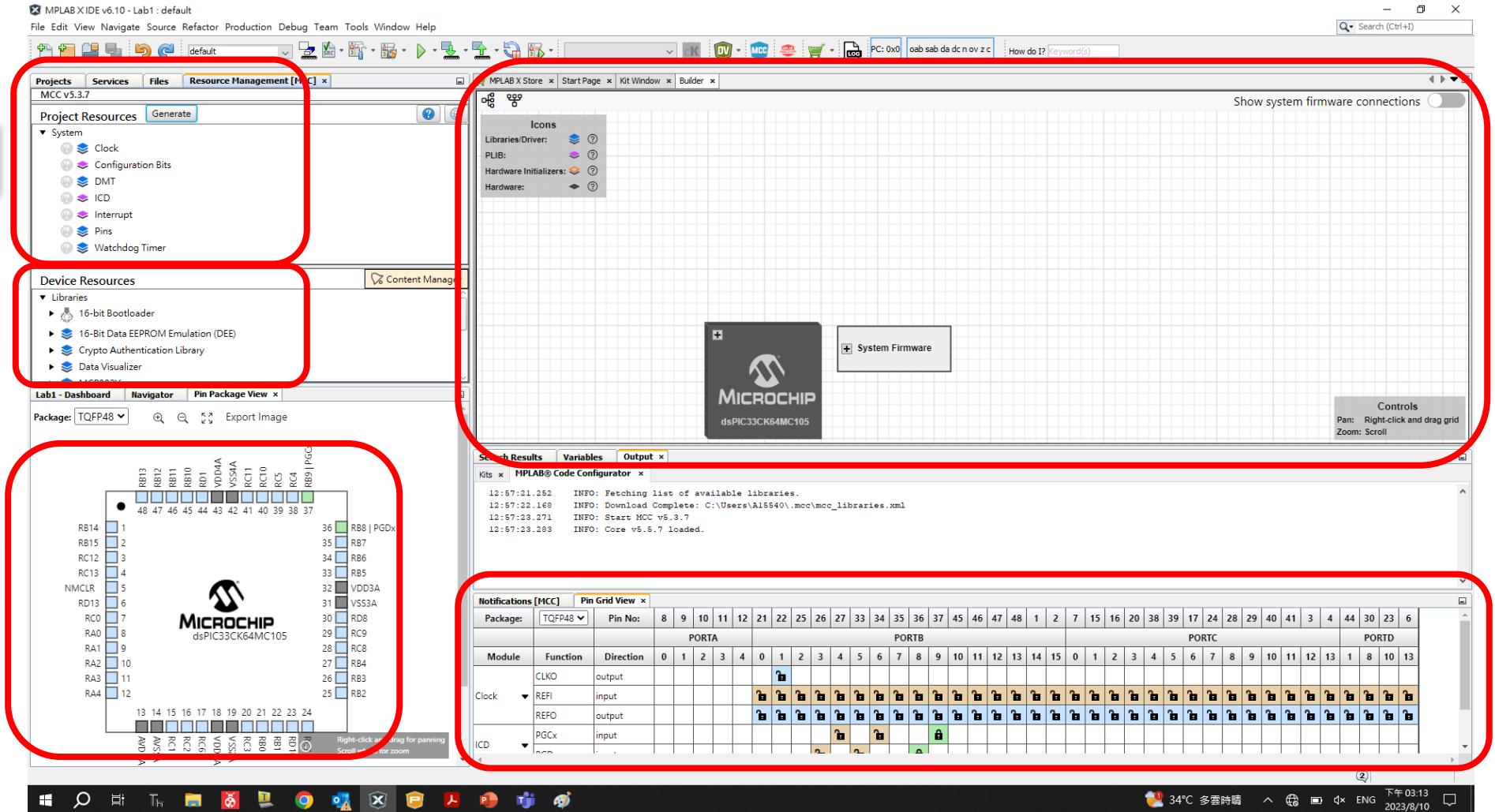
IC使用資源

IC可用資源

腳位規劃

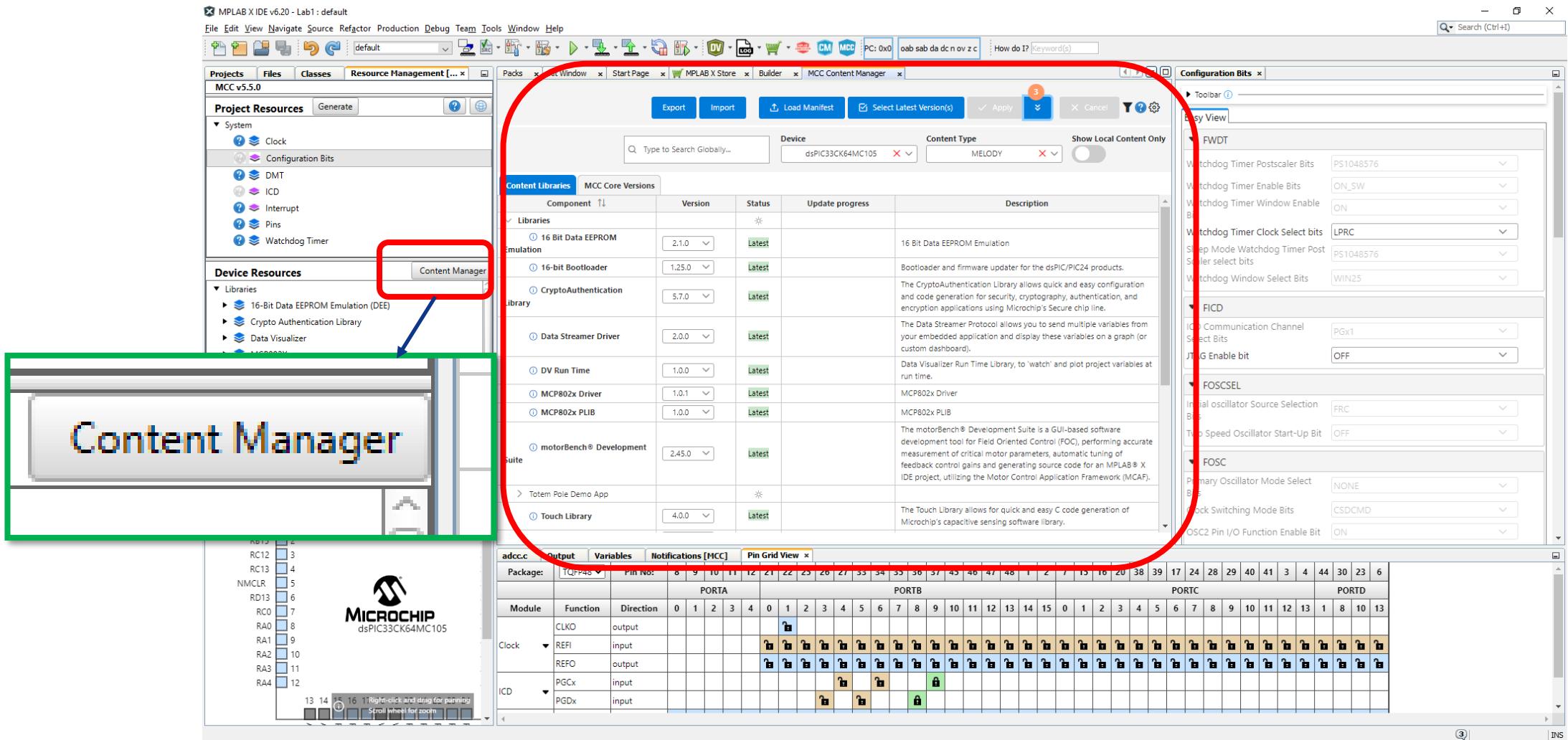
MCC  
程式庫  
設計  
架構圖

腳位功能  
規劃



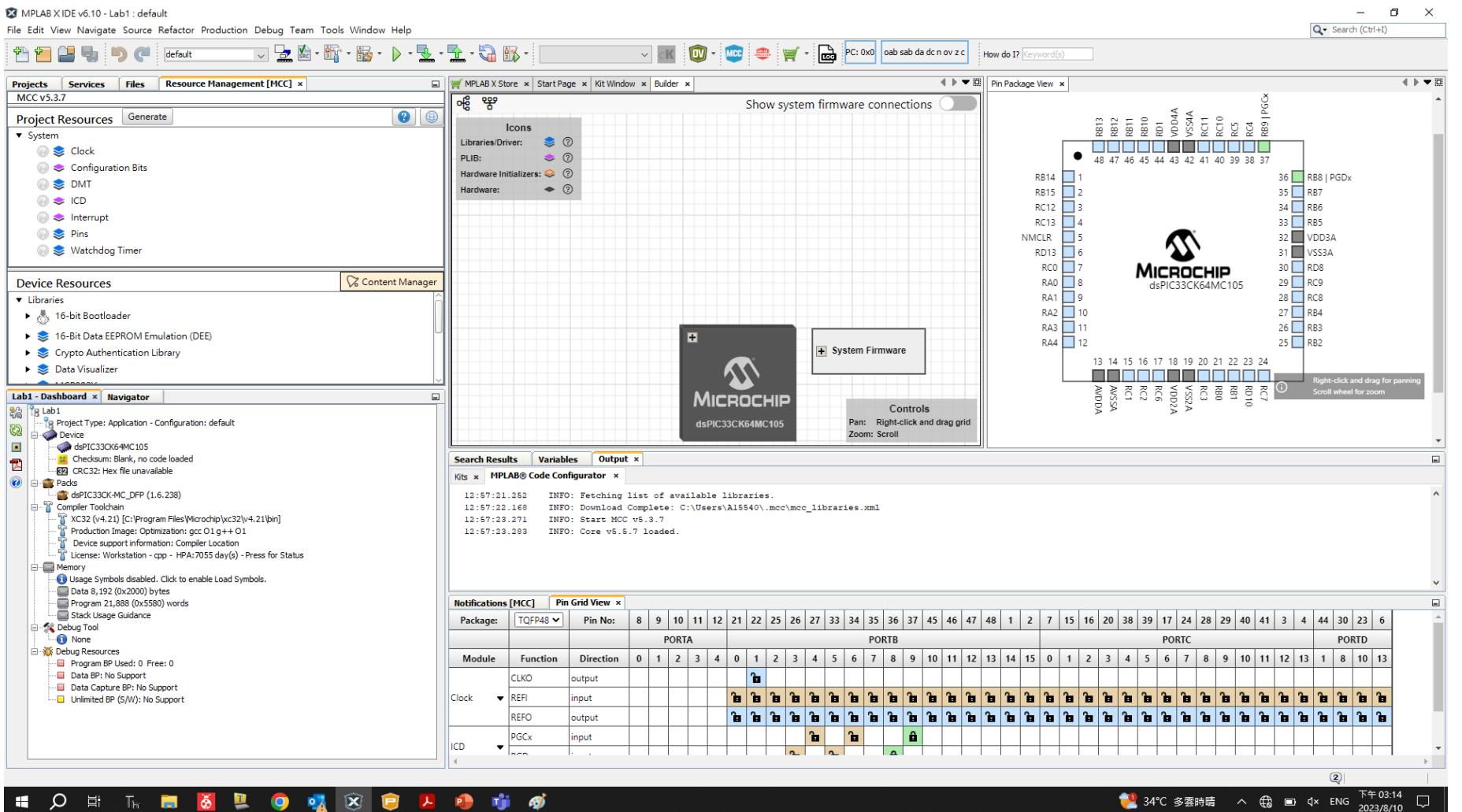
# 11. 下載MCC資料

## Content Manager – 選擇其它程式庫

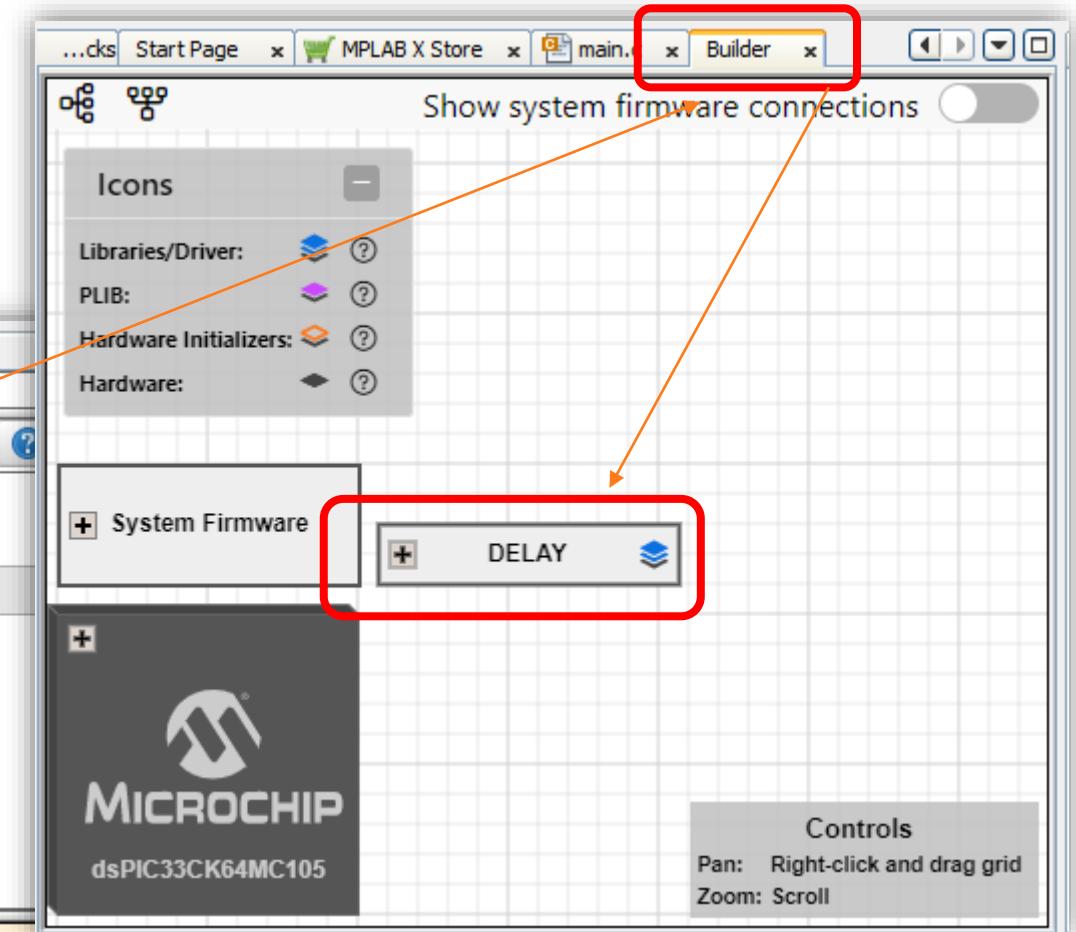
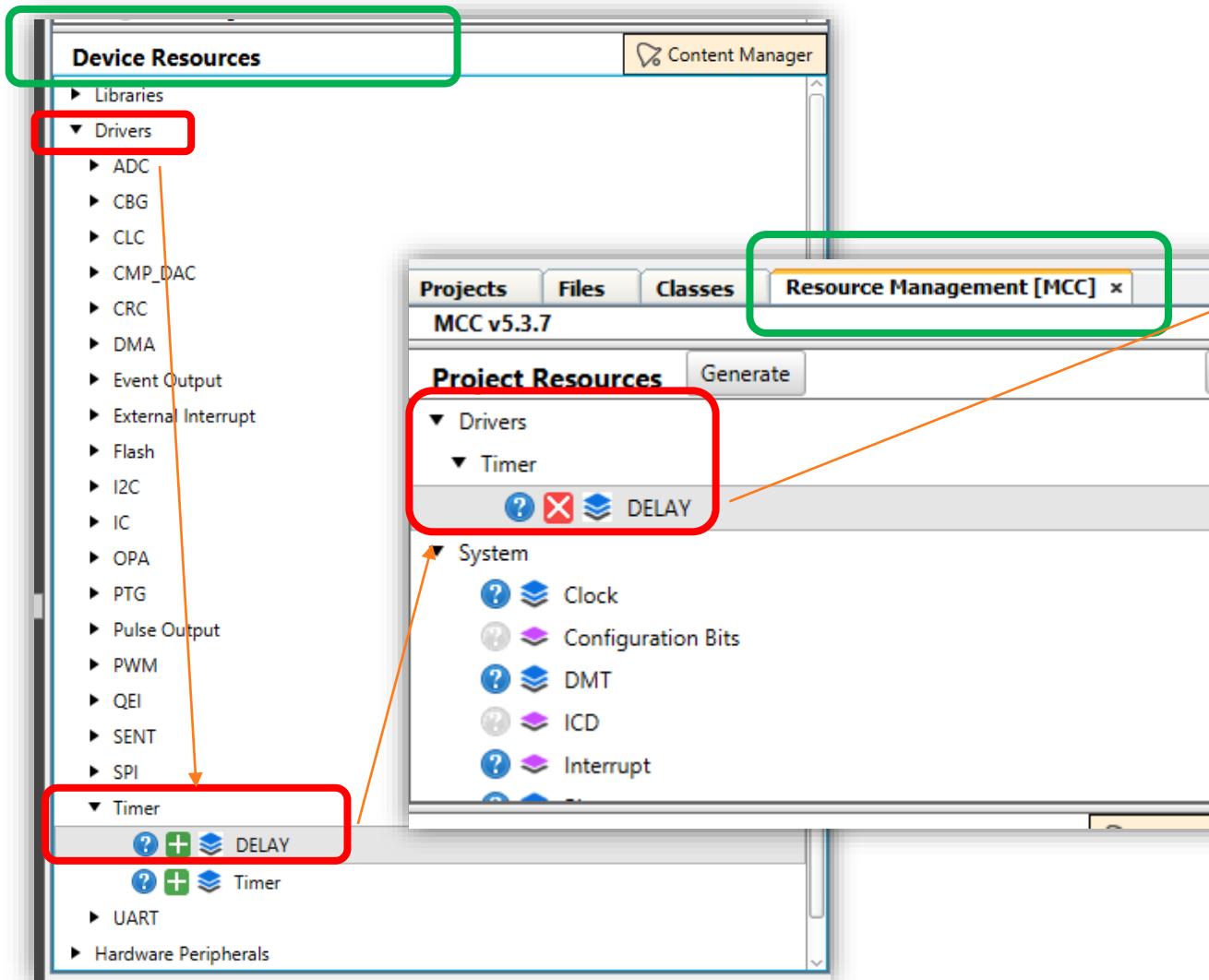


# 12.重新排版

可以用拖曳方式，調成你喜歡的配置

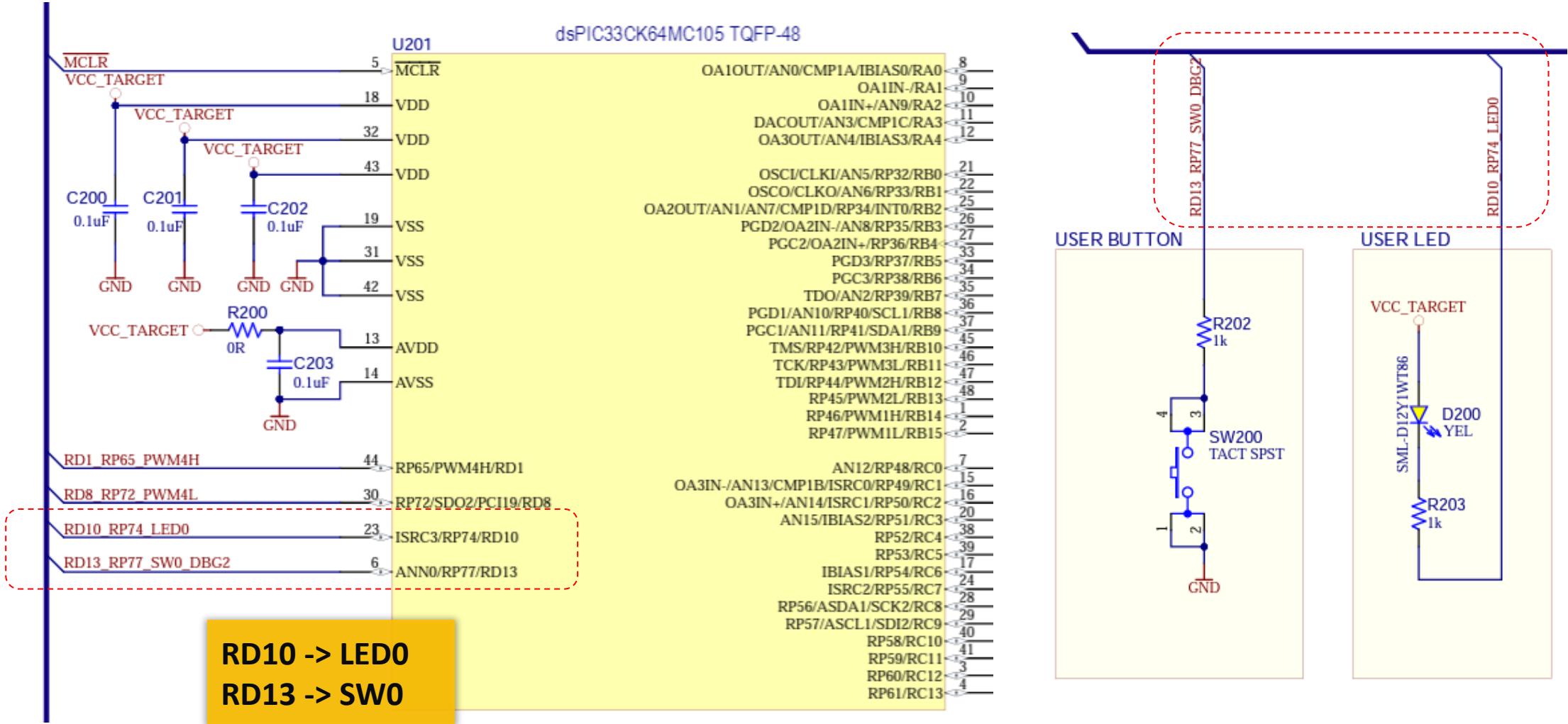


# 13.加入Delay函式 到Drivers->Timer->點選DELAY



# 14. 確認接腳

## dsPIC33CK64MC105\_Curiosity\_Nano\_Schematics.pdf

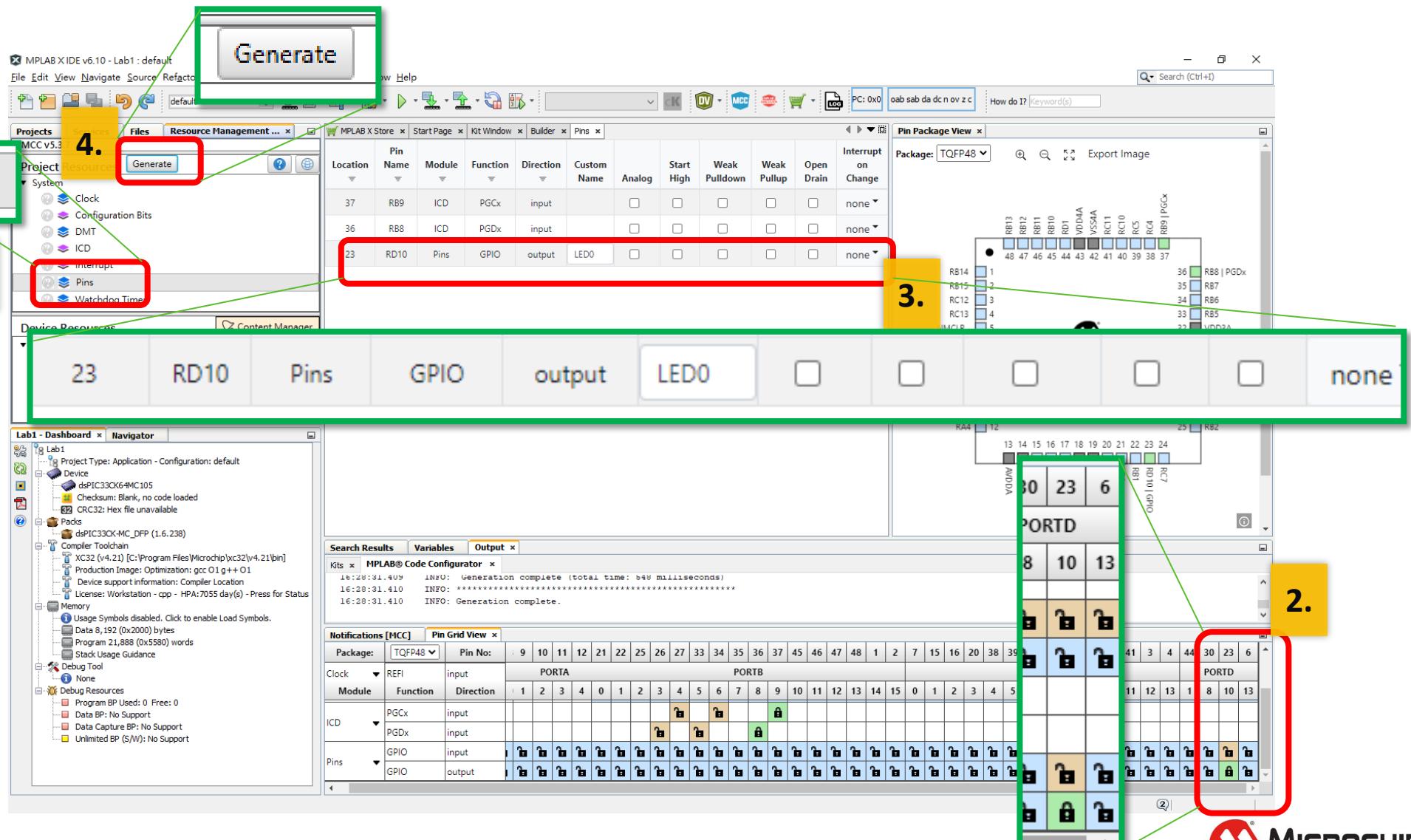


# 15. 設定LEDO

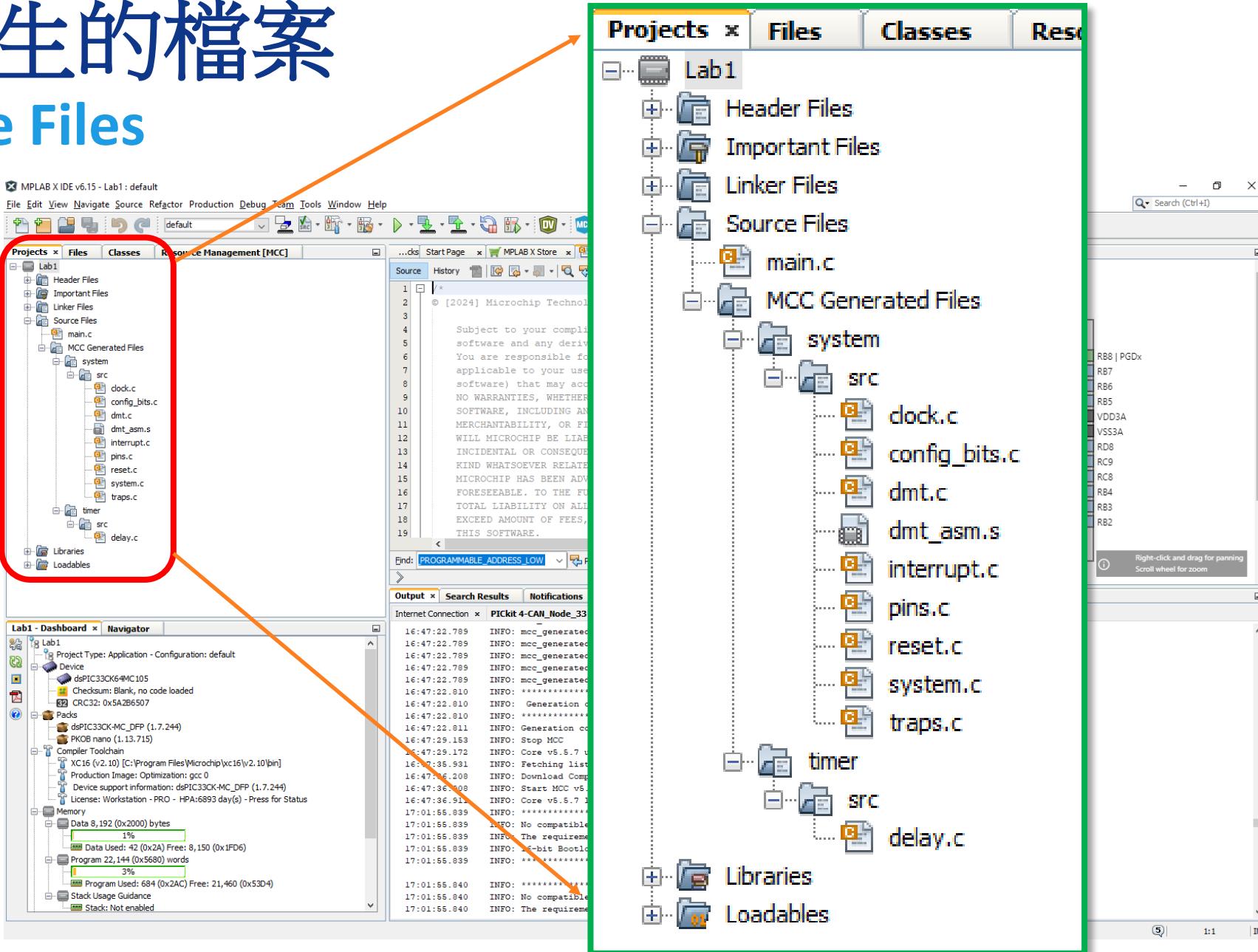
## 1. 點Pins



2. 點RD10  
設輸出  
3. 改名  
LEDO  
4. 產生  
CODE

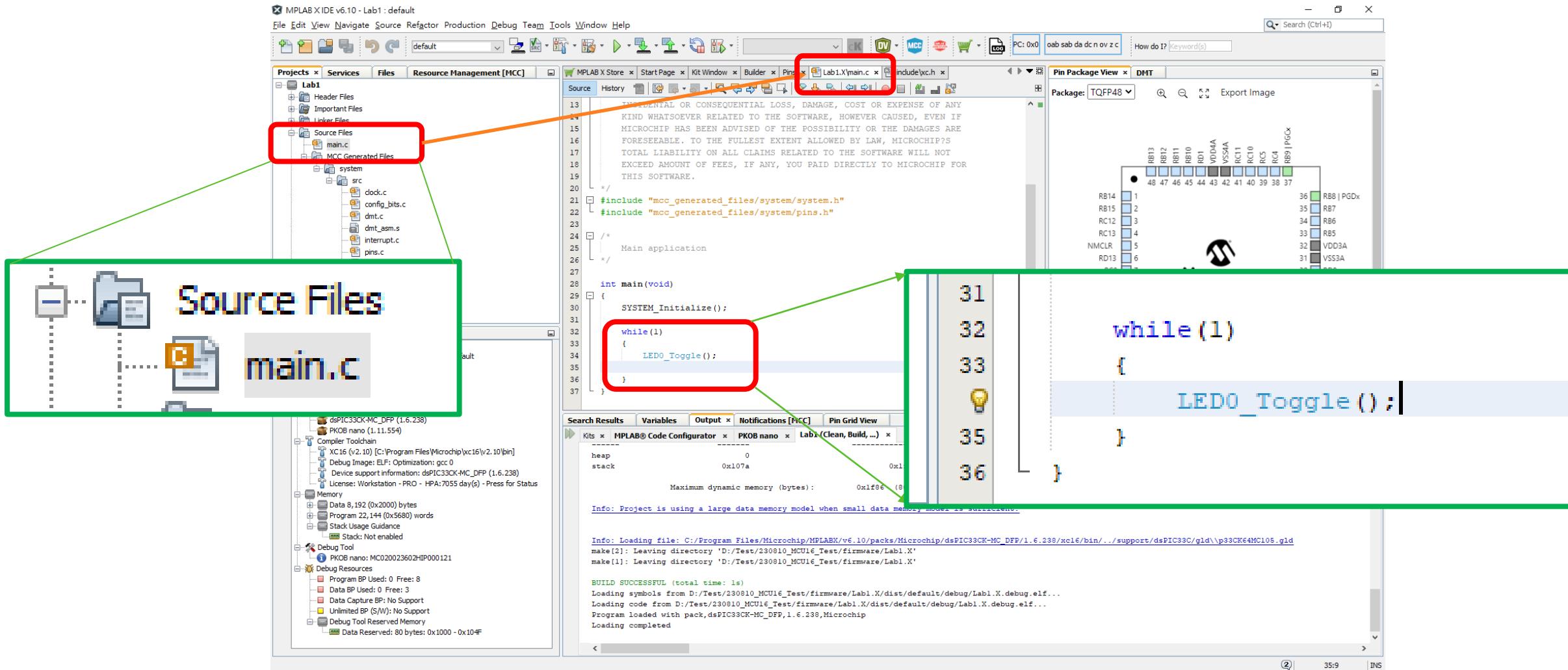


# 16. 產生的檔案 在Source Files



# 17. 寫程式 - LED

開啟main.c → 在while (1) → 加入 LED0\_Toggle(); → 達到LED反向



# 18. Delay函式

The screenshot shows the MPLAB X IDE interface with the following details:

- Title Bar:** MPLAB X IDE v6.10 - Lab1 : default
- Menu Bar:** File Edit View Navigate Source Refactor Production Debug Team Tools Window Help
- Toolbar:** Includes icons for New, Open, Save, Build, Run, and Debug.
- Project Explorer:** Shows the project structure under "Lab1". A red box highlights the "delay.c" file located in the "src\delay.c" folder under the "timer" directory.
- Source Editor:** Displays the code for "delay.c". A large red box highlights the implementation of the `DELAY(milliseconds)` and `DELAY(microseconds)` functions.
- File List:** Shows the open files: main.c, include\c.h, and src\delay.c.

```
32 33 #ifndef FCY
34 #define FCY CLOCK_InstructionFrequencyGet()
35 #endif
36
37 #include "../../system/clock.h"
38 #include <libpic30.h>
39 #include <stdint.h>
40
41 void DELAYMilliseconds(uint16_t milliseconds) {
42     while(milliseconds--) {
43         _delay_ms(1);
44     }
45 }
46
47 void DELAYMicroseconds(uint16_t microseconds) {
48     while( microseconds >= 32 )
49     {
50         _delay_us(32);
51         microseconds -= 32;
52     }
53
54     while( microseconds-- )
55     {
56         _delay_us(1);
57     }
58 }
```

# 19. 寫程式 - Delay

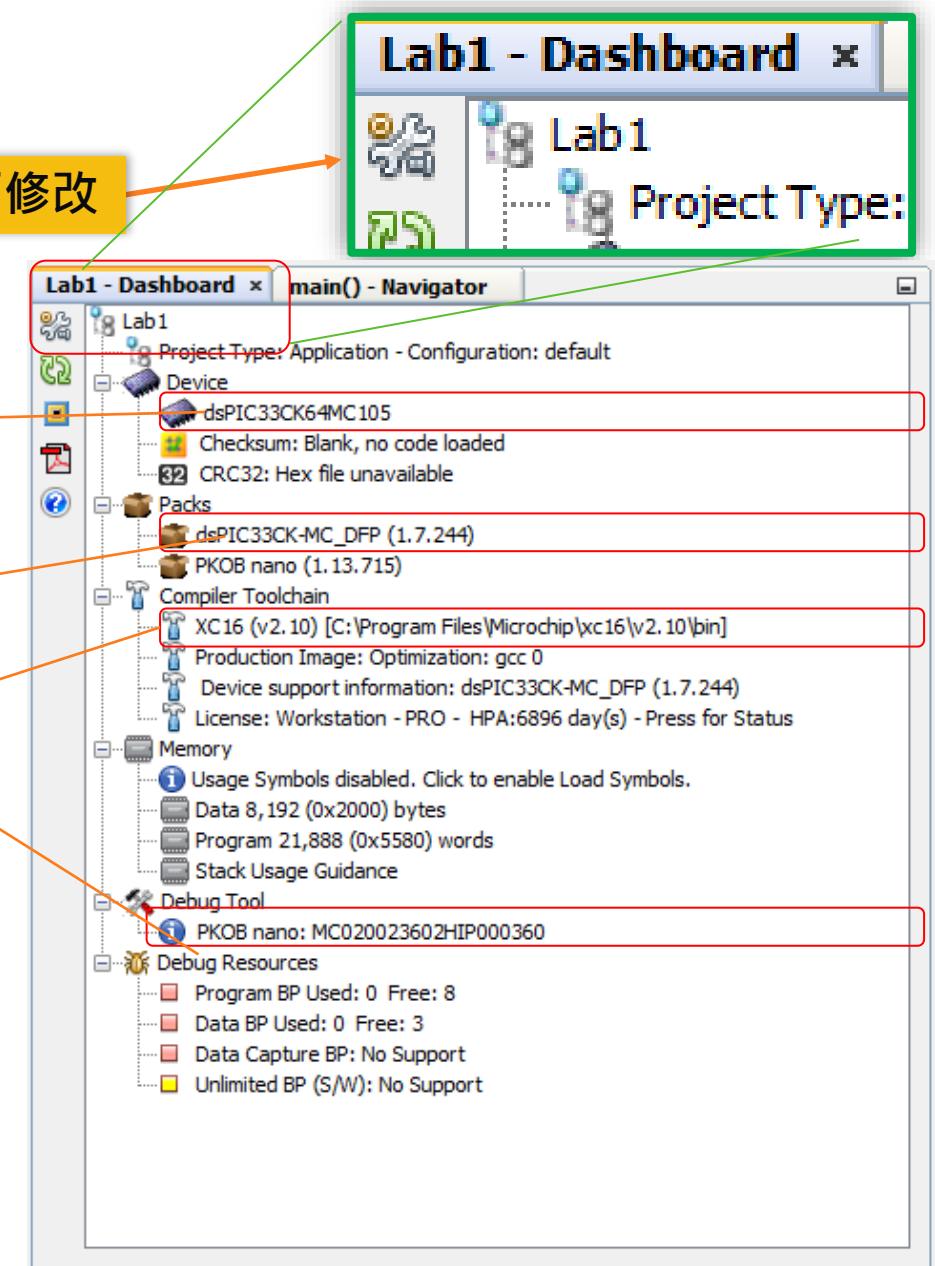
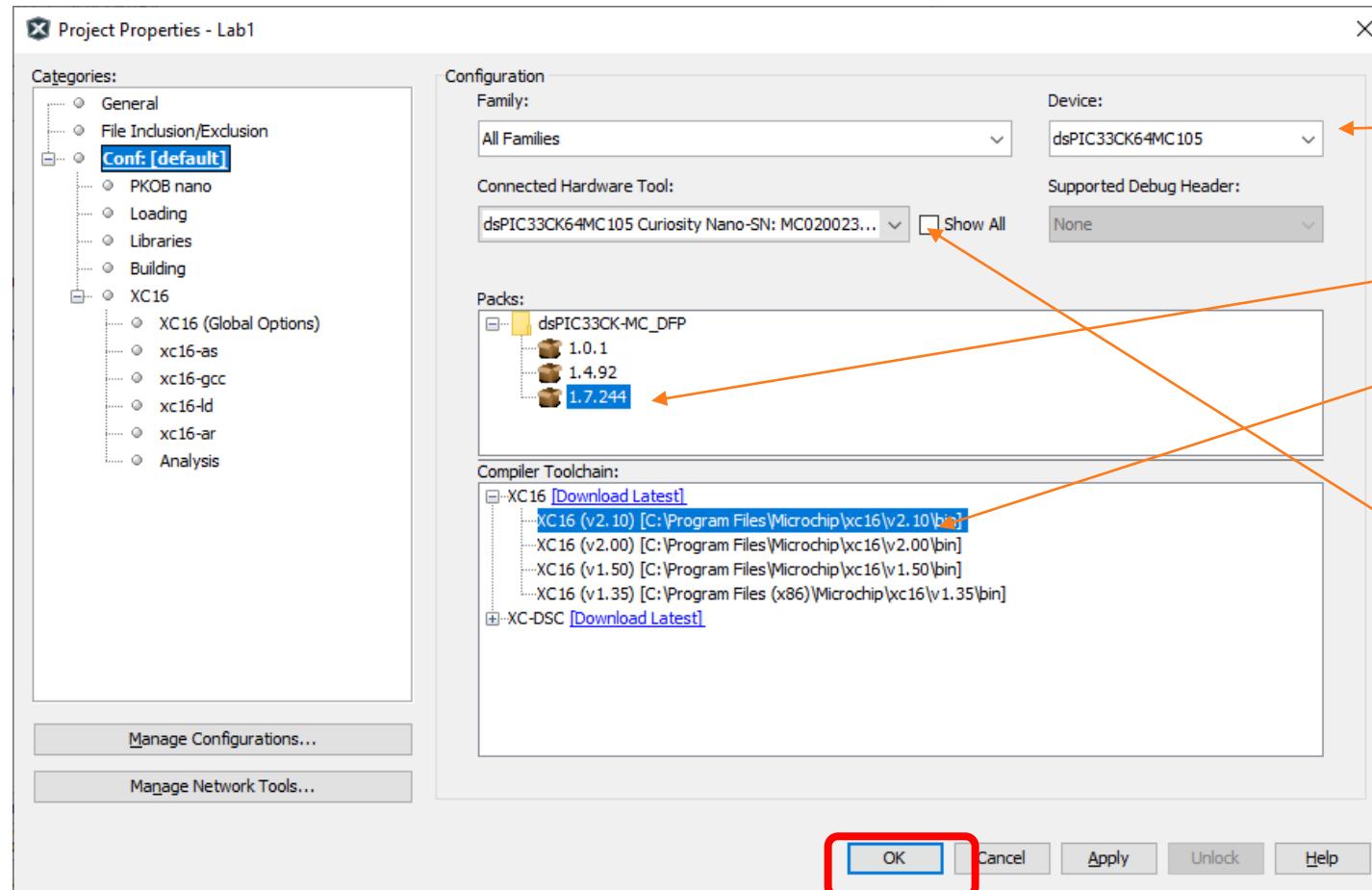
# 加入延時 500ms

- MCC產生的delay.c
    - 含有delay函式
  - 加一行delay減緩LED 反向速度
  - **DELAY(milliseconds(500));**

# 20.確認編譯環境(Dashboard)

Device\DFP\XC16\Debug Tool

1. 點選  後可修改



# 21. 啟動編輯



## Clean and Build Project(Lab1)

The screenshot shows the MPLAB X IDE interface with several toolbars and panels. A green box highlights the toolbar at the top, which includes icons for file operations, project management, and build tools. A red box highlights the toolbar below the main menu, specifically the 'Clean and Build' icons. A green box highlights the central workspace area, showing the 'Source' tab with code snippets and the 'Packs' tab with project details. A red box highlights the bottom right corner of the interface, showing the build log output.

**BUILD SUCCESSFUL (total time: 992ms)**

MPLAB X IDE v6.20 - Lab1 : default

File Edit View Navigate Source Refactor Production Debug Team Tools Window Help

Projects x Files Classes Resource Management ...

Lab1

Source

#include "mcc\_generated\_files/system/system.h"  
#include "mcc\_generated\_files/system/pins.h"

Packs

Source

Builder

MCC Content Manager

Configuration Bits

DELAY

Pins

LED0

LED1

LED2

LED3

LED4

LED5

LED6

LED7

LED8

LED9

LED10

LED11

LED12

LED13

LED14

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LED1173

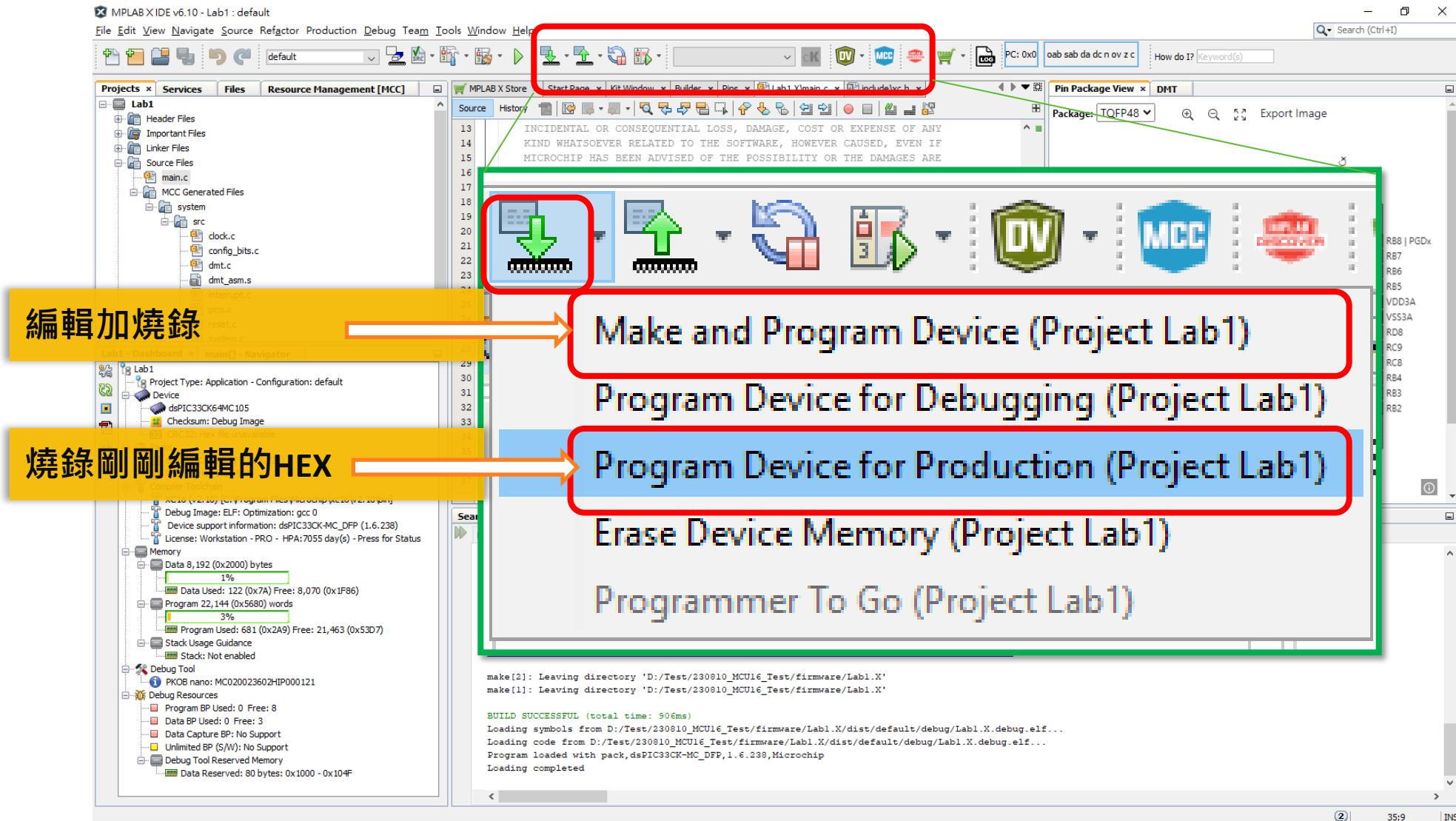
LED1174

LED1175

LED1176

LED117

# 22. 啟動燒錄



編輯加燒錄

Make and Program Device (Project Lab1)

Program Device for Debugging (Project Lab1)

燒錄剛剛編輯的HEX

Program Device for Production (Project Lab1)

Erase Device Memory (Project Lab1)

Programmer To Go (Project Lab1)

```
make[2]: Leaving directory 'D:/Test/230810_MCU16_Test/firmware/Lab1.X'
make[1]: Leaving directory 'D:/Test/230810_MCU16_Test/firmware/Lab1.X'

BUILD SUCCESSFUL (total time: 906ms)
Loading symbols from D:/Test/230810_MCU16_Test/firmware/Lab1.X/dist/default/debug/Lab1.X.debug.elf...
Loading code from D:/Test/230810_MCU16_Test/firmware/Lab1.X/dist/default/debug/Lab1.X.debug.elf...
Program loaded with pack,dsPIC33CK-MC_DFP,1.6.238,Microchip
Loading completed
```

# 23. 燒錄完成

MPLAB X IDE v6.15 - Lab1 : default

File Edit View Navigate Source Refactor Production Debug Team Tools Window Help

Projects x Files Classes Resource Management [MCC]

Lab1 Header Files Important Files Linker Files Source Files Libraries Loadables

Kit Window x Pack

MCU Boards dsPIC33CK64MC105

Currently loaded versions:  
Application version.....1.30.35 (0x01.0x1e.0x23)  
Tool pack version .....1.13.715  
Target voltage detected  
Target device dsPIC33CK64MC105 found.  
Device Revision Id = 0x1  
Device Id = 0x99120000  
UDID1 = 0elle2  
UDID2 = 004650  
UDID3 = 0d0000  
UDID4 = 000000  
UDID5 = 0000e5

Calculating memory ranges for operation...

Erasing...

The following memory area(s) will be programmed:  
program memory: start address = 0x0, end address = 0x7ff  
configuration memory

Programming complete

燒錄器抓到的IC資訊

Lab1 - Dashboard x main() - Navigator Pin Package View

Project Type: Application - Configuration: default

Device dsPIC33CK64MC105  
Checksum: 0x13CB  
CRC32: 0x5A2B6507

Packs dsPIC33CK-MC\_DFP (1.7.244)  
PKOB nano (1.13.715)

Compiler Toolchain XC16 (v2.10) [C:\Program Files\Microchip\xc16\v2.10\bin]  
Production Image: Optimization: gcc 0  
Device support information: dsPIC33CK-MC\_DFP (1.7.244)  
License: Workstation - PRO - HPA:6895 day(s) - Press for Status

Memory Data 8,192 (0x2000) bytes  
Data Used: 42 (0x2A) Free: 8,150 (0x1FD6)  
Program 22,144 (0x5680) words  
Program Used: 684 (0x2AC) Free: 21,460 (0x53D4)

Stack Usage Guidance Stack: Not enabled

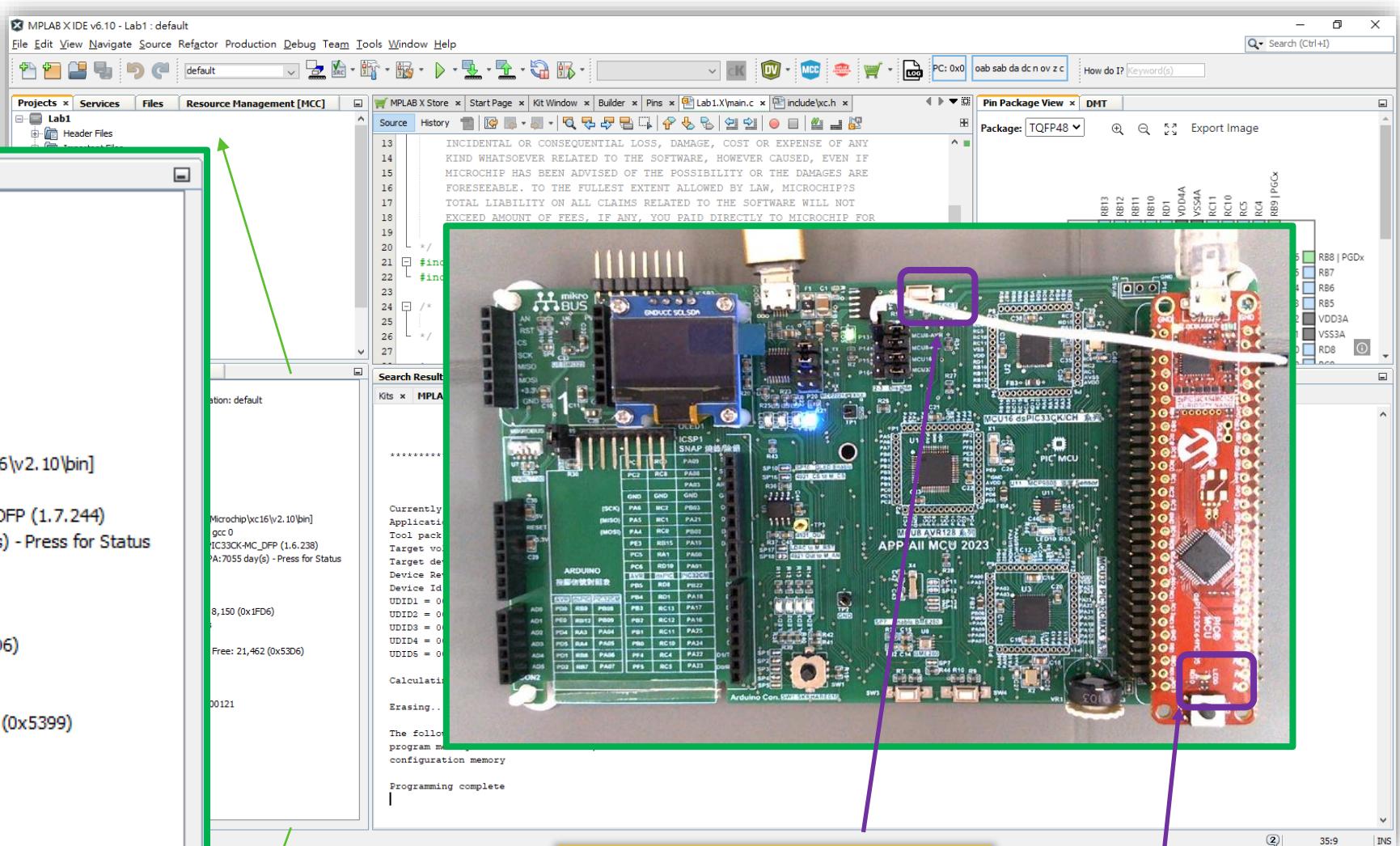
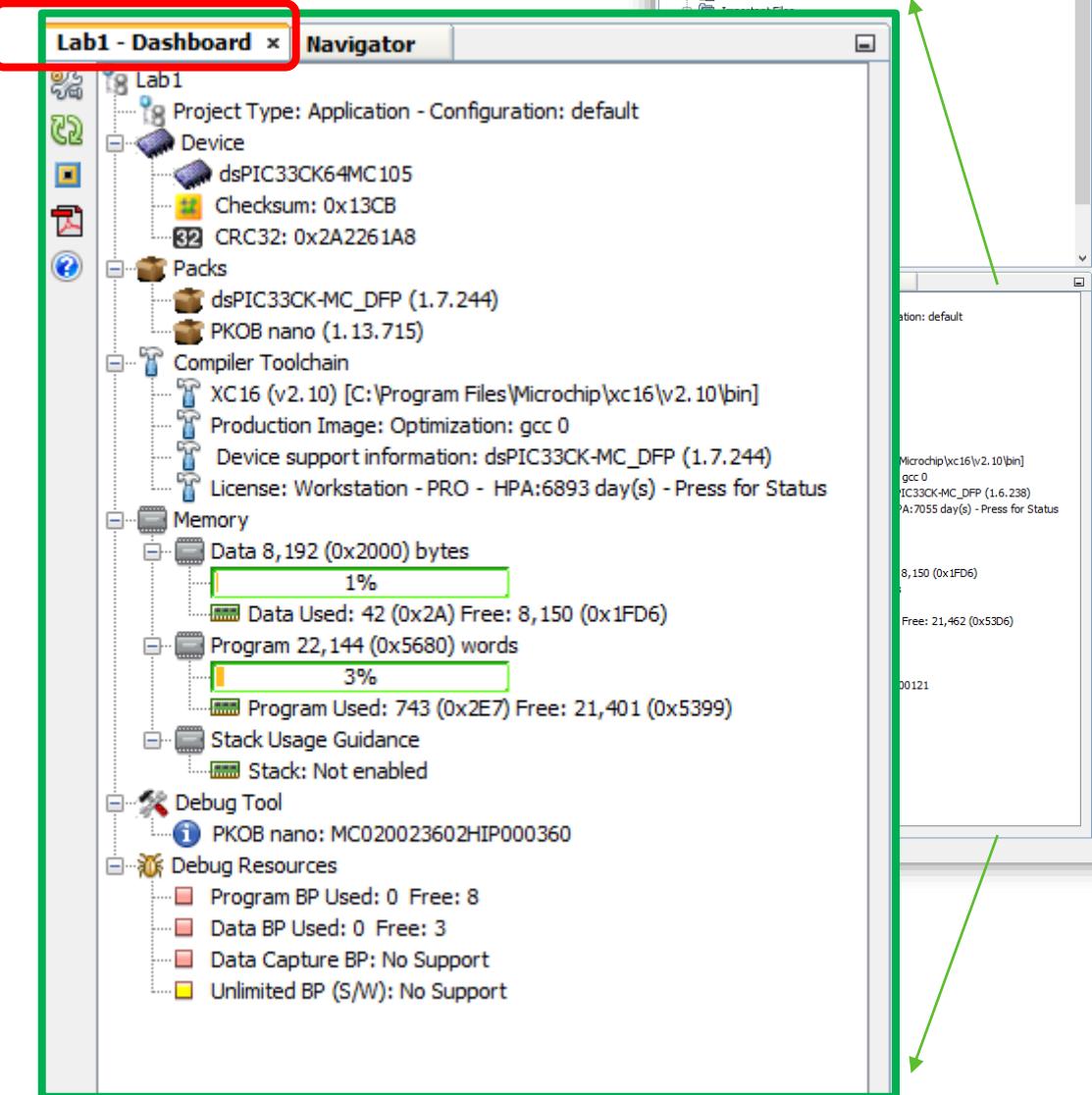
Debug Tool PKOB nano: MC020023602HIP000360

Debug Resources Program BP Used: 0 Free: 8  
Data BP Used: 0 Free: 3  
Data Capture BP: No Support  
Unlimited RP (S/W): No Support

Kits x PKOB nano x MPLAB® Code Configurator x Lab1 (Build, Load, ...) x PKOB nano-Lab1 x

# 24.結果

## LED0閃爍

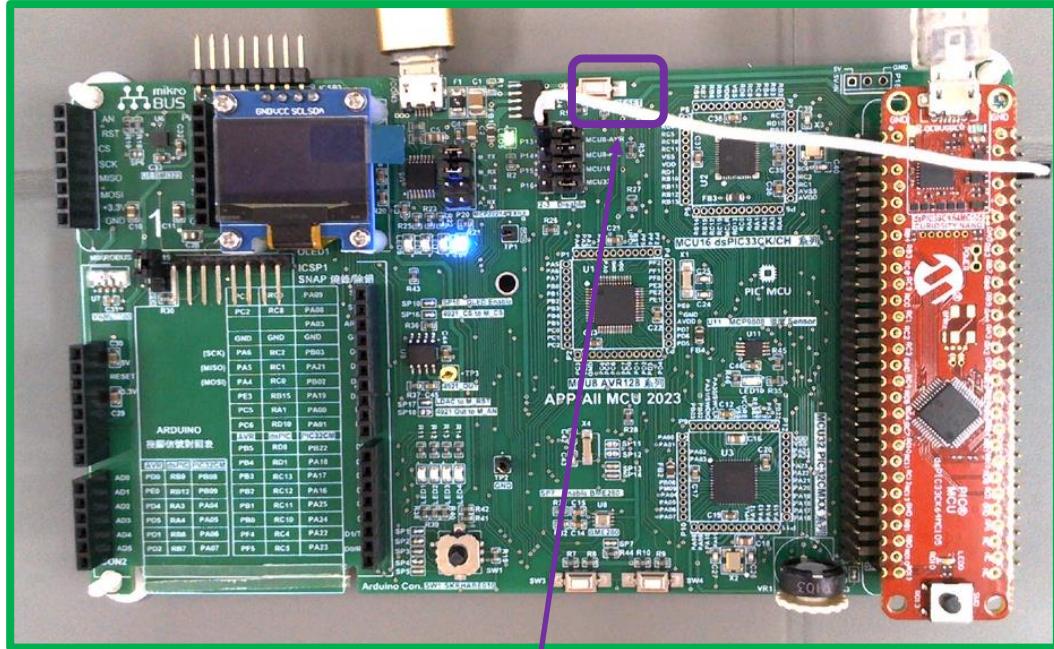


如果有接白色RESET線  
要按一下RESET鈕(SW2)

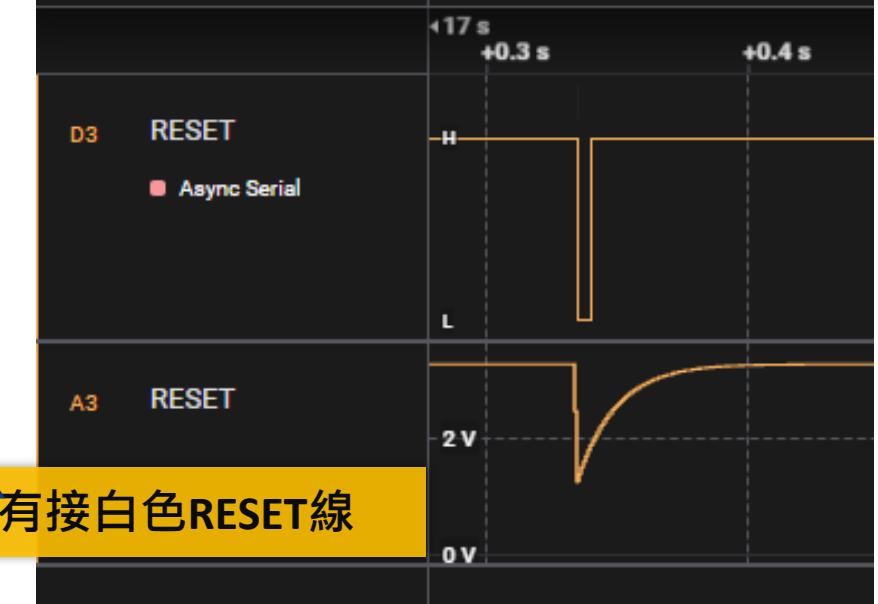
LED0閃爍

# 25. RESET

要再按一次的原因



因紅板內建燒錄器  
RESET Pin驅動能力不足驅動綠板  
燒完後，需要按一下RESET鈕(SW2)  
讓MCU Reset 完全



有接白色RESET線

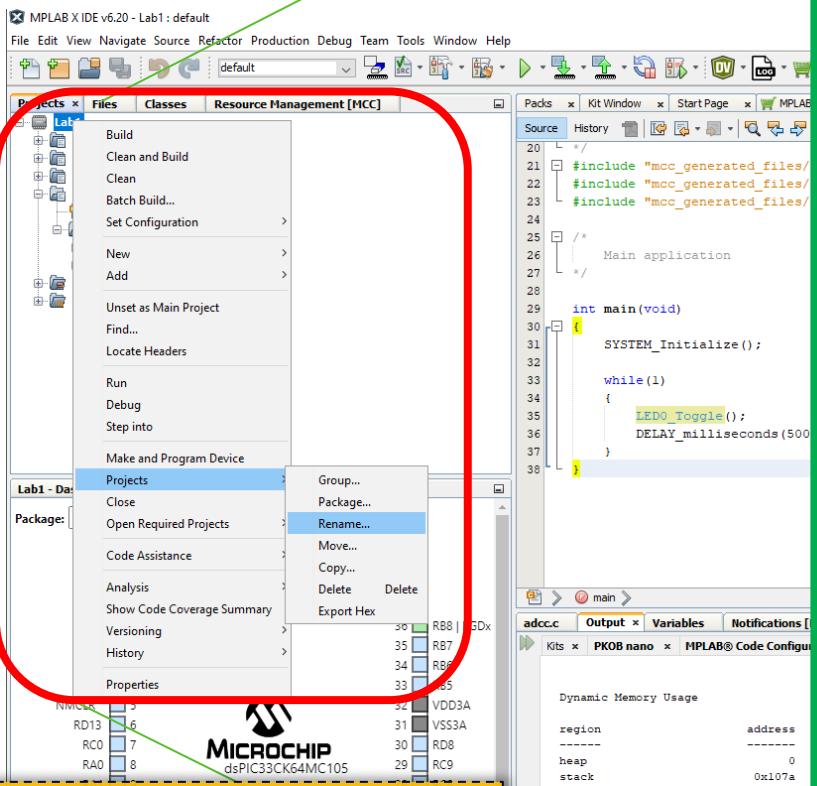
沒有接白色RESET線

# 26. 成果

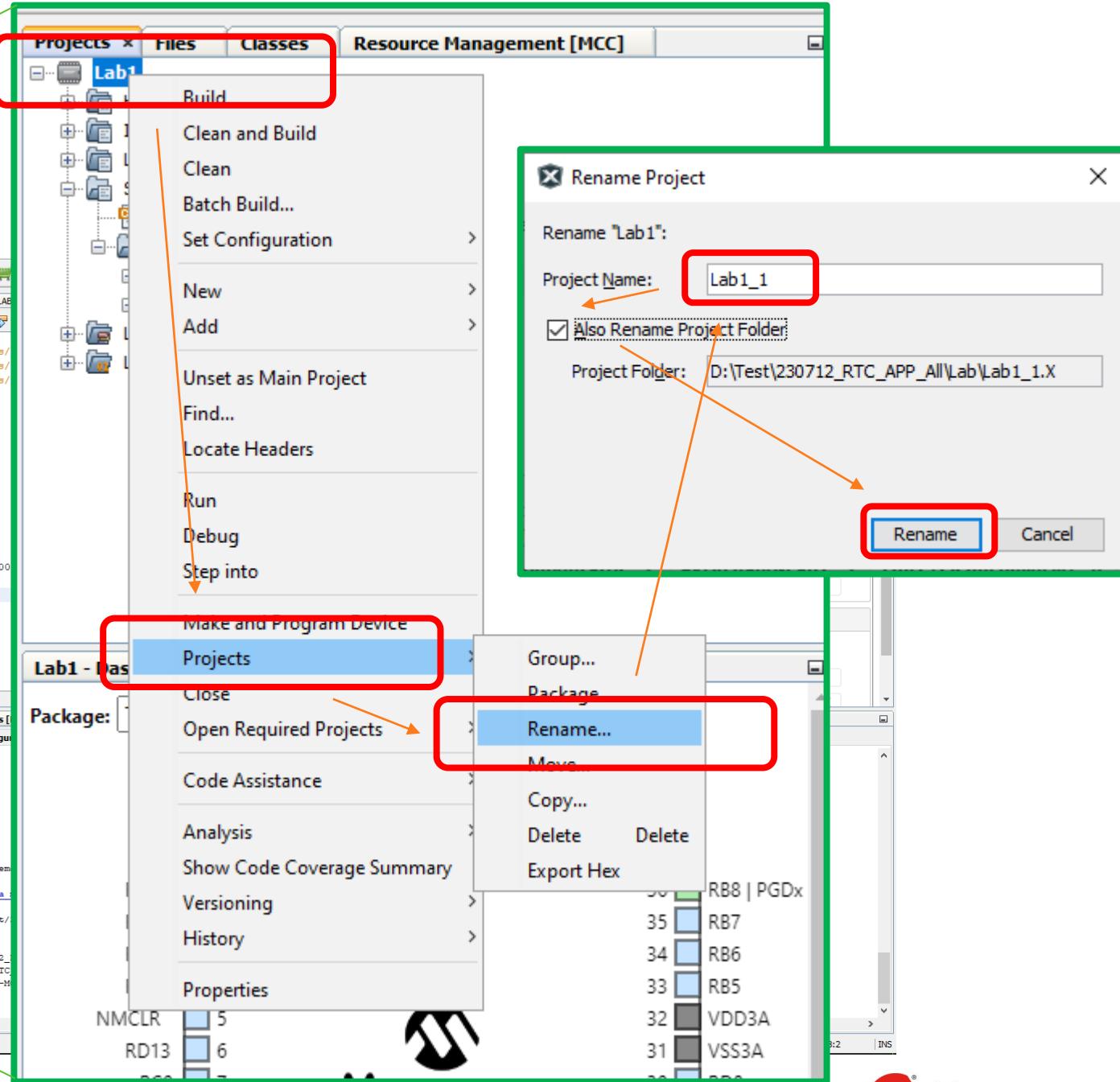
- 以上步驟完成，看到LED閃爍代表
  - MPLAB X IDE → 安裝OK
  - MCC → 安裝OK
  - XC16 → 安裝OK
- EVB(紅板) → 燒錄功能 OK
- dsPIC33 → 型號正確 OK
- 可以開始進一步練習

# 專案重新命名

Lab1\_1



1. 滑鼠移到專案名(Lab1)上
2. 選Projects
3. 選Rename
4. 改為Lab1\_1
5. 按Rename



# 測試input

## Lab1\_1 透過SWO控制LED0

- 1) 延續Lab1
- 2) 開啟MCC
- 3) 設定輸入(參考步驟14,15)
  - a) Project Resource→點Pins
  - b) 在Pins /input處→點RD13
  - c) IO\_RD13改名成SW0
  - d) 並在同一行，勾選Weak Pullup
  - e) 在產生一次Code
- 4) 改Code (如右圖) (參考步驟17)  
到main.c 的while(1){...}
- 5) 燒入(參考步驟22)
- 6) 結果: 按SW0 -> LED0 亮

```
29 int main(void)
30 {  
31     SYSTEM_Initialize();  
32  
33     while(1)  
34     {  
35         // LED0_Toggle();  
36         // DELAY_milliseconds(500);  
37  
38         if(SWO_GetValue())  
39         { LED0_SetHigh(); }  
40         else  
41         { LED0_SetLow(); }  
42     }  
43 }  
44 }
```

# 實驗二

---

透過UART(非同步串列通訊)顯示信息

# 入門實驗

## 實驗二：透過UART(非同步串列通訊)顯示信息

- 本實驗目的：

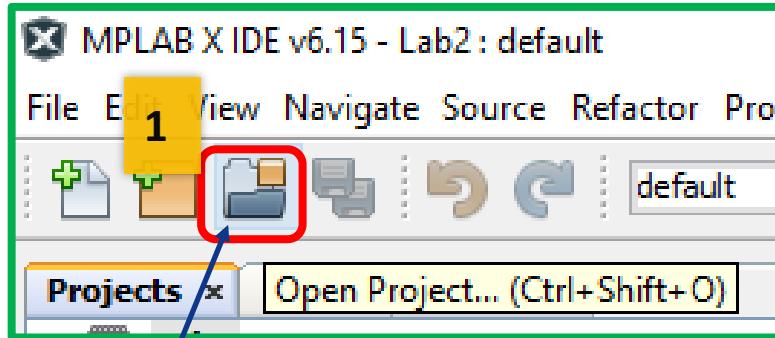
- 確認底板正常
  - 訊號可以通過 115200-8-N-1 格式傳到底板
  - MCP2221動作正常
  - 方便後續輸出除錯訊息

- 結果呈現：

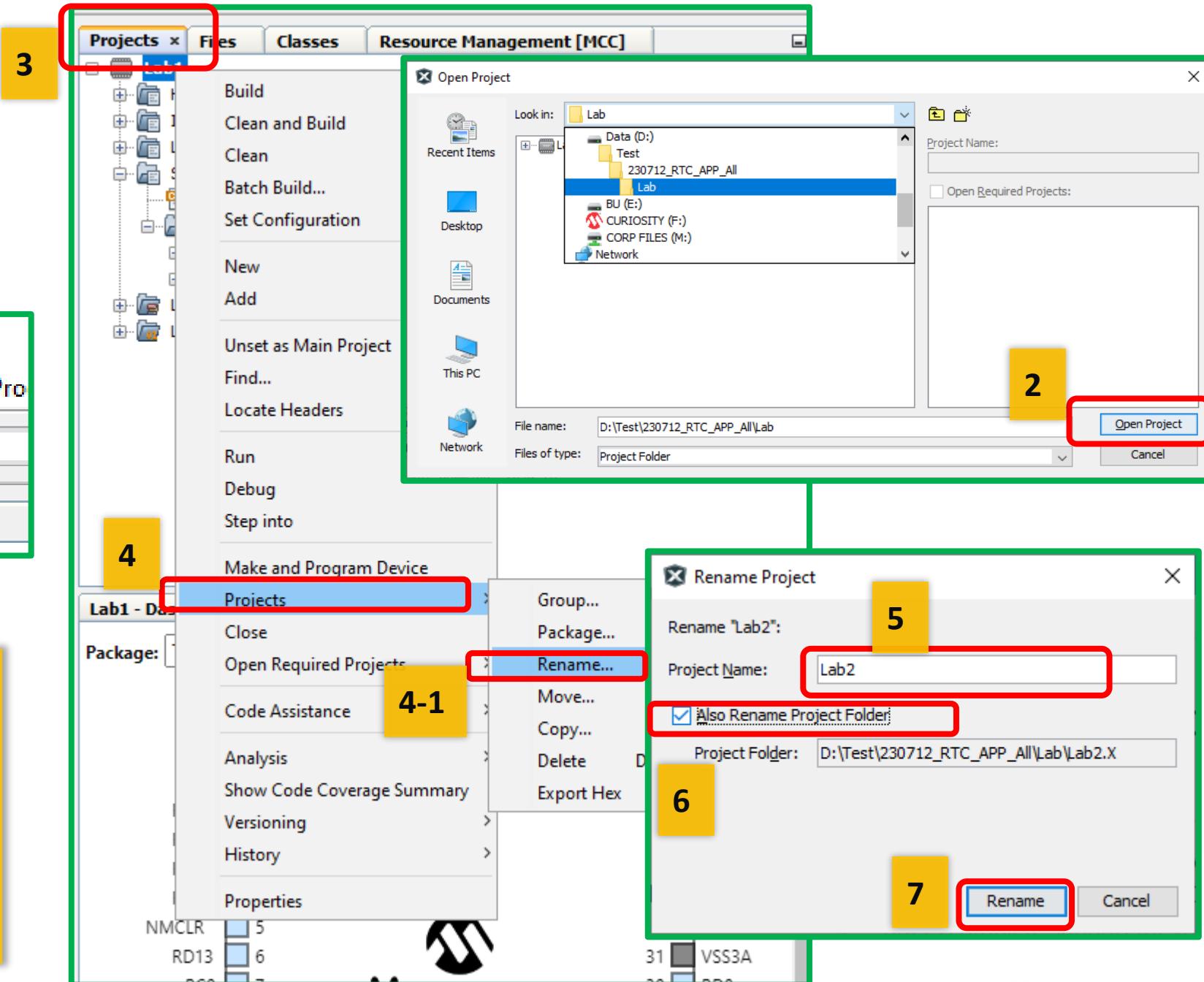
- 在電腦終端機上顯示字串
  - dsPIC33: Hi

# 1. 建立Lab2

## 將Lab 1改名成Lab2

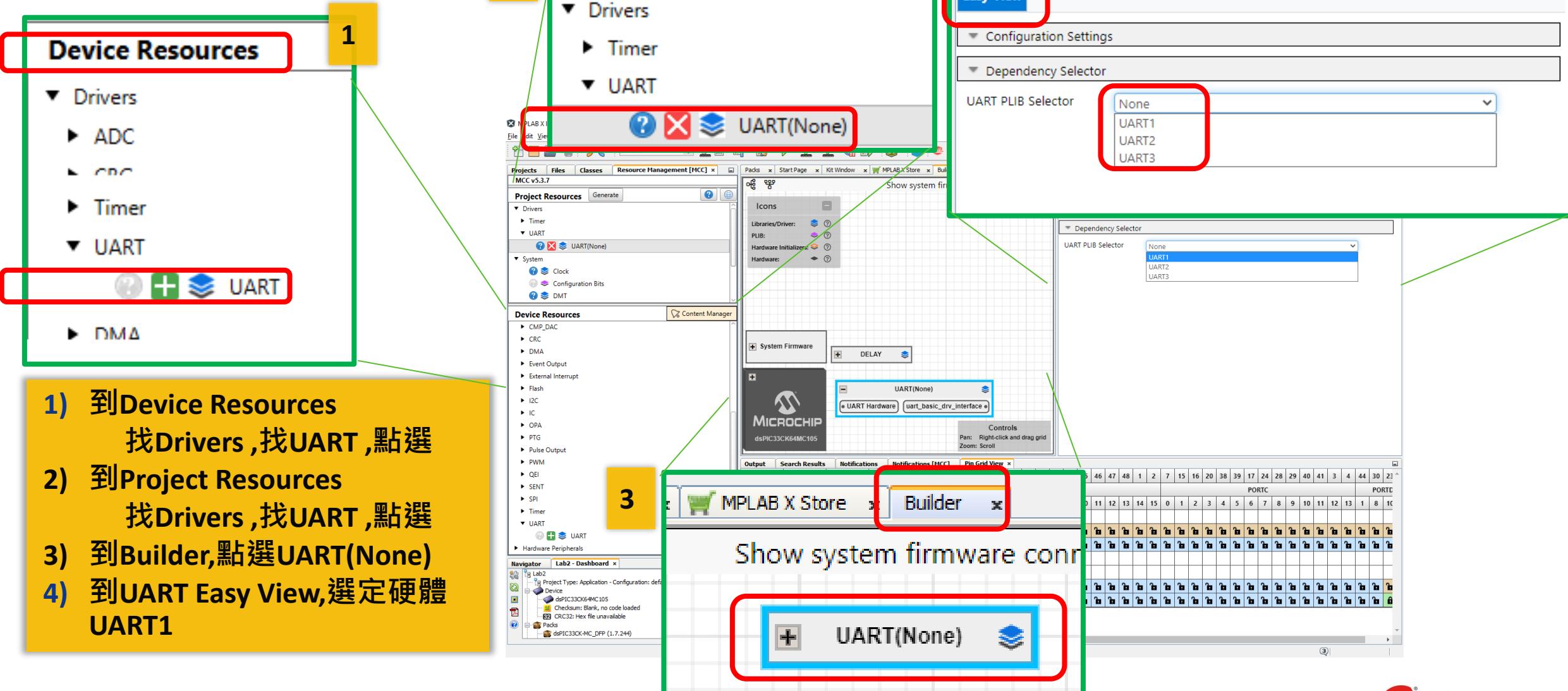


- 1) 點選 → 開啟專案
- 2) 到對映路徑中選取 → Lab1
- 3) 到Projects 在Lab1上  
滑鼠點右鍵
- 4) 找到Projects → Rename
- 5) 修改成Lab2
- 6) 勾選順便改資料夾名
- 7) 按 Rename 完成名稱修改



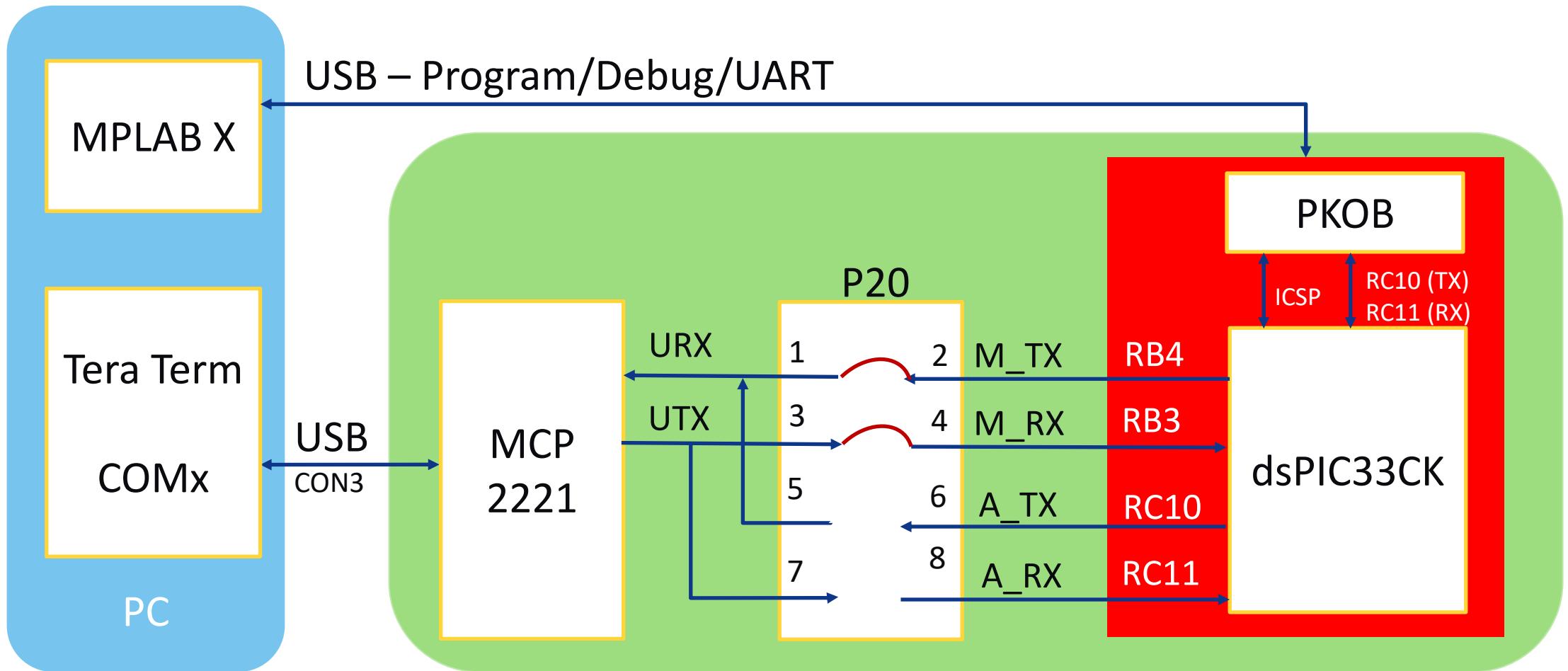
## 2. 在MCC中選取UART

選UART1



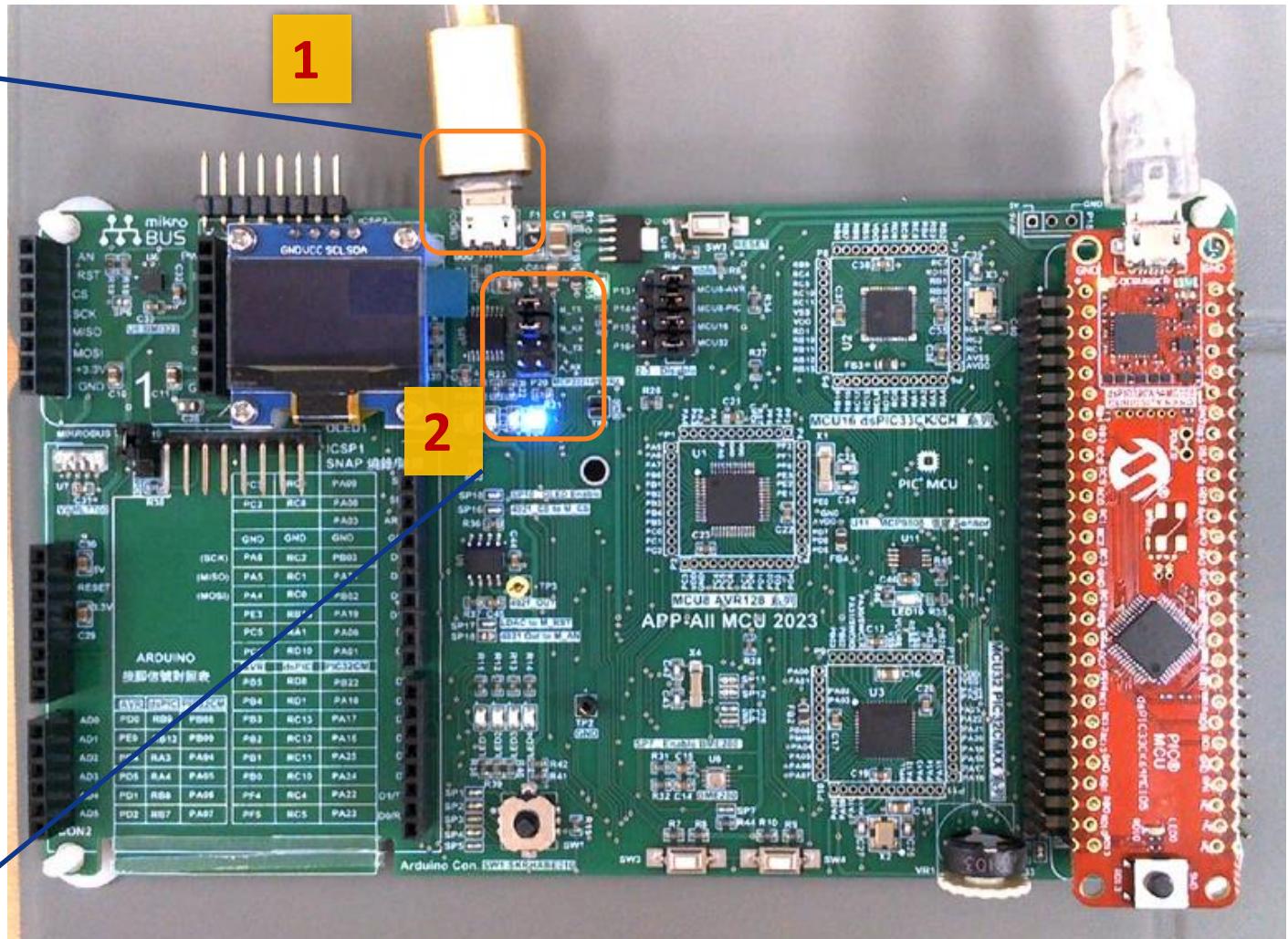
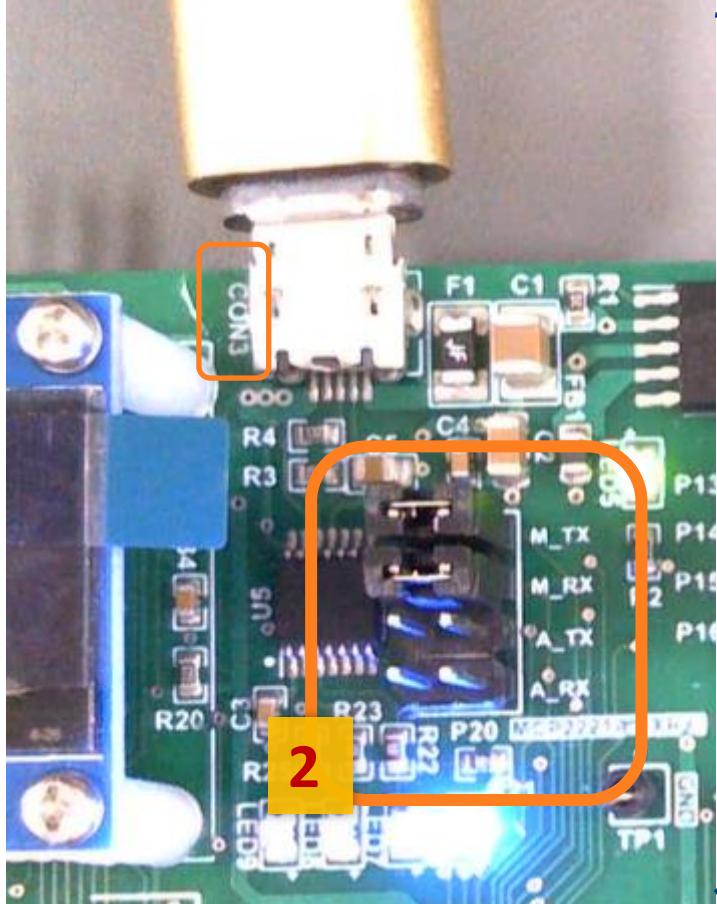
### 3. 架構圖

#### UART 相關連線



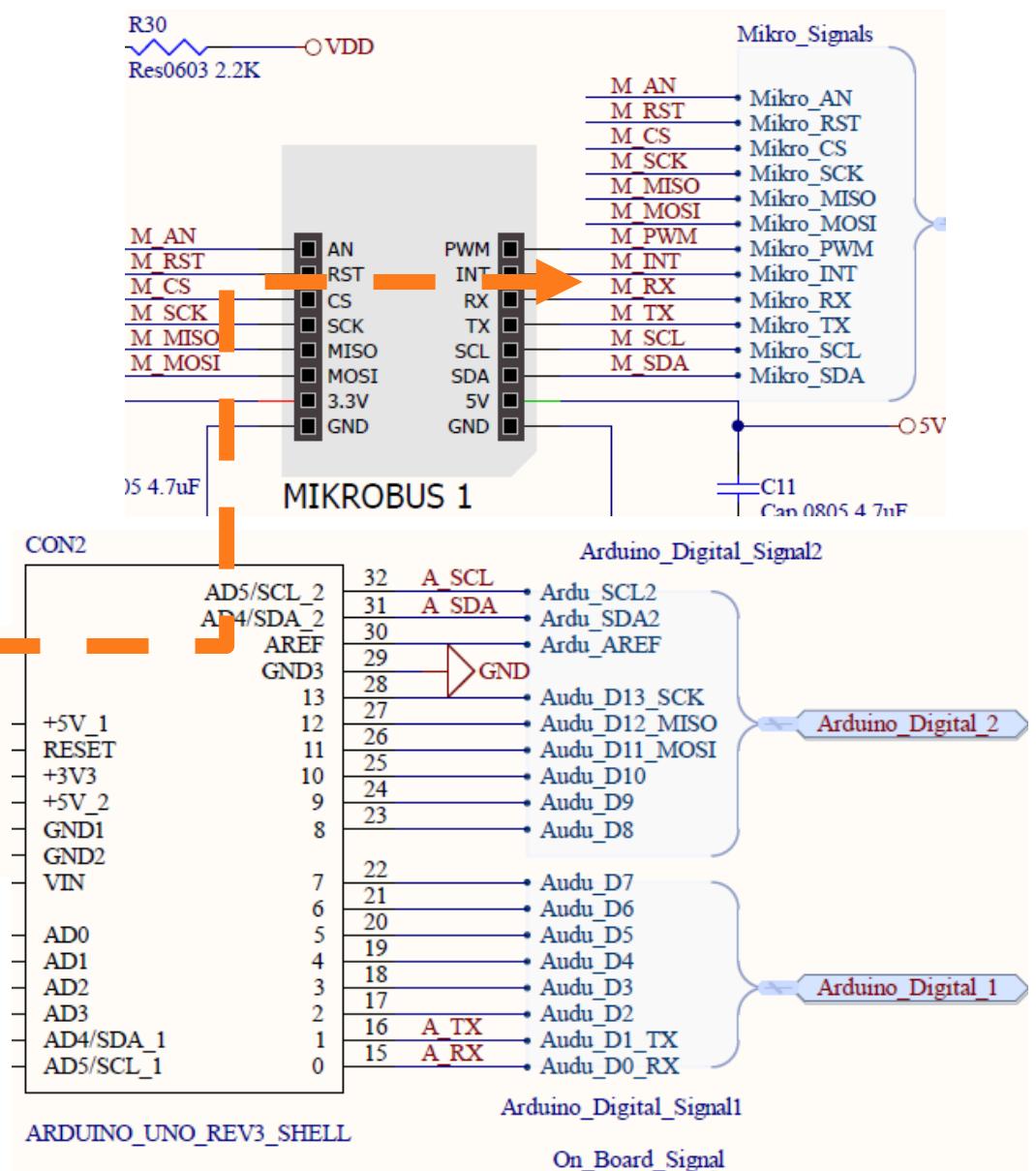
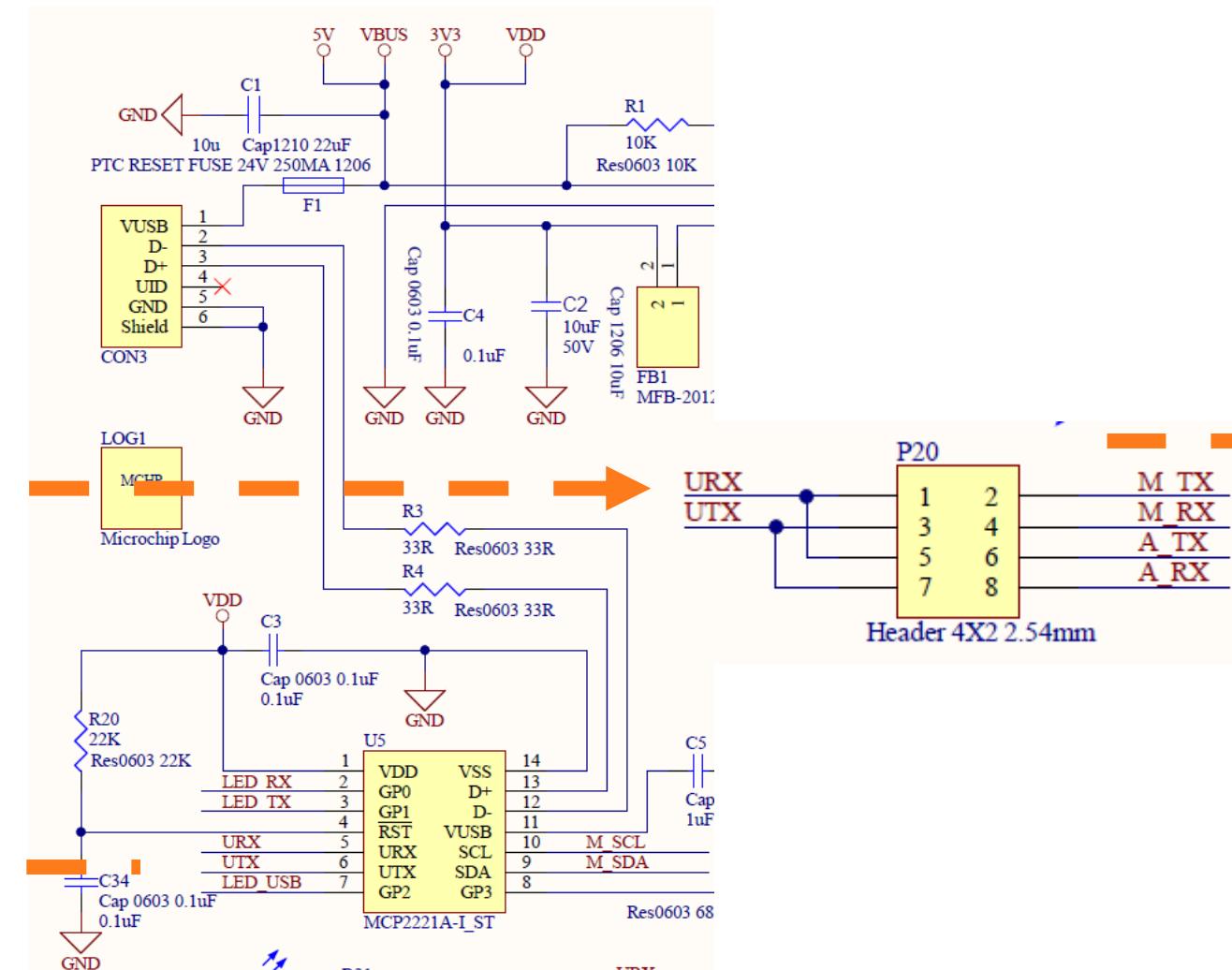
## 3-2. UART 相關接線

### P20-Jump 位置



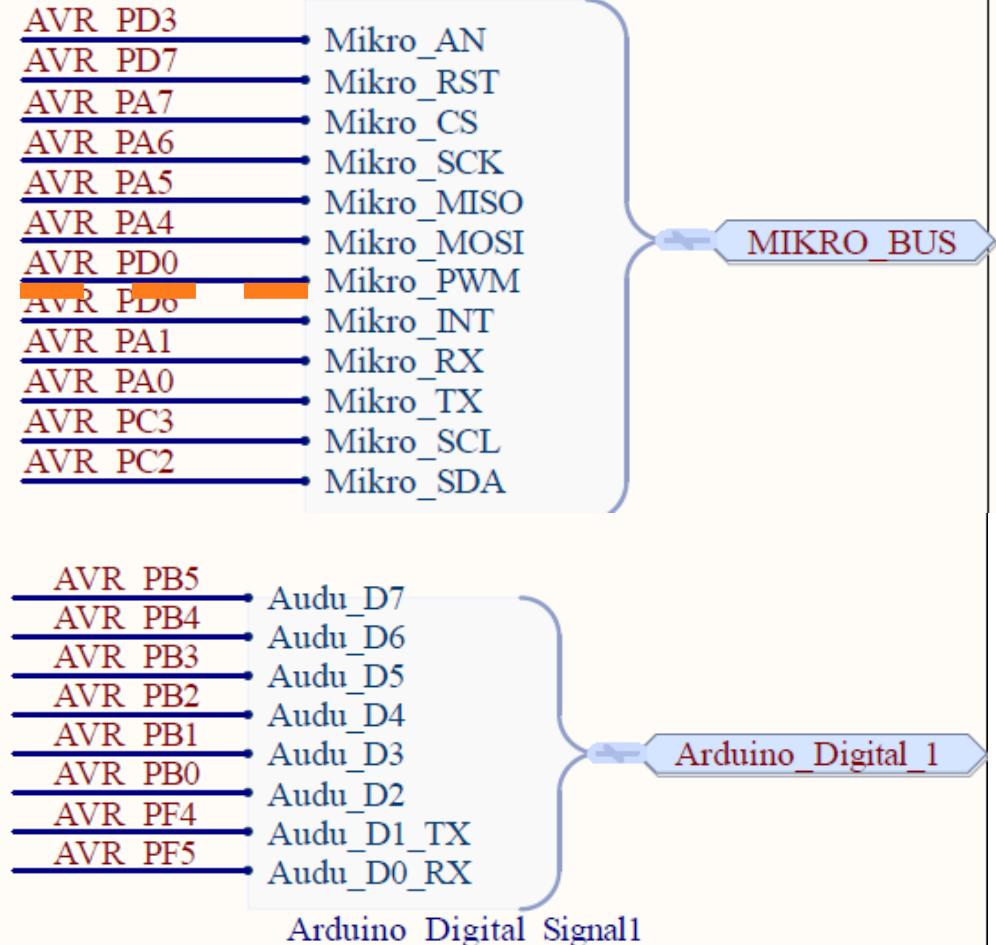
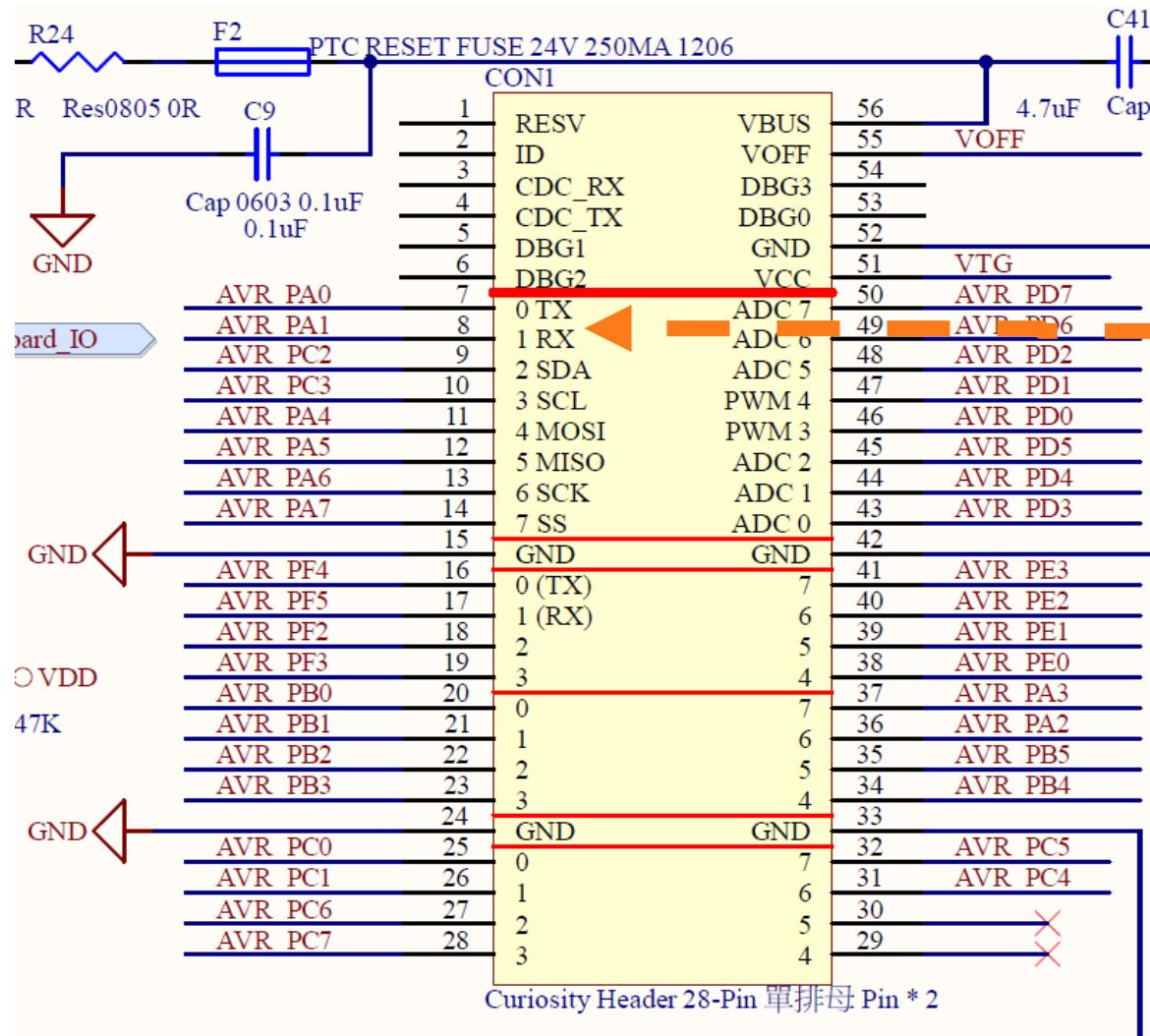
# 3-1. UART 電路圖

## 大板相關電路



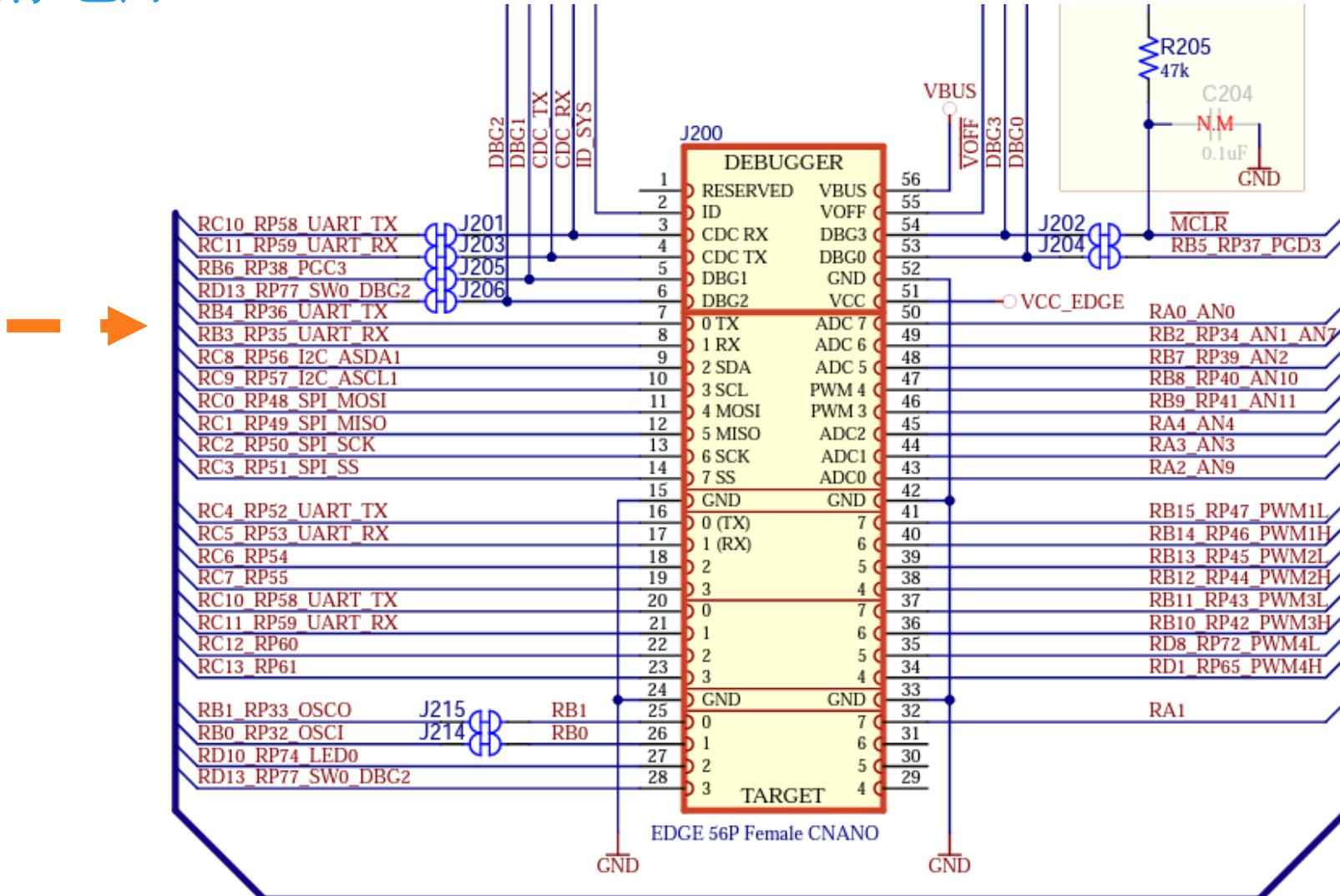
# 3-2. UART電路圖

## 大板相關電路



# 3-3. UART電路圖

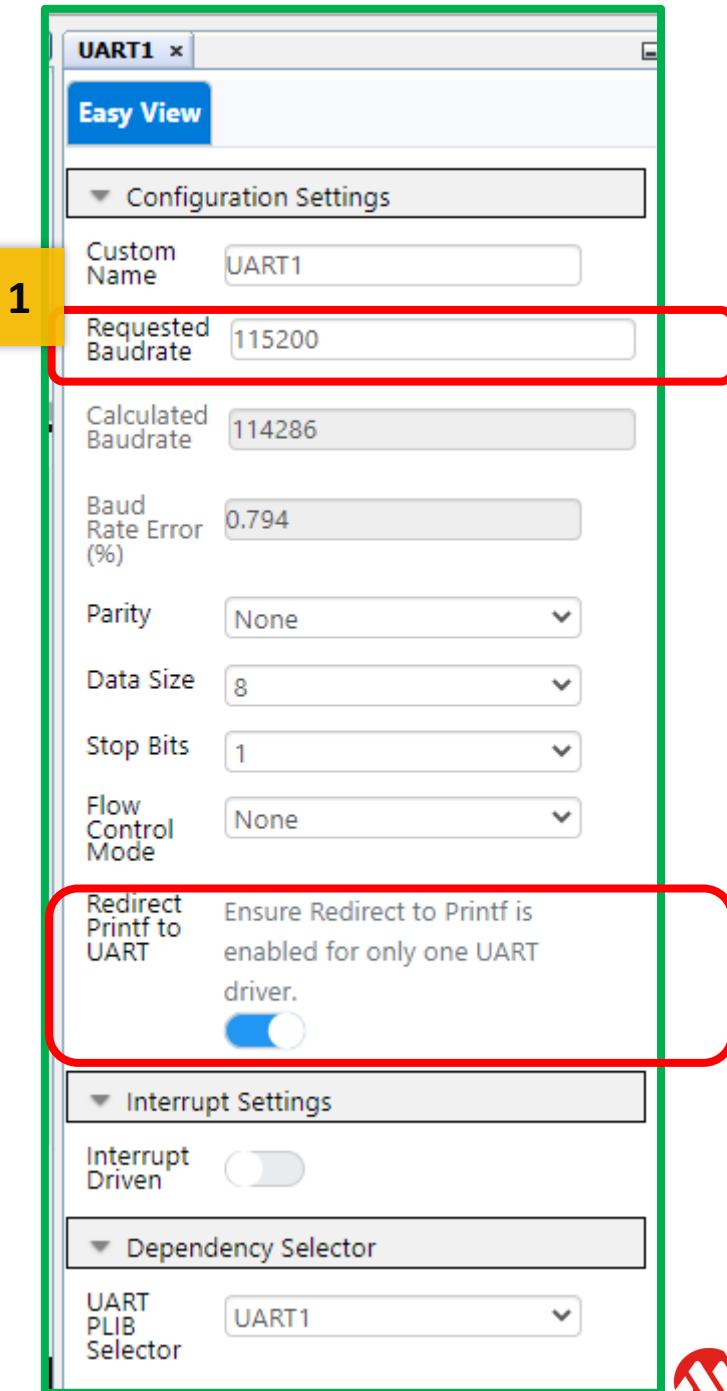
## 小板相關電路



# 4. 確認UART腳位 設腳位RB4 TX, RB3 RX

- 1) 到UART1, Easy View  
改115200-8-N-1  
Redirect printf to UART
- 2) 到Pin Grid View  
設RB4 TX, RB3 RX
- 3) 產生Code

Module	Function	Direction	1	3	4	5	6	7	8	9	10	11	12	13	14	15	0
Clock	CLKO	output	■														
	REFI	input	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■
	REFO	output	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■
ICD	PGCx	input				■						■					
	PGDx	input				■			■			■					
UART1	U1TX	output	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■
	U1RX	input	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■
Pins	GPIO	input	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■
	GPIO	output	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■



# 5. 寫程式

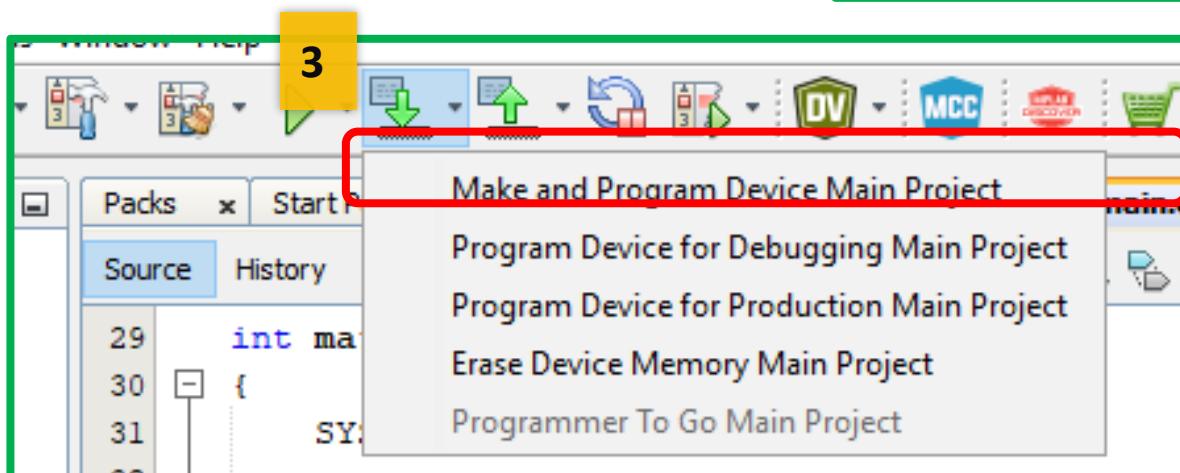
printf("Hi");

1) 到main.c

2) 到while(1); 上一行  
寫 printf("dsPIC33: Hi\r\n");

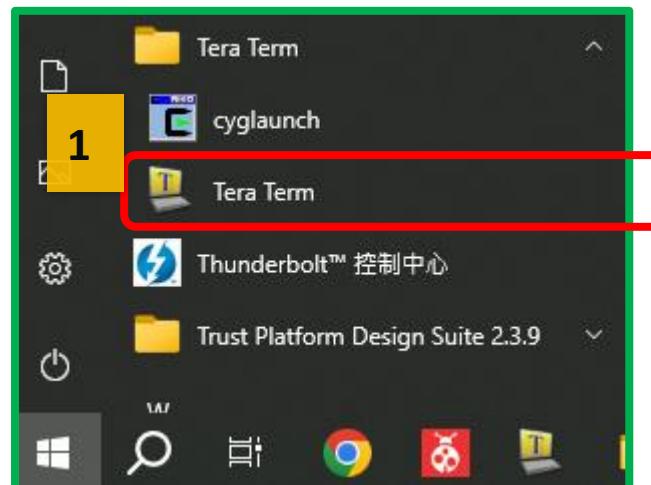
3) 燒錄

```
Kit Window x Packs x Start Page x MPLAB X Store x 1 main.c x Builder x
Source History
30 - {
31     SYSTEM_Initialize();
32     printf("dsPIC33: Hi\r\n");
33
34     while (1)
35
36 }
```



# 6. 結果 顯示dsPIC33:Hi

- 1) 開啟Tera Term
- 2) 找到COM port  
COM21
- 3) Setup -> Serial port
- 4) Baud rate → 115200



2

3

4

The image shows the configuration steps for Tera Term to connect to the dsPIC33:Hi device.

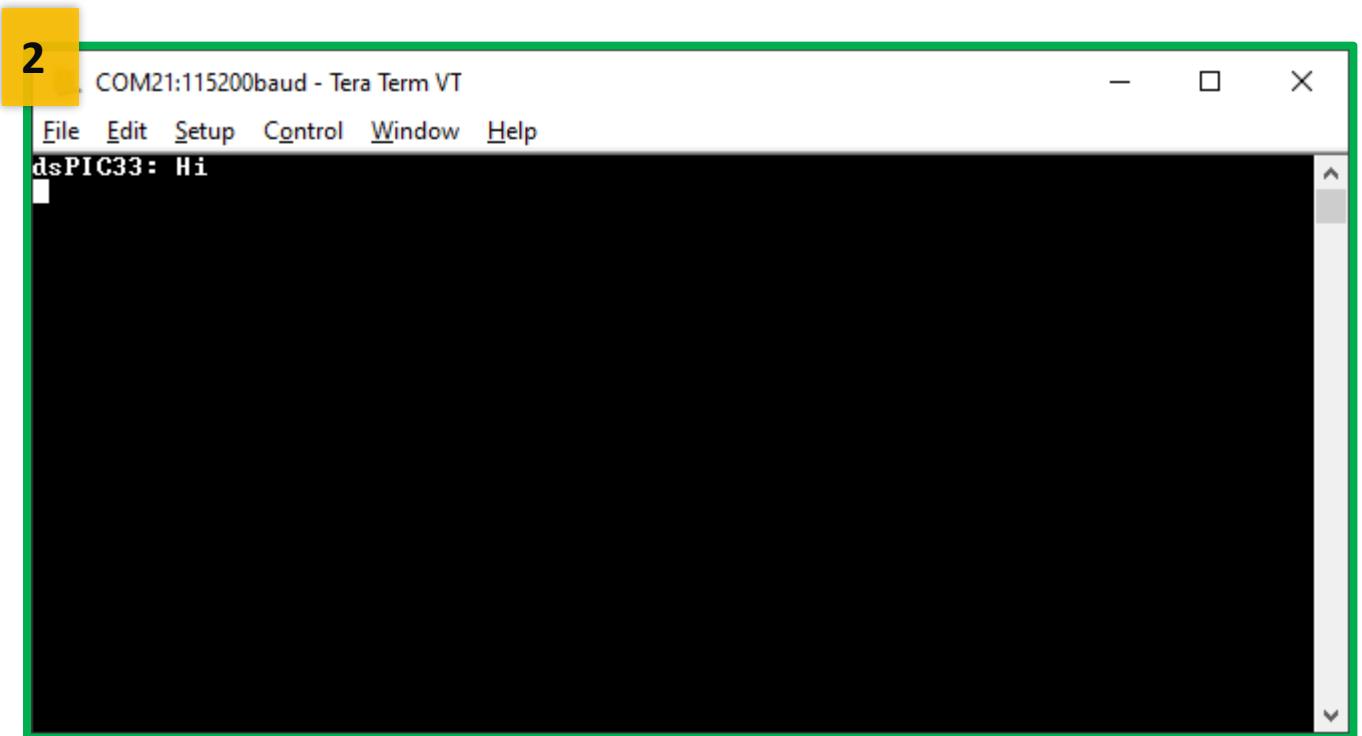
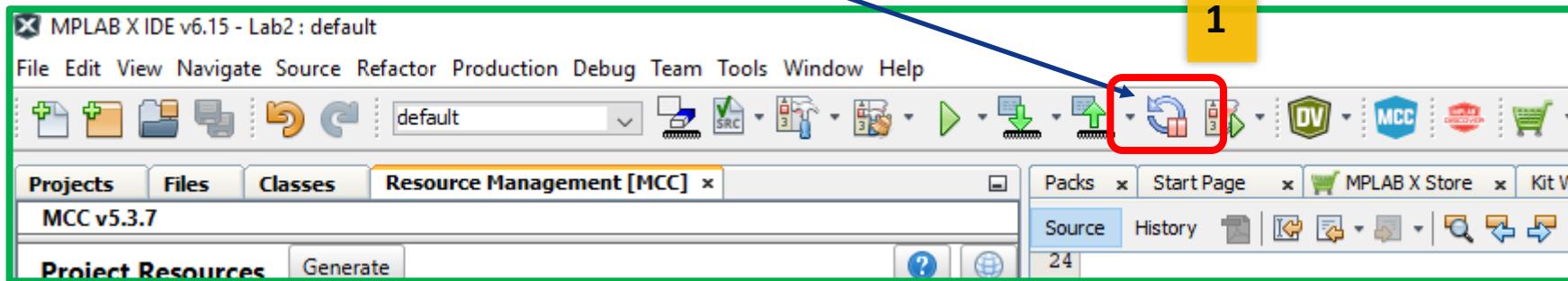
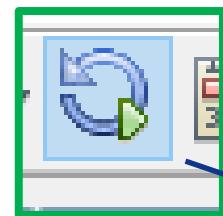
- Step 1:** The Windows taskbar shows the Tera Term icon highlighted with a red box.
- Step 2:** The "Tera Term: New connection" dialog box is open. It shows the "Serial" tab selected. The "Port" dropdown lists several options, with "COM21: USB Serial Device (COM21)" highlighted with a red box. The "OK" button is also highlighted with a red box.
- Step 3:** The "Setup" menu is open, and the "Serial port..." option is highlighted with a red box.
- Step 4:** The "Tera Term: Serial port setup" dialog box is open. The "Baud rate:" dropdown is set to "115200". The "OK" button is highlighted with a red box.

# 6-1.結果

## PC上顯示 dsPIC33: Hi

- 1) 按MPLAB 上的  
Reset icon
- 2) Tera Term  
上顯示Hi

進階測試：  
根據步驟3架構圖  
修改腳位由紅板上  
內建的UART輸出到  
另一個COM PORT



# 內建硬體程式開發

---

Timer/PWM/Config

# 實驗三

---

Timer

# 內建硬體程式開發

## 實驗三：Timer

- 本實驗目的：
  - 架設計時器
    - 最常用的硬體”時間或計數”
    - 用輪詢(Polling)
    - 用中斷(Interrupt)
- 結果
  - 一個LED 每秒只亮100ms (Polling 或 Interrupt)

# 背景知識

---

dsPIC33CK datasheet

# 確認IC內建Timer數量

Datasheet : 只有一個16-bit Timer???

TABLE 1: dsPIC33CK64MC105 FAMILY

Product	Pins	Program Memory	Data Memory	General Purpose I/O/PPS	High-Resolution PWM (Generators)	12-Bit ADC (External Channels)	Remappable Peripherals					Op Amplifiers	Comparators	12-Bit DACs	I <sup>2</sup> C	QEI	SENT	32-Bit CRC	PTG	Current Bias Generator	DMA (Channels)	Packages		
							Dedicated 16-Bit Timers <sup>(3)</sup>		UARTs	S CCP <sup>(1)</sup>	CLC													
dsPIC33CK32MC102	28	32K	8K	21/16	4	11 <sup>(2)</sup>	1	3	4	4	2	2	1	1	1	1	1	1	1	1	1	4	SSOP/UQFN	
dsPIC33CK32MC103	36	32K	8K	27/22	4	15 <sup>(2)</sup>	1	3	4	4	2	3	1	1	1	1	1	1	1	1	1	1	4	UQFN
dsPIC33CK32MC105	48	32K	8K	39/34	4	15 <sup>(2)</sup>	1	3	4	4	2	3	1	1	1	1	1	1	1	1	1	1	4	UQFN/TQFP
dsPIC33CK64MC102	28	64K	8K	21/16	4	11 <sup>(2)</sup>	1	3	4	4	2	2	1	1	1	1	1	1	1	1	1	1	4	SSOP/UQFN
dsPIC33CK64MC103	36	64K	8K	27/22	4	15 <sup>(2)</sup>	1	3	4	4	2	3	1	1	1	1	1	1	1	1	1	1	4	UQFN
dsPIC33CK64MC105	48	64K	8K	39/34	4	15 <sup>(2)</sup>	1	3	4	4	2	3	1	1	1	1	1	1	1	1	1	1	4	UQFN/TQFP

# 計時器 : Timer

16-bit x 1 + (16-bit x 8 或 32-bit x4 )

最多可以有  
9個16-bit計時器：

1個16-bit  
的專用計時器

8個16-bit  
由4個SCCP設成  
的計時器

## dsPIC33CK64MC105 FAMILY

### Peripheral Features

- Two Four-Wire SPI modules (up to 50 Mbps):
  - 16-byte FIFO
  - Variable width
  - I<sup>2</sup>S mode
- One I<sup>2</sup>C Host and Client w/Address Masking and IPMI Support
- Three Protocol UARTs with Automated Handling Support for:
  - LIN 2.2
  - DMX
  - Smart card (ISO 7816)
- One SENT module
- Timers/Counters:
  - One dedicated 16-bit timer/counter
- Four Single Output Capture/Compare/PWM/Timer (SCCP) modules:
  - Flexible configuration as PWM, input capture, output compare or timers
  - Two 16-bit timers or one 32-bit timer in each module
  - PWM resolution down to 2.5 ns
  - Single PWM output

### Debug Features

- Three Programming and Debugging Interfaces:
  - Two-wire ICSP™ interface with non-intrusive access and real-time data exchange with application
- Three Complex, Five Simple Breakpoints
- IEEE Standard 1149.2 Compatible (JTAG) Boundary Scan

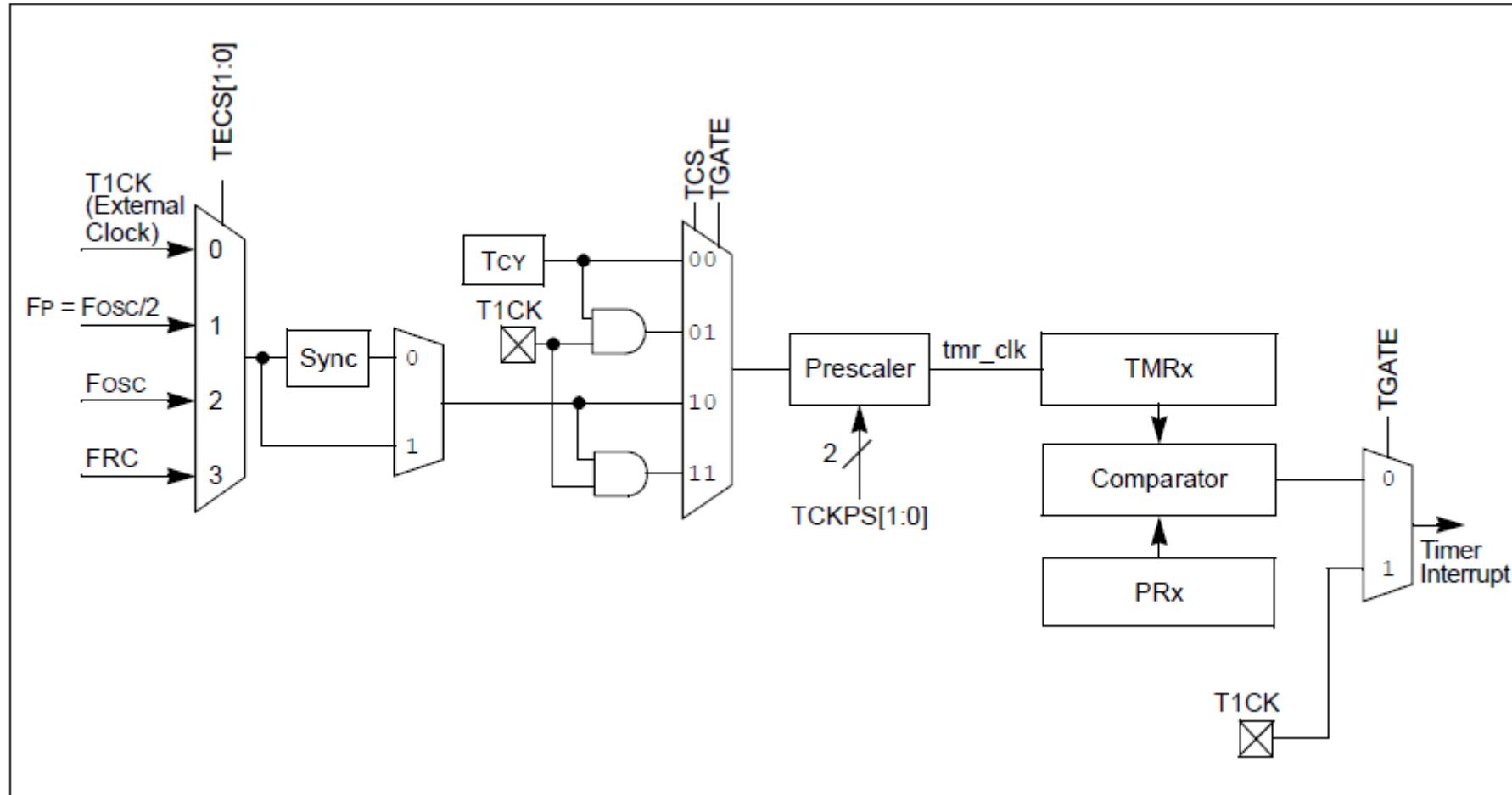
### Safety Features

- Backup Fast RC Oscillator (BFRC)
- Brown-out Reset (BOR)
- Capless Internal Voltage Regulator
- Clock Monitor System with Backup Oscillator
- CodeGuard™ Security
- Cyclic Redundancy Check (CRC)
- Dual Watchdog Timer (WDT)
- Fail-Safe Clock Monitoring (FSCM)
- Flash Error Correcting Code (ECC)
- Flash OTP by ICSP™ Write Inhibit
- RAM Memory Built-In Self-Test (MBIST)
- Two-Speed Start-up

# Timer架構

專用16-bit 計時/計數器

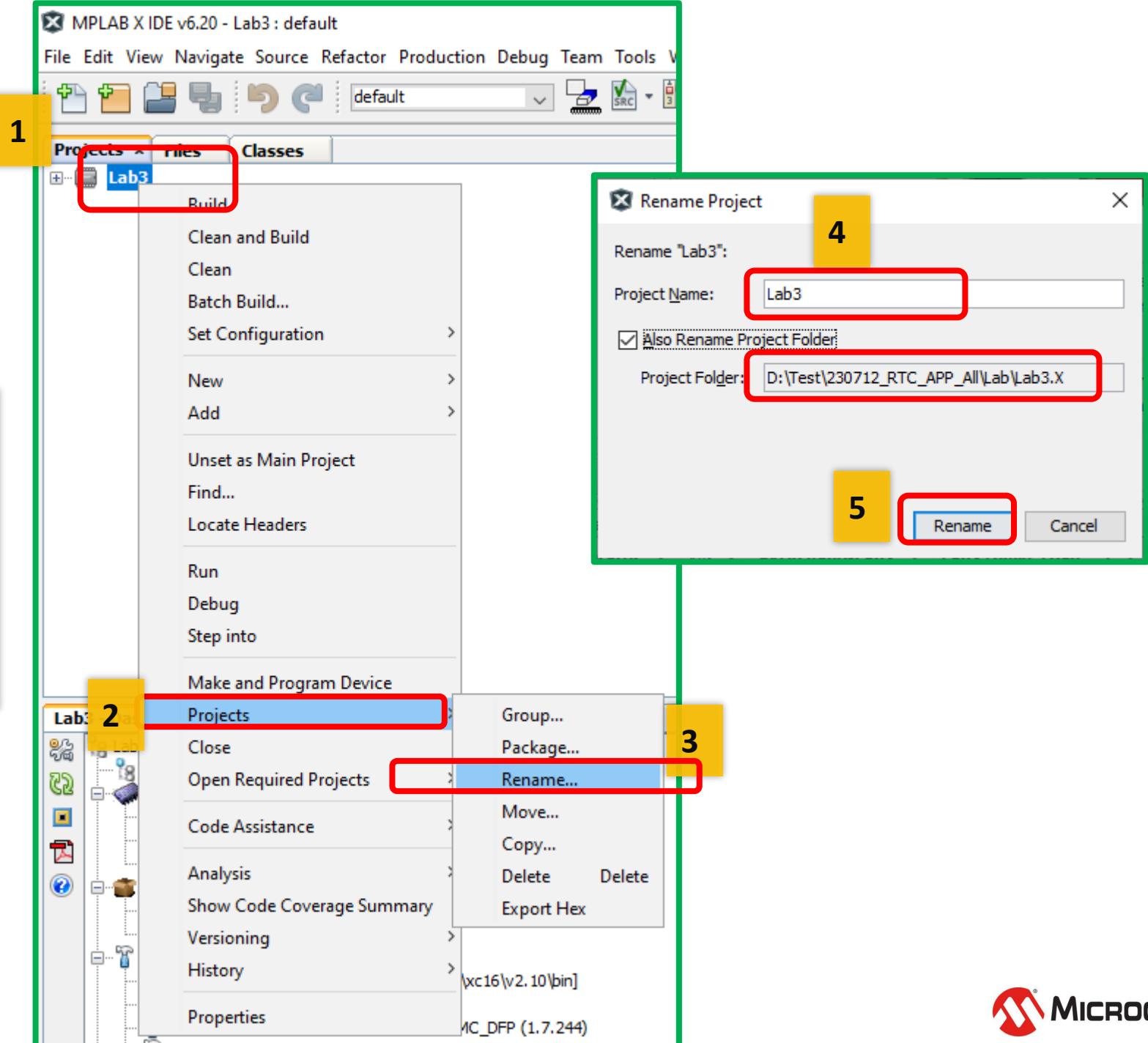
FIGURE 19-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM



# 1. 建立Lab3

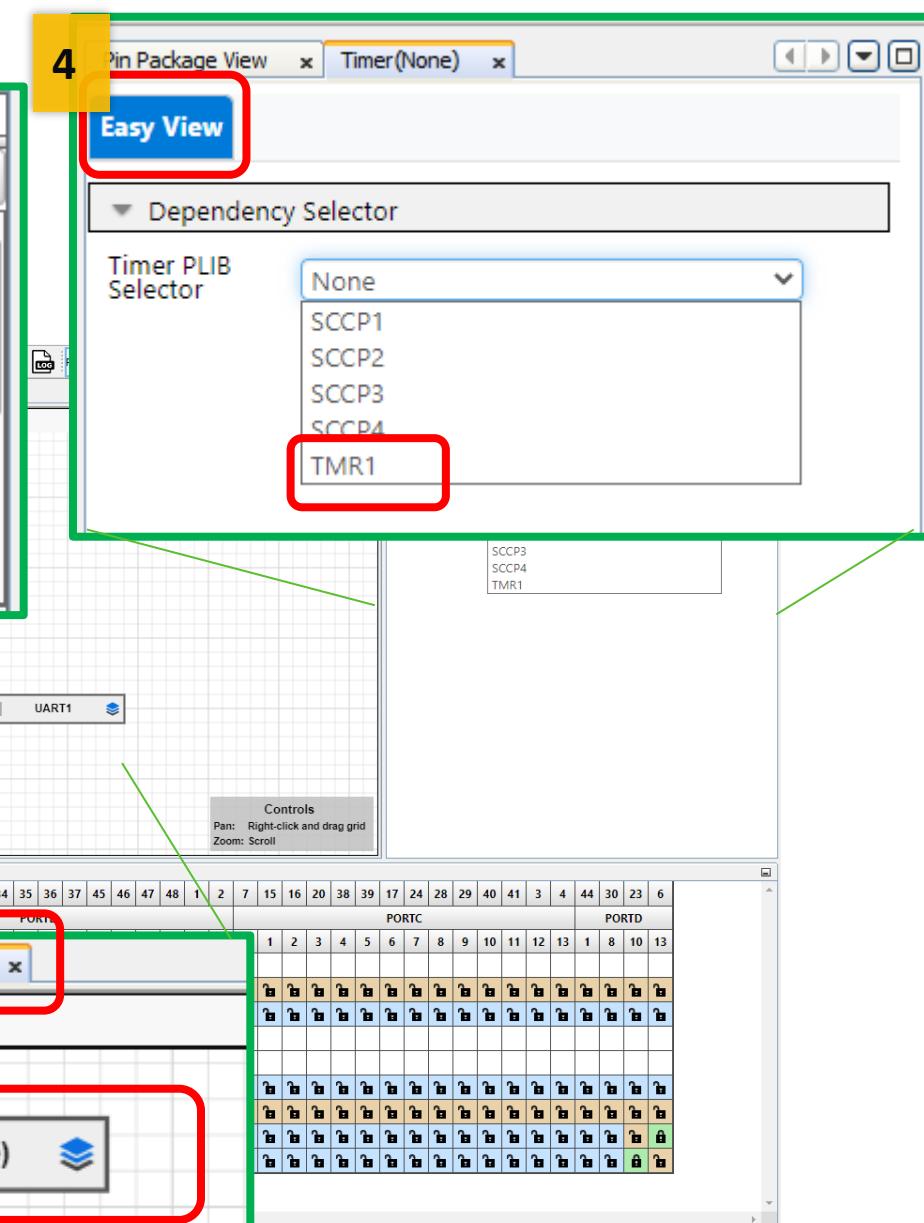
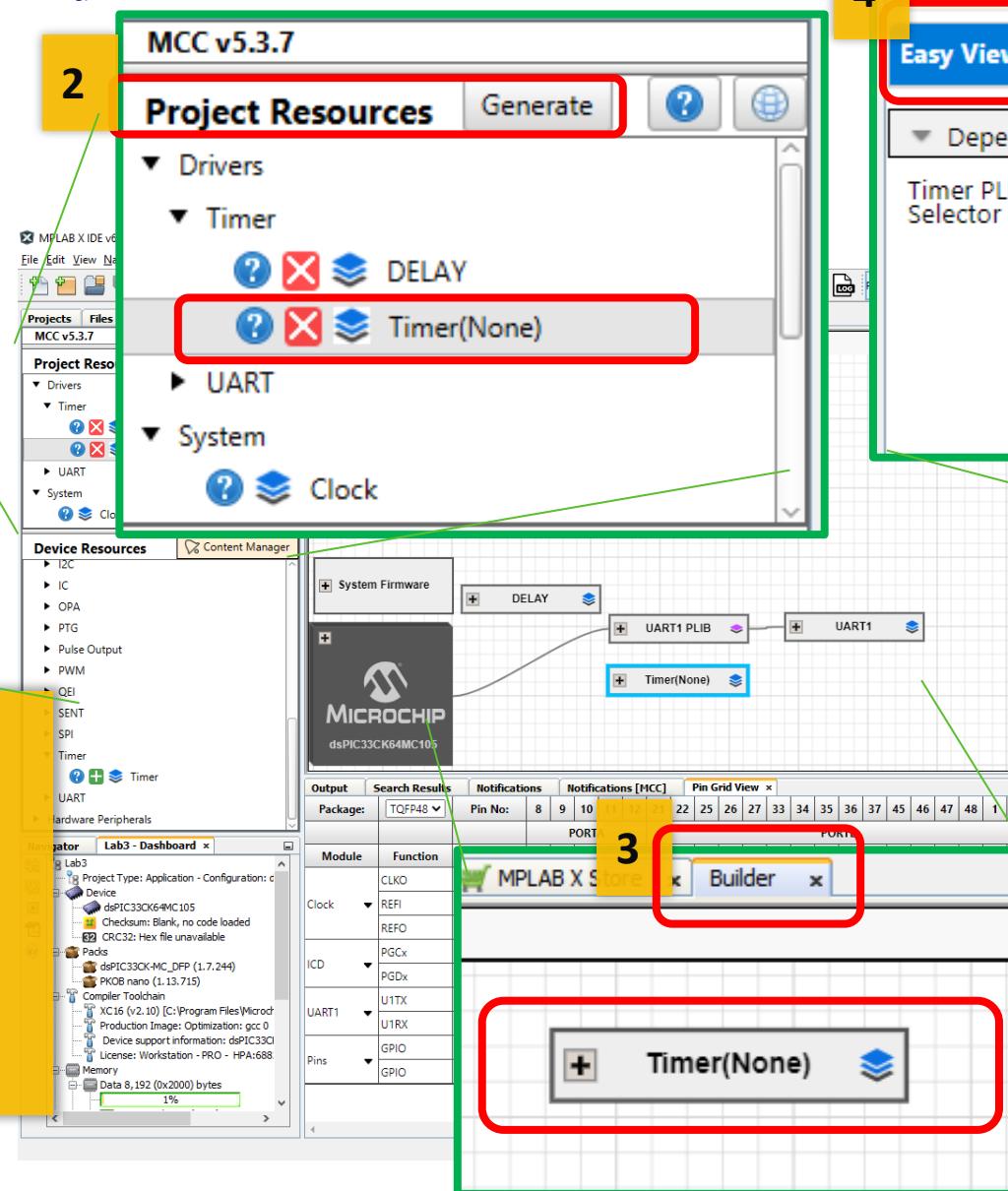
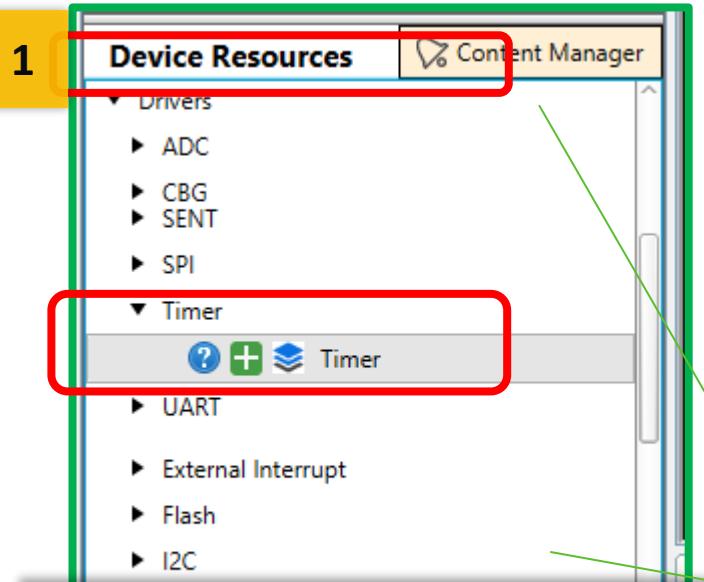
## 將Lab 2改名成Lab3

- 1) 到Projects 在Lab2上滑鼠點右鍵
- 2) 找到Projects -> Rename
- 3) 修改成Lab3
- 4) 勾選順便改資料夾名
- 5) 按 Rename 完成名稱修改



# 2. 在MCC中選取Timer

## 選Timer1



# 3. 設定Timer

設定1 sec => 1000ms

The screenshot shows the MPLAB X IDE interface with several windows open:

- Builder** window (highlighted by a red box):
  - Contains a yellow callout box with steps 1-6.
  - Shows the selected component is **TMR1 PLIB**.
  - Shows the selected timer is **Timer1**.
- Timer1** window (highlighted by a yellow box):
  - Shows the **Easy View** tab.
  - Shows the **Software Settings** section with:
    - Custom Name: Timer1
    - Timer Enable: On
    - Requested Timer Period (ms): 1000 (highlighted by a red box)
    - Calculated Timer Period (ms): 1000 (highlighted by a red box)
    - Interrupt Driven: Off (highlighted by a red box)
- TMR1 PLIB** window (highlighted by a red box):
  - Shows the **Clock Settings** section with:
    - Clock Source: FOSC/2 (highlighted by a red box)
    - Clock Source Frequency (Hz): 4000000
    - Configure Clock Prescaler: On
    - Timer\_PeriodSet() API Range (ms): [0.032 - 1048.576]

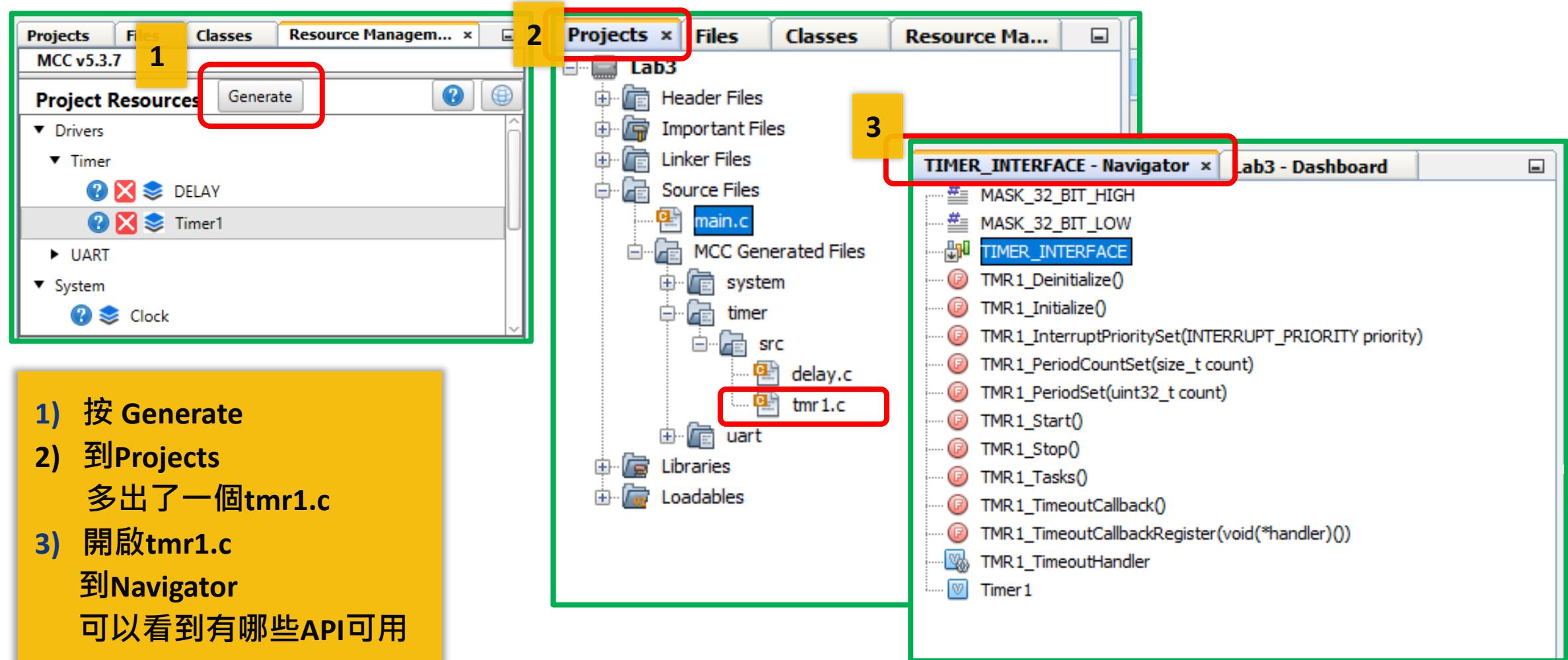
**Yellow Callout Box (Left):**

- 到Builder ,點選TMR1 PLIB
- 到Easy View
- Clock source 選FOSC/2
- 到Builder ,點選Timer1
- 到Easy View
- Requested Timer Period  
改1000ms
- 確認Calculated Timer Period  
也是1000ms
- 關閉中斷(Interrupt Driven)

**Yellow Boxes (Bottom):**

- 1 TMR1 PLIB
- 3 Timer1

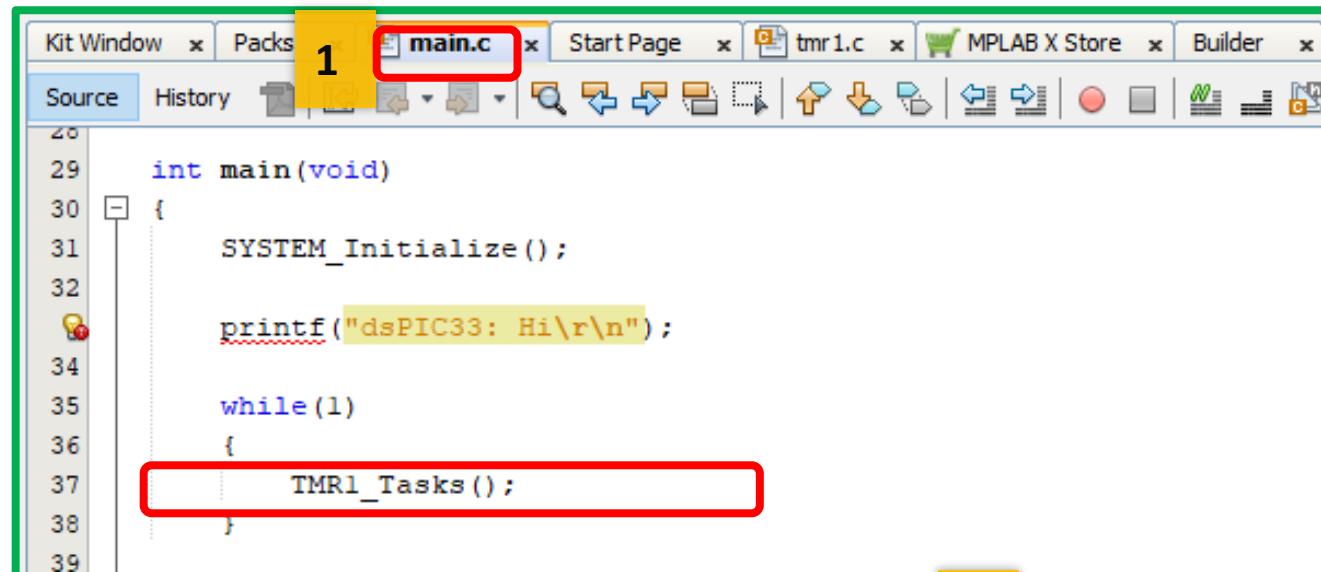
# 4. 產生CODE



# 5. 寫CODE

## LED0 - 1 Hz

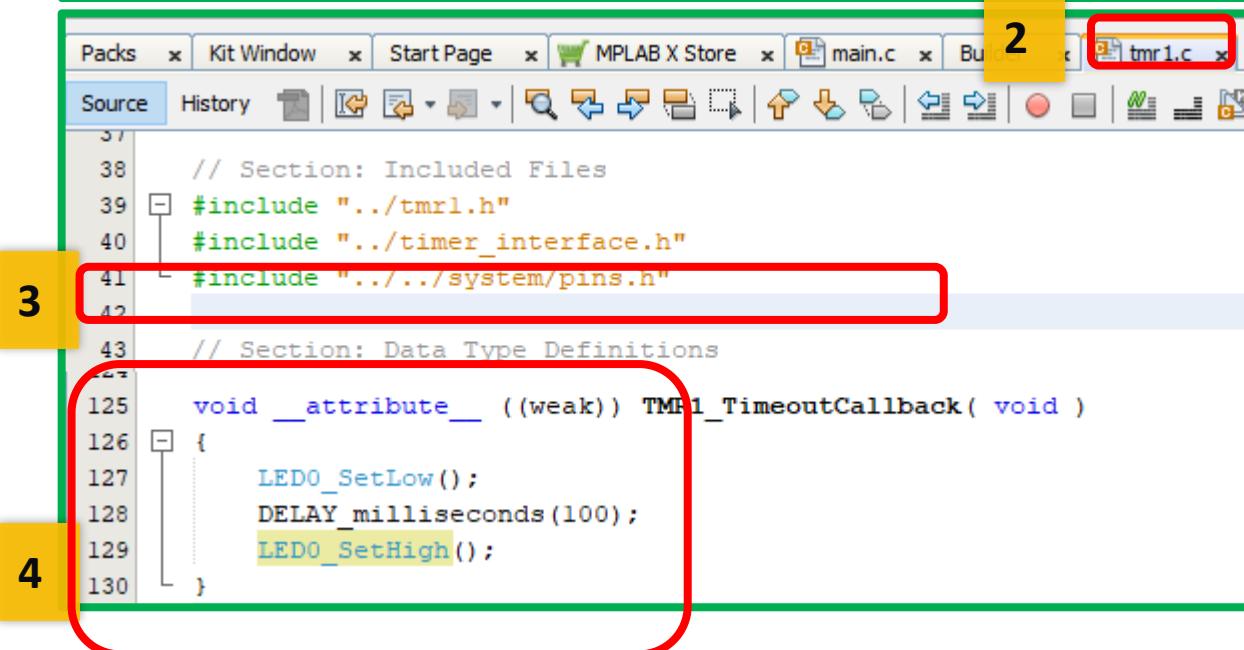
- 1) 到main.c  
的while(1) {}內  
寫TMR1\_Task();
- 2) 到tmr1.c
- 3) 開頭處  
`#include "../../system/pins.h"`
- 4) TMR1\_TimeoutCallback( void )  
{}內寫  
`LED0_SetLow();`  
`DELAY_milliseconds(100);`  
`LED0_SetHigh();`



```
int main(void)
{
    SYSTEM_Initialize();

    printf("dsPIC33: Hi\r\n");

    while(1)
    {
        TMR1_Tasks();
    }
}
```



```
// Section: Included Files
#include "../tmr1.h"
#include "../timer_interface.h"
#include "../../../../system/pins.h"

// Section: Data Type Definitions

void __attribute__((weak)) TMR1_TimeoutCallback( void )
{
    LED0_SetLow();
    DELAY_milliseconds(100);
    LED0_SetHigh();
}
```

# 6.結果

## Lab3\_0

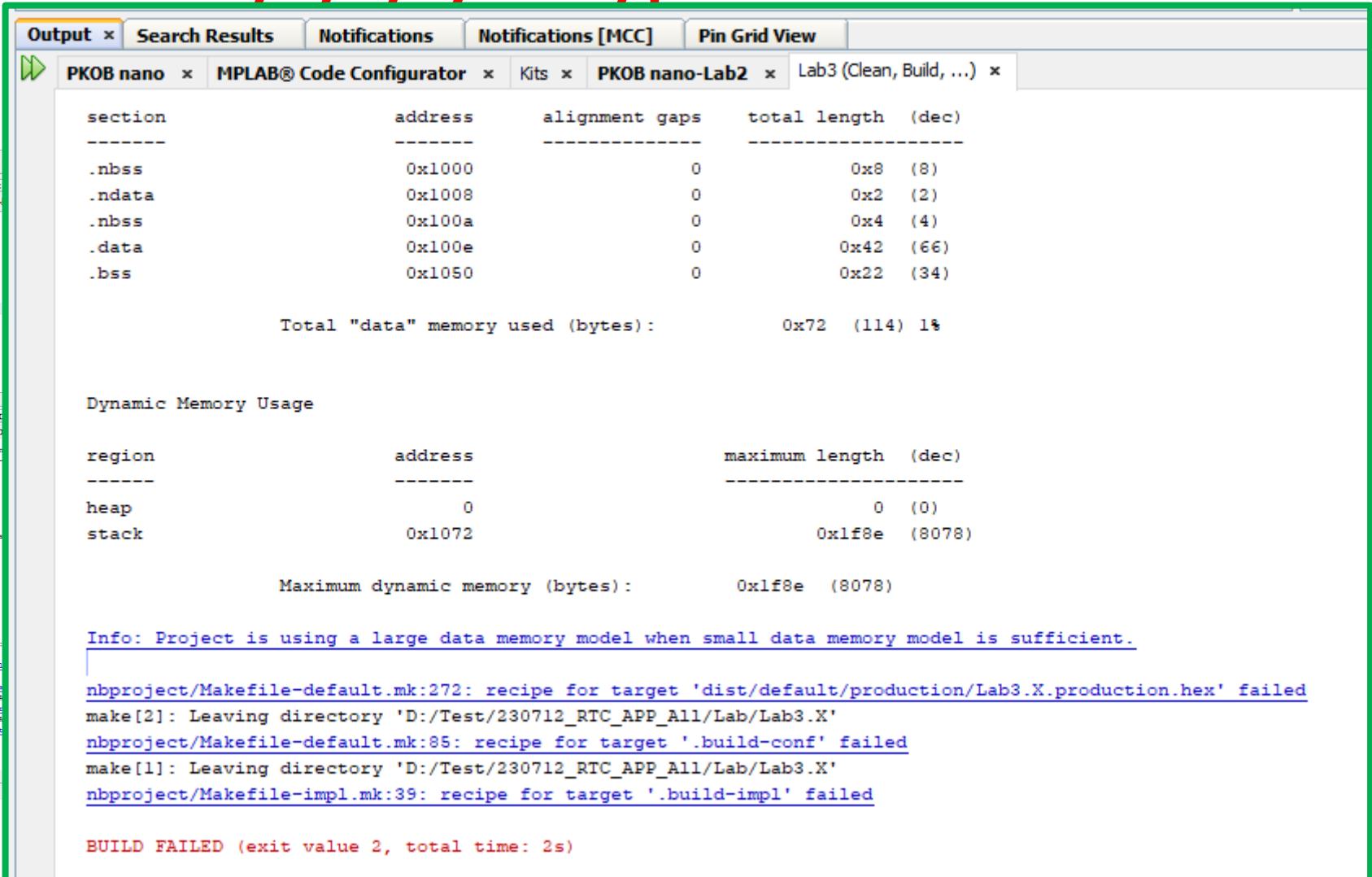
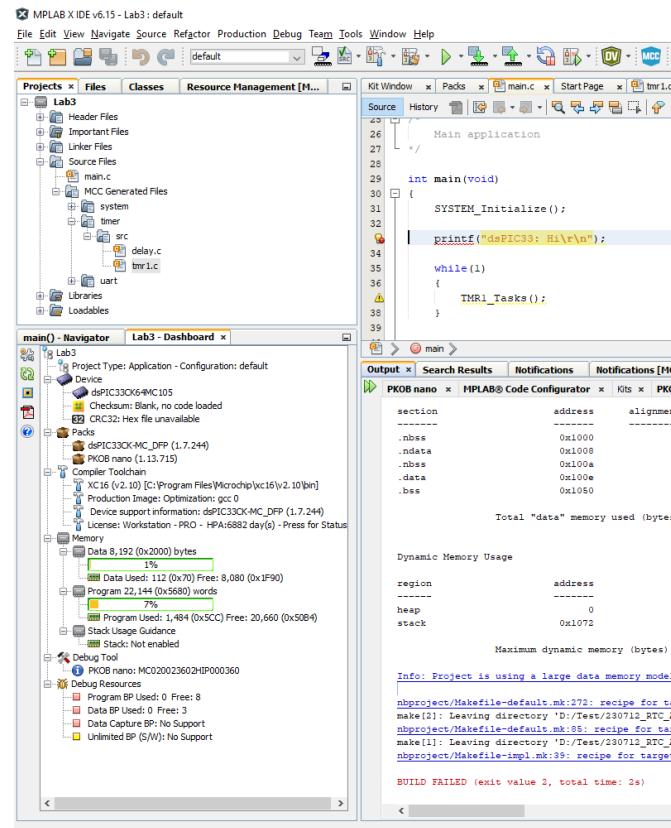
1)燒錄測試

2)結果

紅板上LED0，每秒亮100ms

# 7. 補充：出現此錯誤

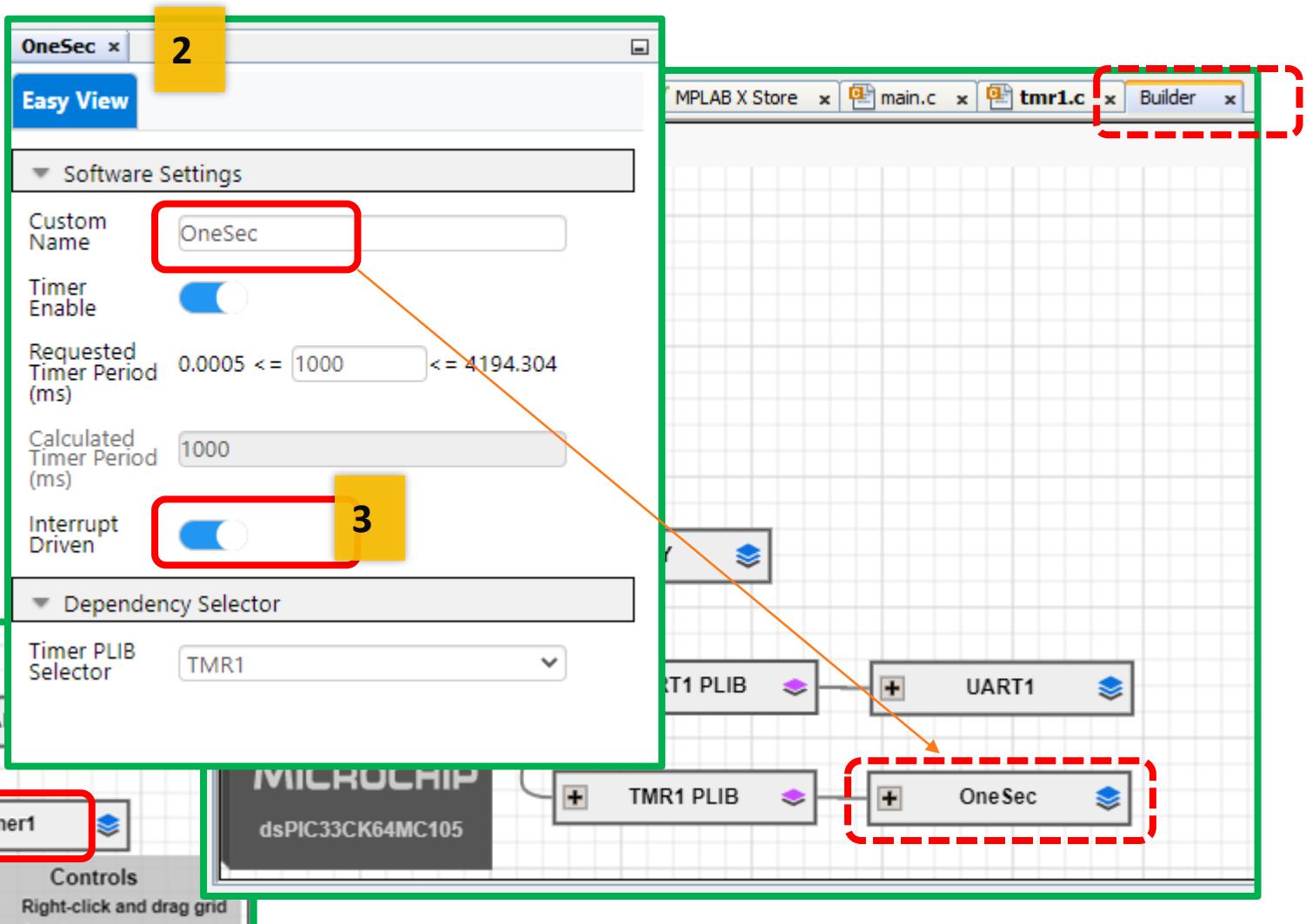
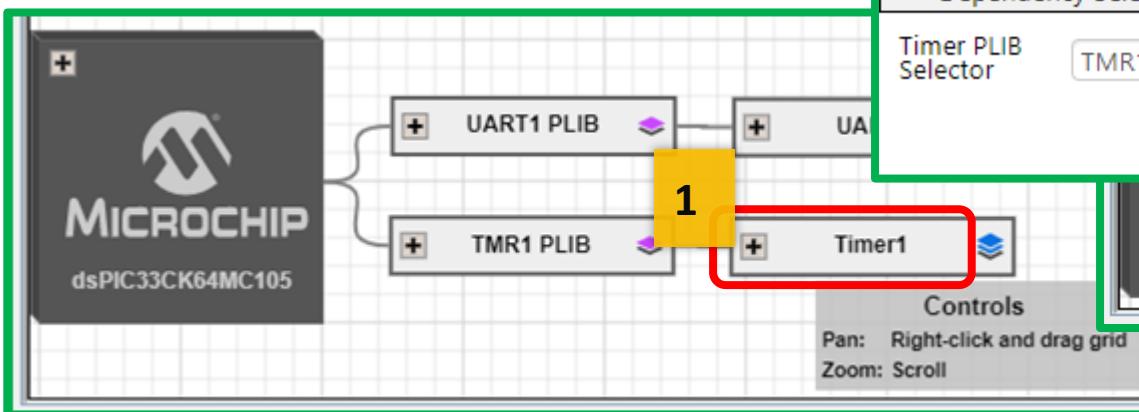
代表沒寫到這行 `#include "../../system/pins.h"`



# 8.改用中斷方式

## Timer1

- 1) 點選Timer1
- 2) 修改Custom Name  
成OneSec  
Builder內容  
也會跟著變
- 3) 開啟Inturrrpt Driven

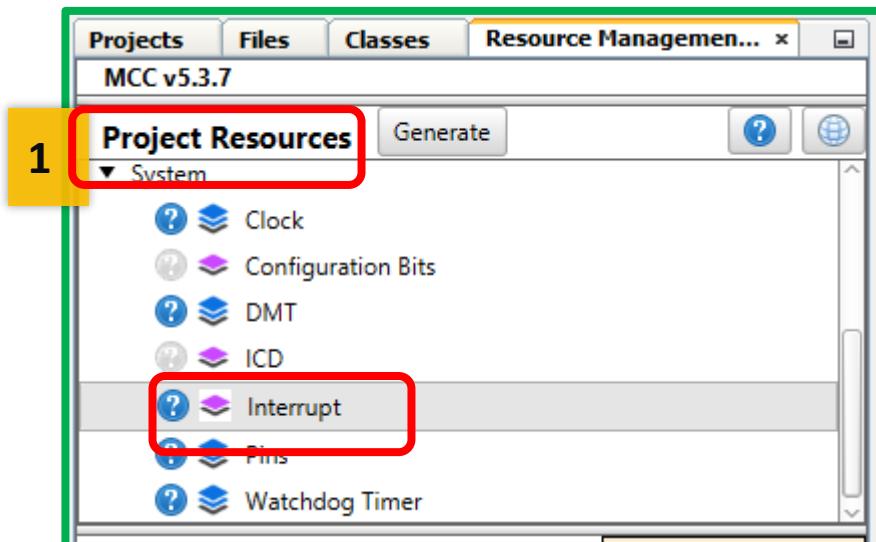


# 9. 設定中斷

## 設定中斷優先權

- 1) 到Project Resource, 點Interrupt
- 2) 到Easy View, 找到OneSec  
修改優先權等級 IPL 為 2

軟體可調優先權最高7  
硬體內定優先權最高15

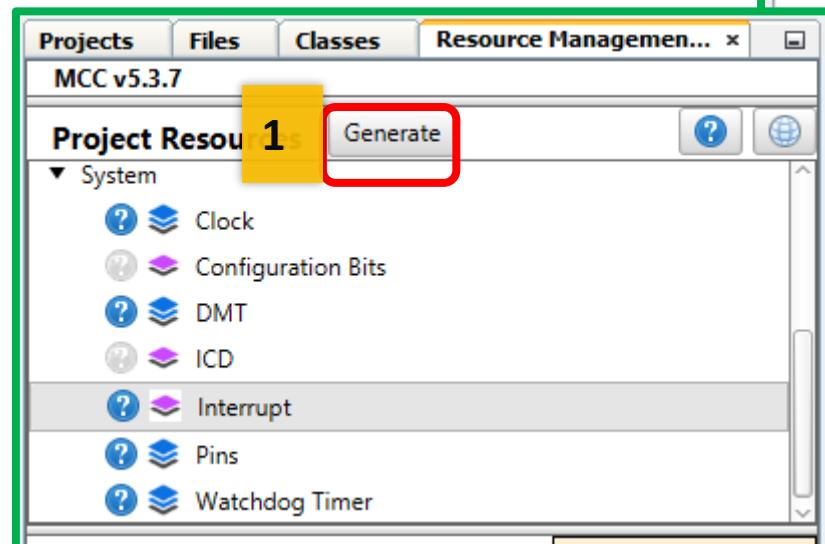


2

Module	Interrupt	Description	IRQ Number	Enabled	Priority(IPL)	Context(CTXTn)
DMT	DMT	Dead Man	45	<input checked="" type="checkbox"/>	1	
OneSec	T1	Timer 1	1	<input checked="" type="checkbox"/>	2	1
Pins	CNA	Change	2	<input type="checkbox"/>	1	2
Pins	CNB	Notification A		<input type="checkbox"/>	3	3
		Change	3	<input type="checkbox"/>	4	4
				<input type="checkbox"/>	5	5
				<input type="checkbox"/>	6	6
				<input type="checkbox"/>	7	7
				<input type="checkbox"/>	8	44
				<input type="checkbox"/>	9	30
				<input type="checkbox"/>	10	23
				<input type="checkbox"/>	11	6
				<input type="checkbox"/>	12	PORTC
				<input type="checkbox"/>	13	PORTD
				<input type="checkbox"/>	14	
				<input type="checkbox"/>	15	
				<input type="checkbox"/>	16	
				<input type="checkbox"/>	17	
				<input type="checkbox"/>	18	
				<input type="checkbox"/>	19	
				<input type="checkbox"/>	20	
				<input type="checkbox"/>	21	
				<input type="checkbox"/>	22	
				<input type="checkbox"/>	23	
				<input type="checkbox"/>	24	
				<input type="checkbox"/>	25	
				<input type="checkbox"/>	26	
				<input type="checkbox"/>	27	
				<input type="checkbox"/>	28	
				<input type="checkbox"/>	29	
				<input type="checkbox"/>	30	
				<input type="checkbox"/>	31	
				<input type="checkbox"/>	32	
				<input type="checkbox"/>	33	
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				<input type="checkbox"/>	43	
				<input type="checkbox"/>	44	
				<input type="checkbox"/>	45	
				<input type="checkbox"/>	46	
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				<input type="checkbox"/>	66	
				<input type="checkbox"/>	67	
				<input type="checkbox"/>	68	
				<input type="checkbox"/>	69	
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				<input type="checkbox"/>	87	
				<input type="checkbox"/>	88	
				<input type="checkbox"/>	89	
				<input type="checkbox"/>	90	
				<input type="checkbox"/>	91	
				<input type="checkbox"/>	92	
				<input type="checkbox"/>	93	
				<input type="checkbox"/>	94	
				<input type="checkbox"/>	95	
				<input type="checkbox"/>	96	
				<input type="checkbox"/>	97	
				<input type="checkbox"/>	98	
				<input type="checkbox"/>	99	
				<input type="checkbox"/>	100	

# 10.產生CODE

- 1) 按 Generate
- 2) 確認差異  
X 或 → 達到刪除或取代
- 3) 按=> 全部取代



The screenshot shows the MPLAB X IDE with the 'Merge [MCC]' tab selected. The code editor displays the merged result of tmr1.c. A red box highlights the 'Merge' tab at the top right. Another red box highlights the line '#include <.../system/pins.h>' in the code, which is marked with a red 'X' and has a green background. The code itself includes sections for included files, data type definitions, and specific functions for the timer.

```
// Section: Included Files
#include "../tmr1.h"
#include "../timer_interface.h"

// Section: Data Type Definitions
#define MASK_32_BIT_LOW 0x0000FFFFU
#define MASK_32_BIT_HIGH 0xFFFF0000U

// Section: File specific functions
ic void (*TMR1_TimeoutHandler) (void) = NULL;
section: Driver Interface
t struct TIMER_INTERFACE OneSec = {
    .Initialize = &TMRI_Initialize,
    .Deinitialize = &TMRI_Deinitialize,
    .Start = &TMRI_Start,
    .Stop = &TMRI_Stop,
#if TIMER_PERIODCOUNTSET_API_SUPPORT
    .PeriodCountSet = &TMRI_PeriodCountSet,
#endif
    .PeriodSet = &TMRI_PeriodSet,
    .PeriodGet = &TMRI_PeriodGet,
    .CounterGet = &TMRI_CounterGet,
    .InterruptPrioritySet = &TMRI_InterruptPrioritySet
};

const struct TIMER_INTERFACE Timer1 = {
    .Initialize = &TMRI_Initialize,
    .Deinitialize = &TMRI_Deinitialize,
    .Start = &TMRI_Start,
    .Stop = &TMRI_Stop,
#if TIMER_PERIODCOUNTSET_API_SUPPORT
    .PeriodCountSet = &TMRI_PeriodCountSet,
#endif
    .PeriodSet = &TMRI_PeriodSet,
    .PeriodGet = &TMRI_PeriodGet,
    .CounterGet = &TMRI_CounterGet,
    .InterruptPrioritySet = &TMRI_InterruptPrioritySet
};
```

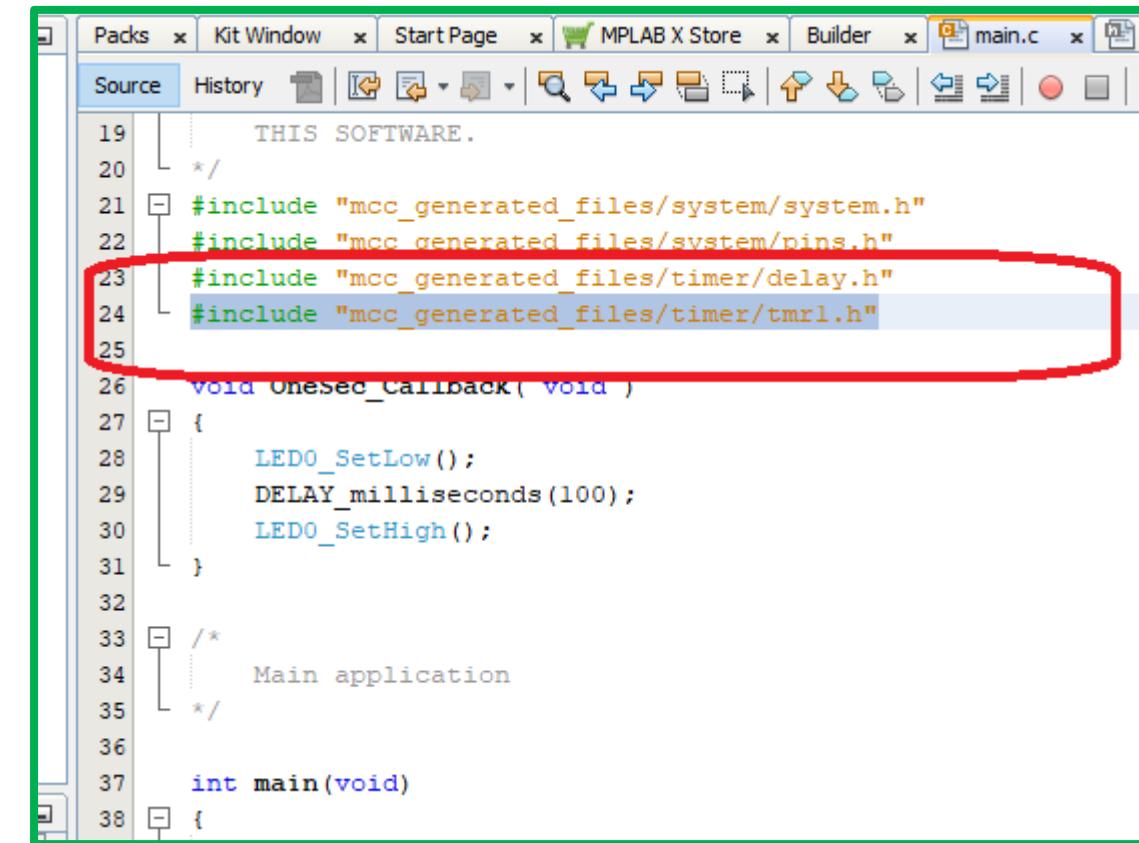
# 11. 寫CODE

## tmr1.h

1) 在main.c

2) 開頭加入

#include "mcc\_generated\_files/timer/tmr1.h"



```
19     THIS SOFTWARE.  
20 */  
21 #include "mcc_generated_files/system/system.h"  
22 #include "mcc_generated_files/system/pins.h"  
23 #include "mcc_generated_files/timer/delay.h"  
24 #include "mcc_generated_files/timer/tmr1.h"  
25  
26 void onesec_callback( void )  
27 {  
28     LED0_SetLow();  
29     DELAY_milliseconds(100);  
30     LED0_SetHigh();  
31 }  
32  
33 /*  
34 Main application  
35 */  
36  
37 int main(void)  
38 {
```

# 12. 寫CODE 用CallBack寫法

- 1) 繼續修改main.c
  - 2) 刪除while(1)中之前加的程式
  - 3) 在SYSTEM\_Initialize後告知中斷時要呼叫的函式  
**OneSec\_TimeoutCallbackRegister(OneSec\_Callback);**
  - 4) 修改printf("dsPIC33: Lab3\r\n");  
方便辨識是否是執行新程式
  - 5) 告知中斷後要做的事

```
void OneSec_Callback( void )
{
    LED0_SetLow();
    DELAY_milliseconds(100);
    LED0_SetHigh();
}
```

1

```
Packs x Kit Window x Start Page x MPLAB X Store x main.c x tmr1  
Source History |             
27 Main application  
28 */  
5 void OneSec_Callback( void )  
31 {  
32     LED0_SetLow();  
33     DELAY_milliseconds(100);  
34     LED0_SetHigh();  
35 }  
36  
37  
38 int main(void)  
39 {  
40     SYSTEM_Initialize();  
41  
3     OneSec_TimeoutCallbackRegister(OneSec_Callback);  
43  
4     printf("dsPIC33: Lab3\r\n");  
45  
46     while(1)  
47     {  
48         // TMR1_Tasks();  
49     }  
50
```

名字相同既可

2

# 12.結果

## Lab3

### 1)燒錄測試

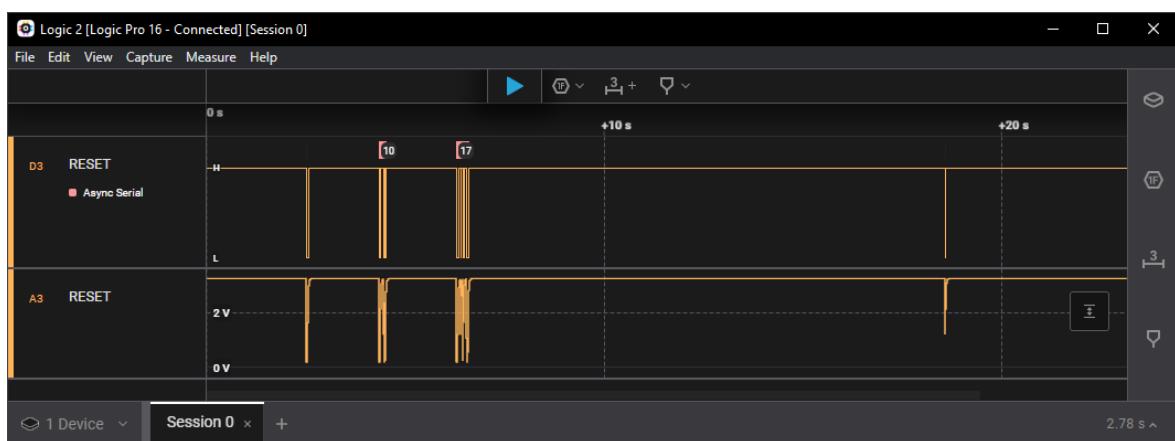
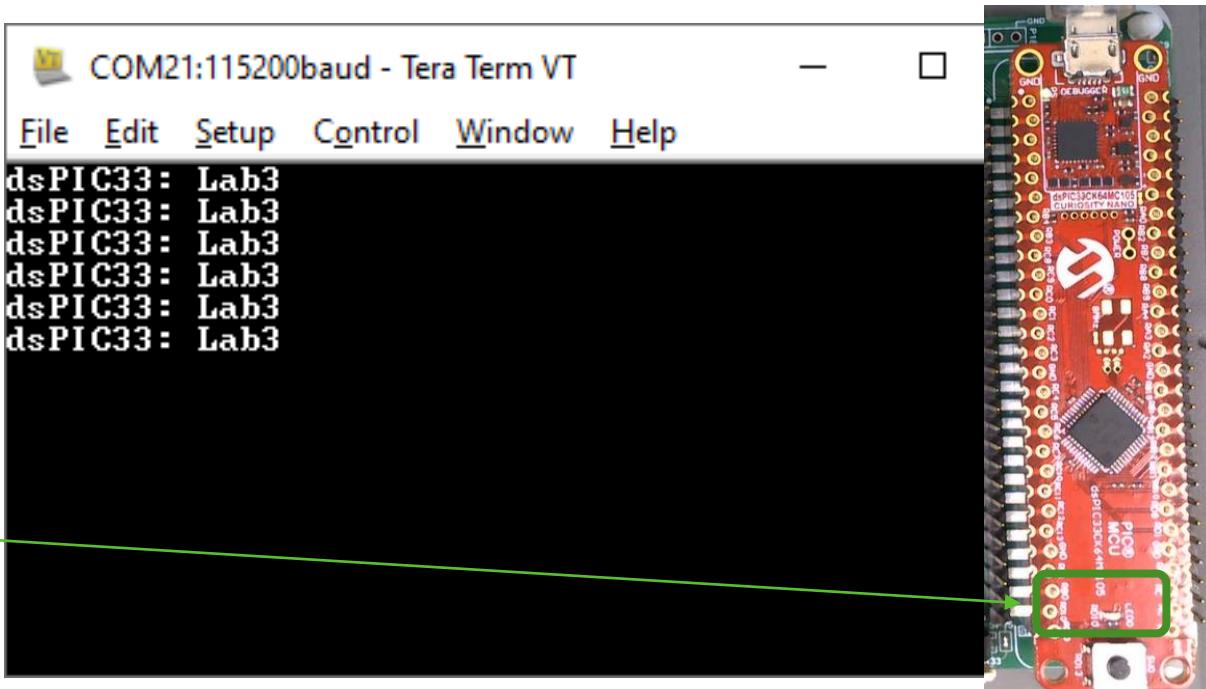
### 2)成果

紅板上LED0

每秒亮100ms

PC顯示 **dsPIC33: Lab3**

- 會顯示很多行**dsPIC33: Lab3?**
- 是因為燒錄時會拉放**RESET**多次



# 實驗四

---

Timer(SCCP)

# 內建硬體程式開發

## 實驗四：Timer(SCCP)

- 本實驗目的：
  - 架設計時器
    - 用一個SCCP完成兩個16-bit Timer
    - 分別控制底板的LED1 ,LED2 /LED3, LED4
- 結果
  - LED1,2 亮1 Hz
  - LED3,4 亮2 Hz

# 背景知識

---

dsPIC33CK datasheet

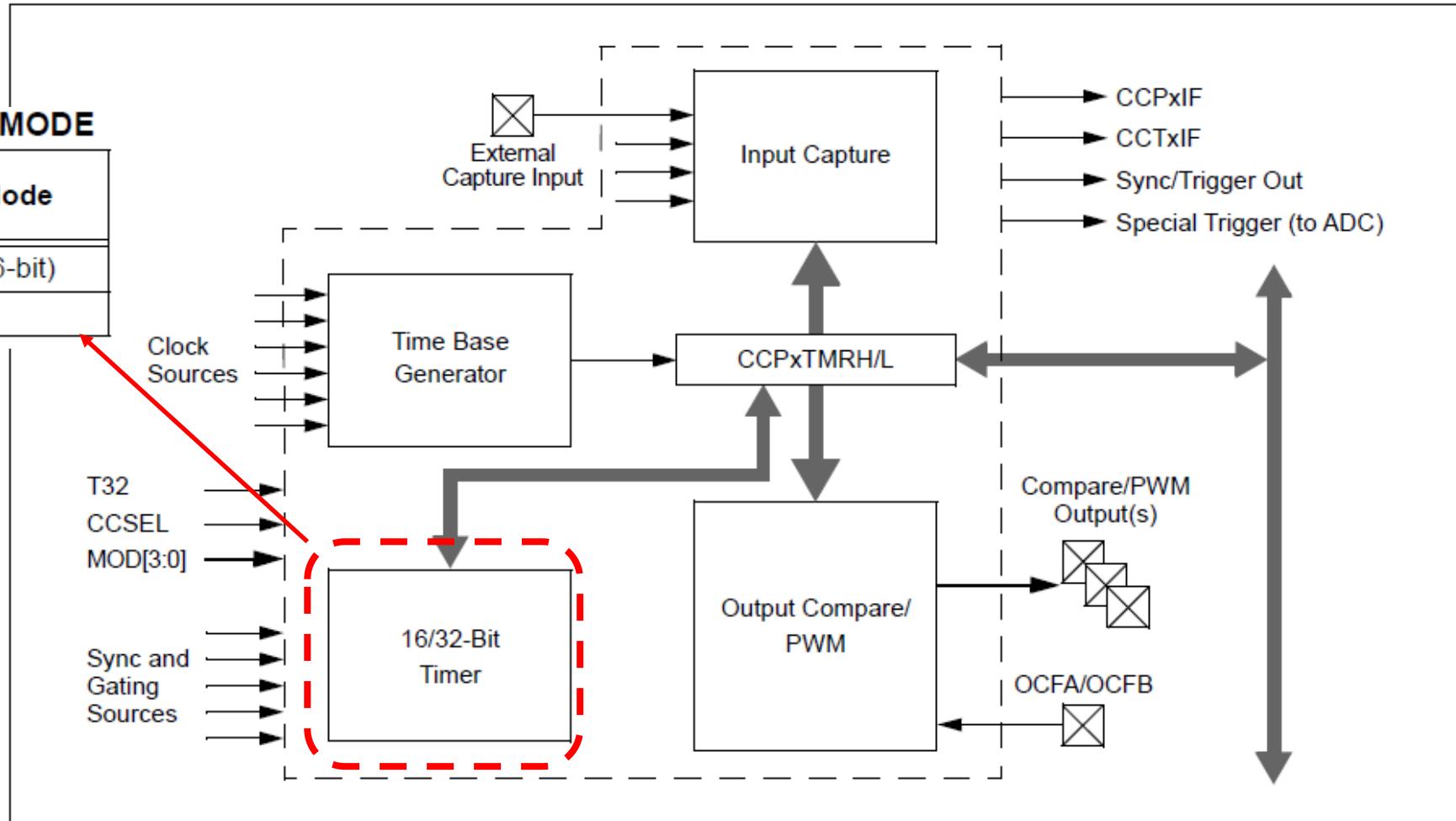
# SCCP架構

SCCP(Single Output Capture/Compare/PWM/Timer modules)

FIGURE 20-1: SCCPx CONCEPTUAL BLOCK DIAGRAM

TABLE 20-1: TIMER OPERATION MODE

T32 (CCPxCON1L[5])	Operating Mode
0	Dual Timer Mode (16-bit)
1	Timer Mode (32-bit)



# SCCP架構

SCCP(Single Output Capture/Compare/PWM/Timer modules)

FIGURE 20-2: TIMER CLOCK GENERATOR

**CLKSEL[2:0]: CCPx Time Base Clock Select bits**

111 = PPS TxCK input

110 = CLC4

101 = CLC3

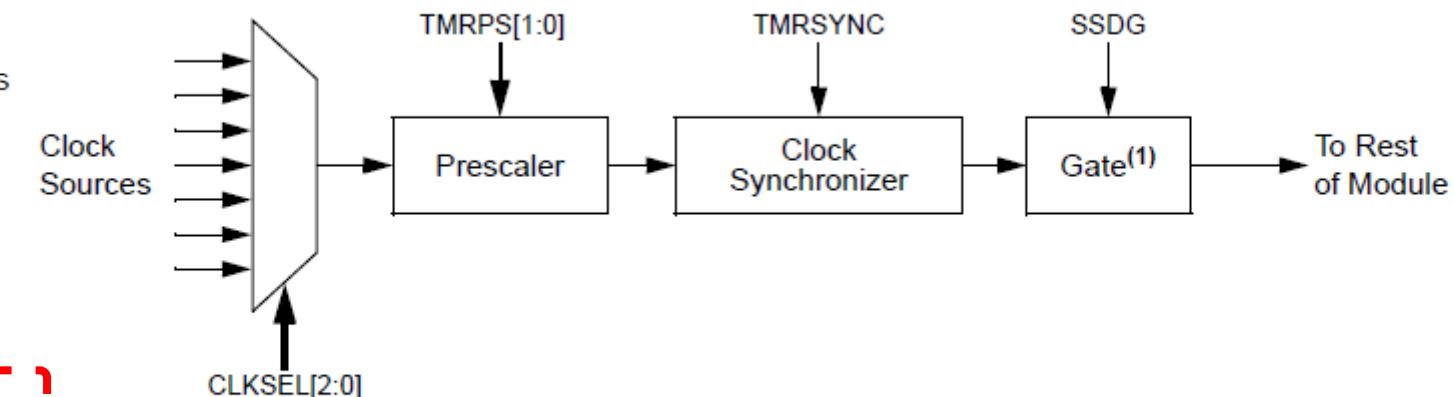
100 = CLC2

011 = CLC1

010 = Reserved

001 = Reference Clock (REFCLK0)

000 = Peripheral Clock ( $FP = Fosc/2$ )



Note 1: Gating is available in Timer modes only.

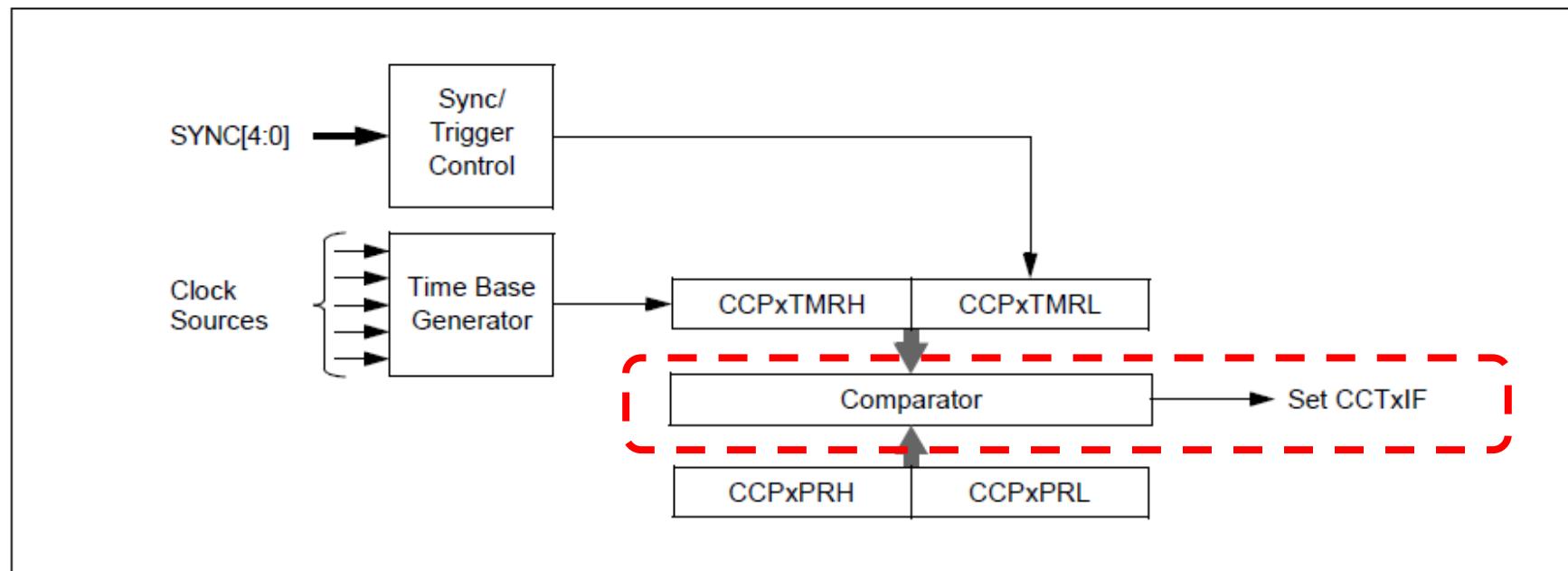
# SCCP架構

# 設定成：一個32-bit 計時器

**TABLE 20-5: SYNCHRONIZATION SOURCES**

<b>SYNC[4:0]</b>	<b>Synchronization Source</b>
00000	None; Timer with Rollover on CCPxPR Match or FFFFh

**FIGURE 20-4: 32-BIT TIMER MODE**

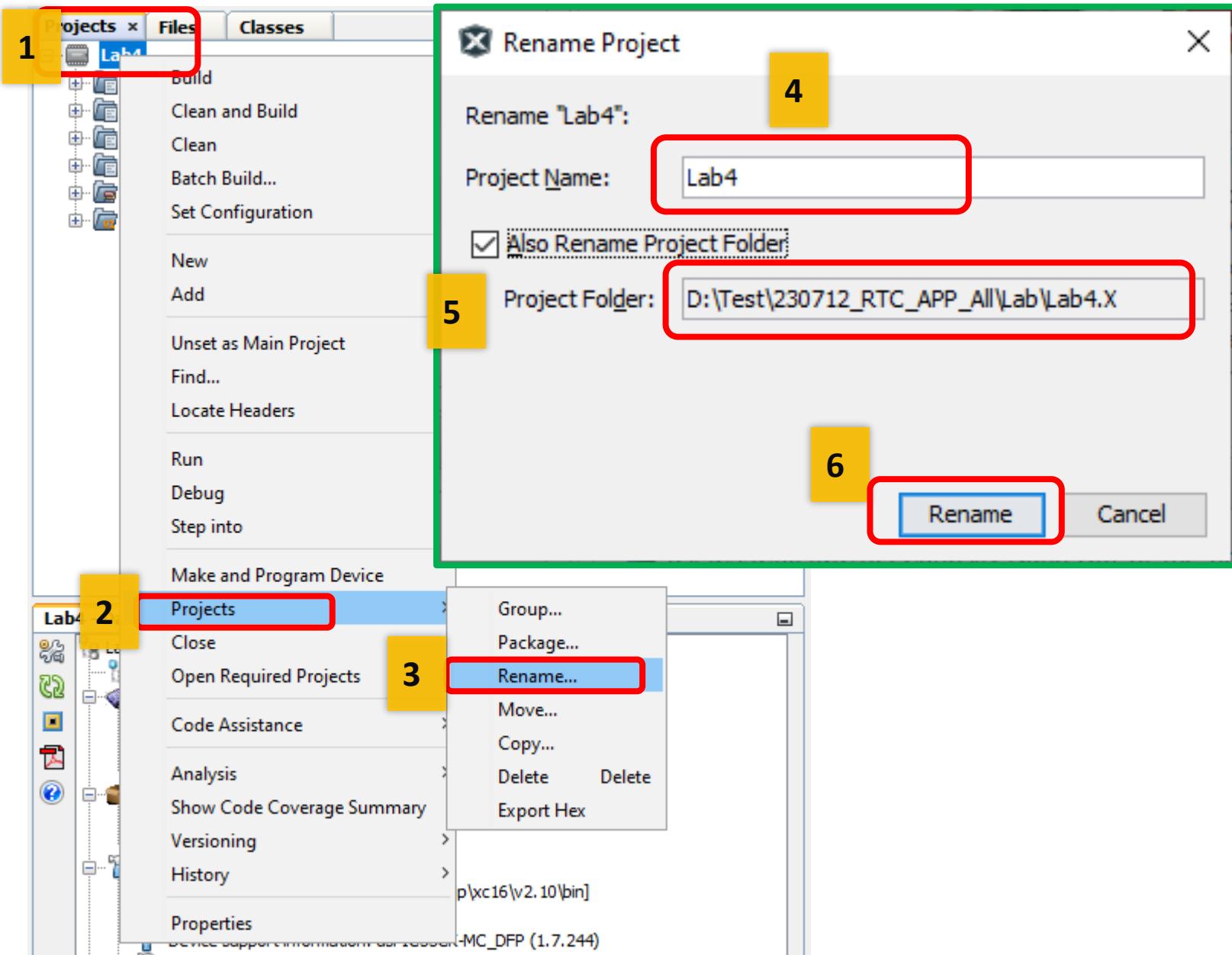


10100	UART3 RX Edge Detect
10101	UART3 TX Edge Detect
10111	Comparator 1 Output
11000–11110	Reserved
11111	None; Timer with Auto-Rollover (FFFFh → 0000h)

# 1. 建立Lab4

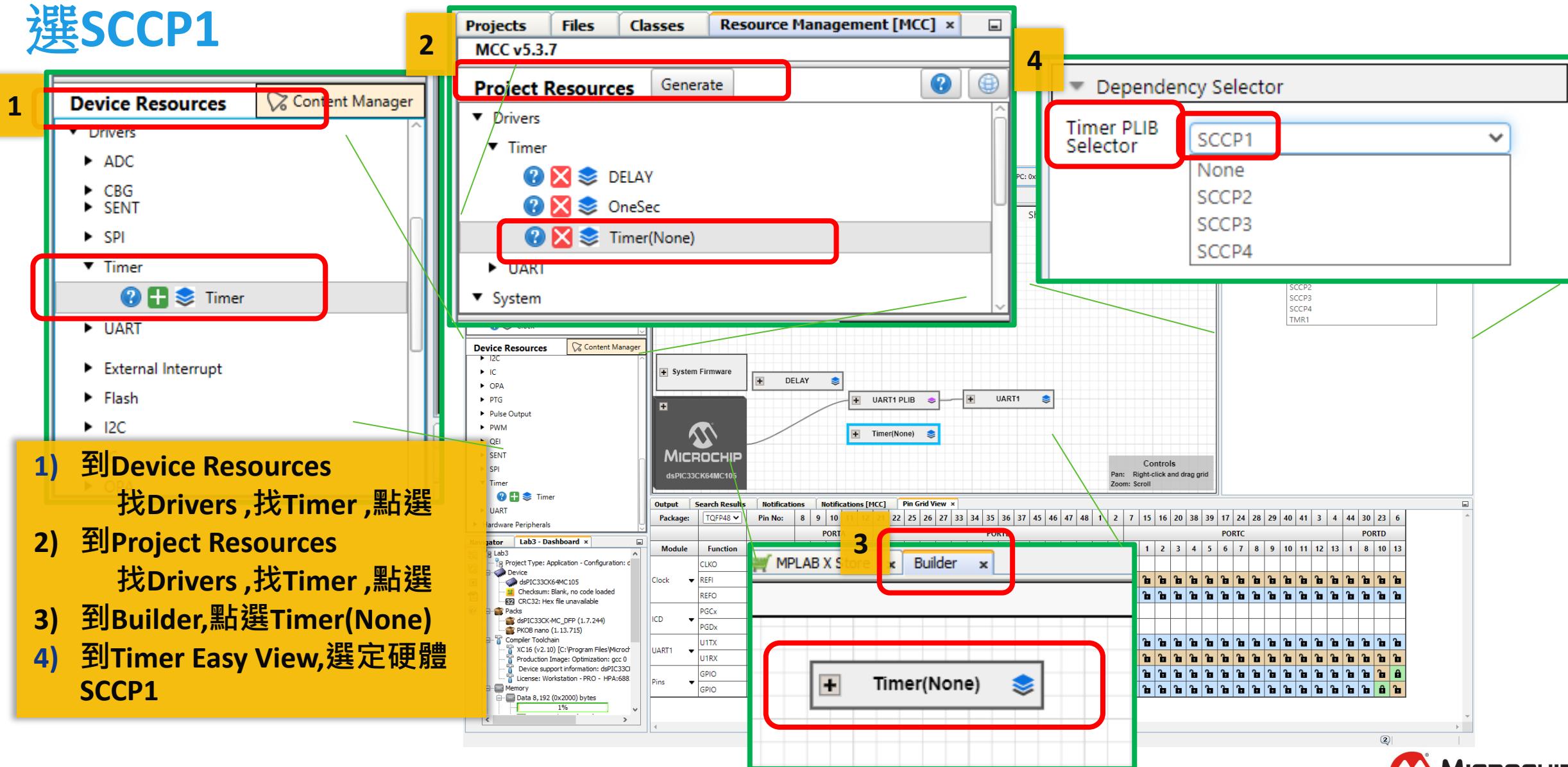
## 將Lab 3改名成Lab4

- 1) 到Projects 在Lab3上  
滑鼠點右鍵
- 2) 找到Projects
- 3) 找到Rename
- 4) 修改成Lab4
- 5) 勾選順便改資料夾名
- 6) 按 Rename - 完成名稱修改



## 2. 再加一組Timer

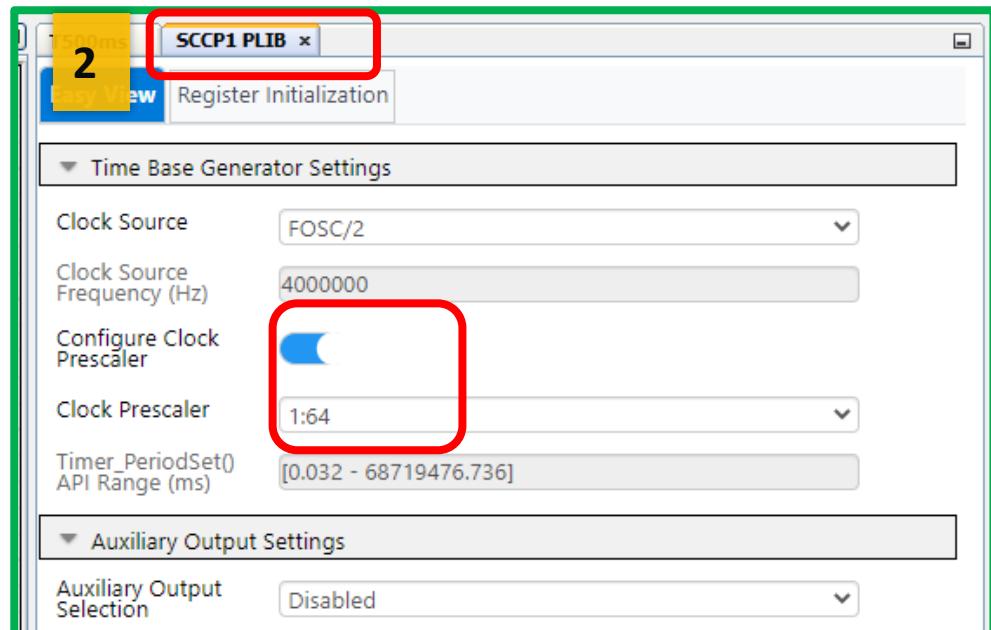
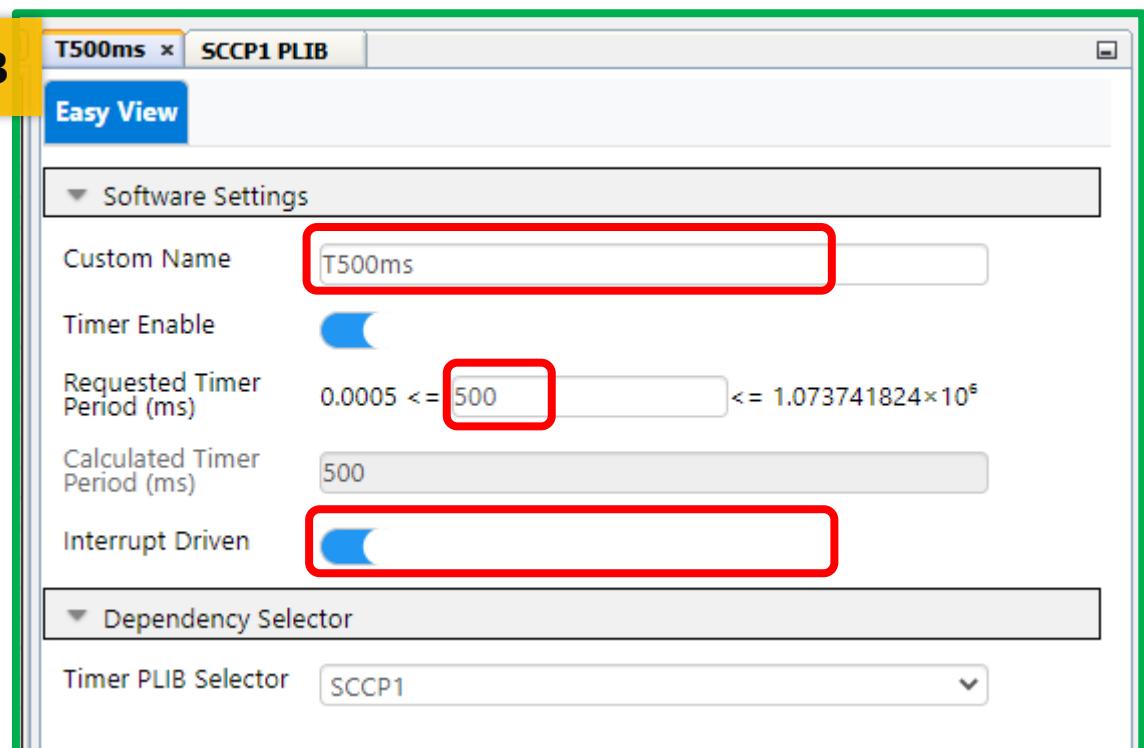
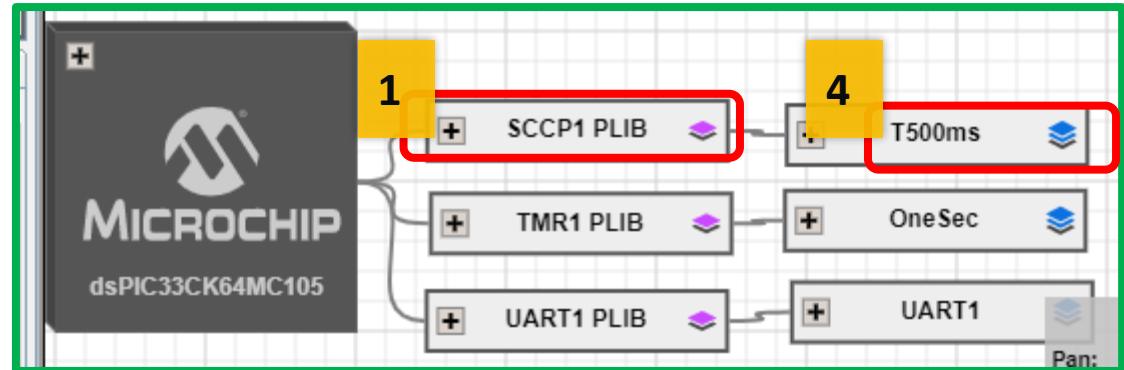
選SCCP1



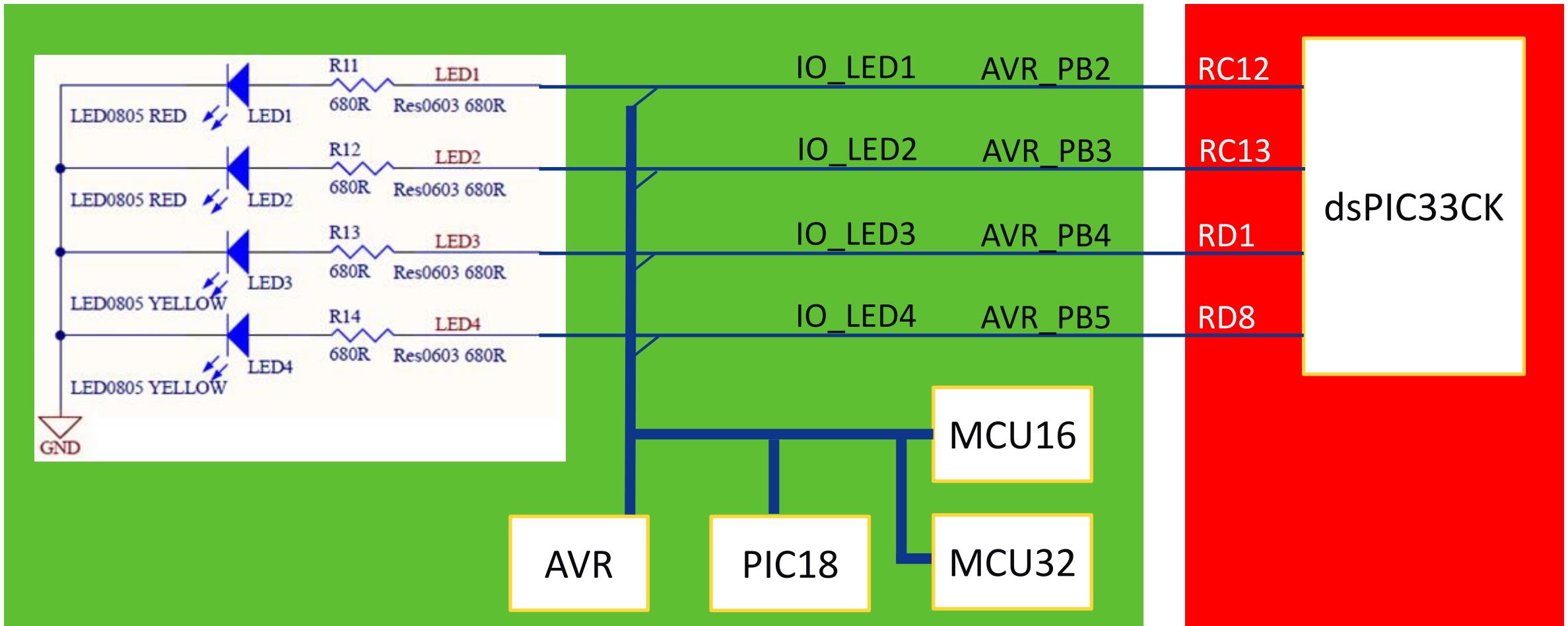
## 2. 設定SCCP

### 選SCCP1

- 1) 選SCCP1 PLIB
- 2) 設Clock Prescaler 1:64
- 3) 選Timer1 設 · Custom Name 改名 T500ms  
500ms , 開Interrupt
- 4) 名字連動成T500ms

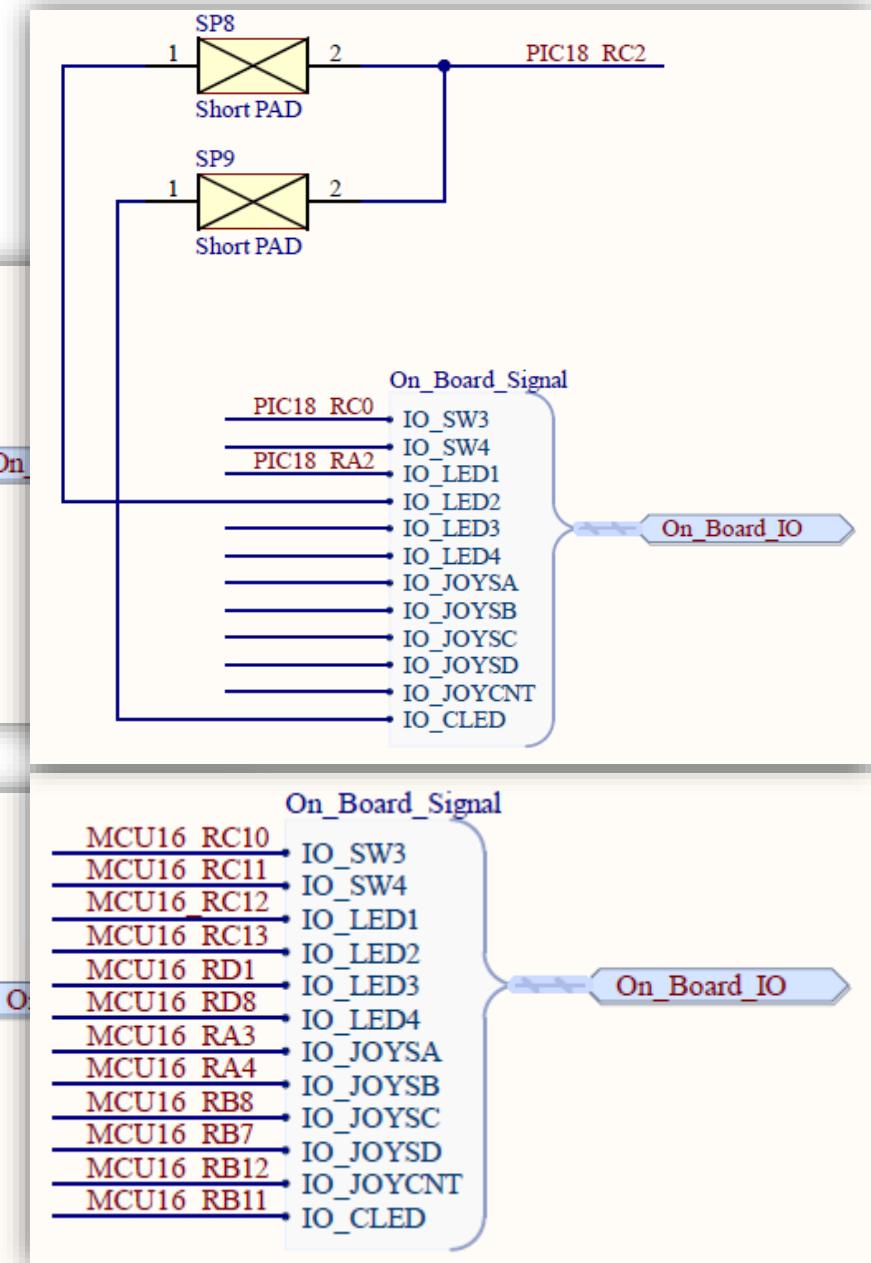
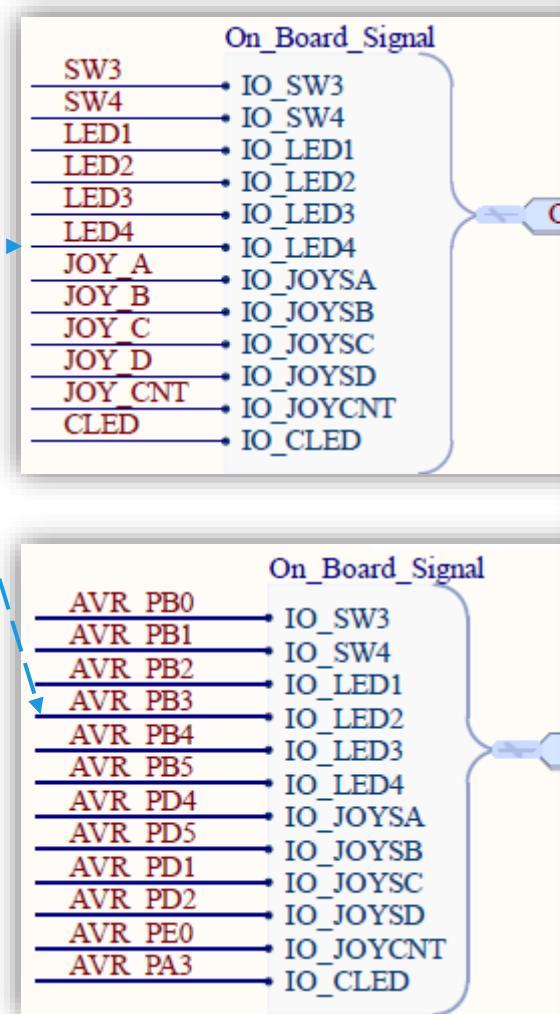
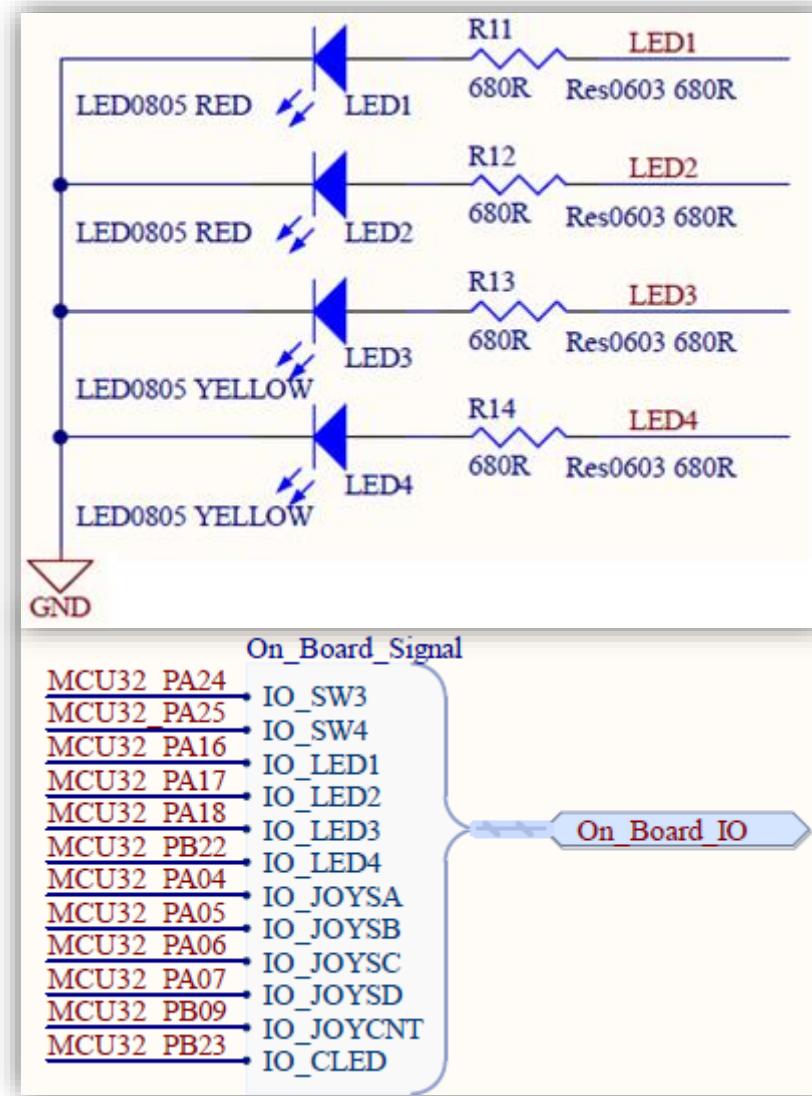


### 3. LED架構圖



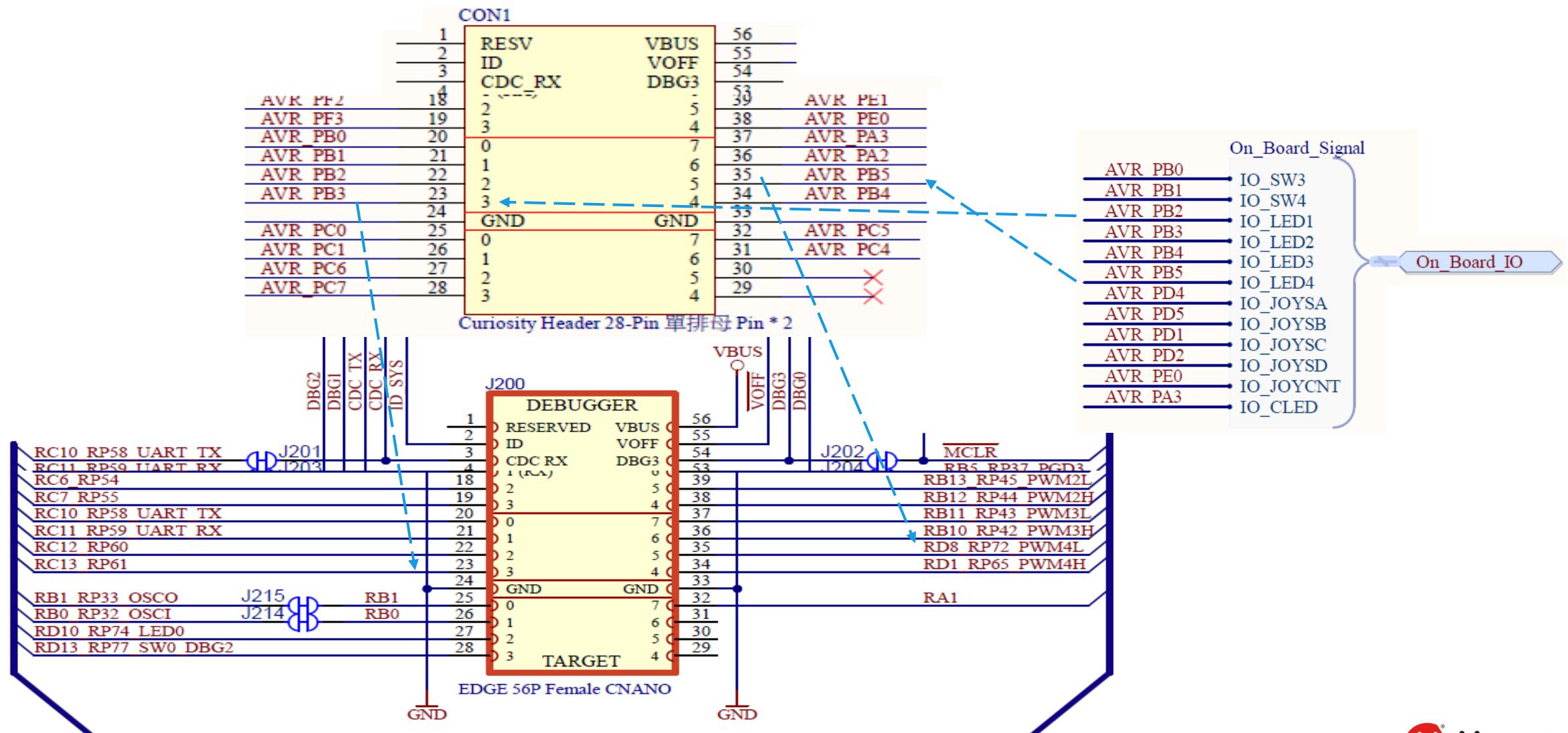
# 3-1. LED架構圖

## LED電路 (APP\_CuriosityNano2Arduino\_V20230315.pdf)



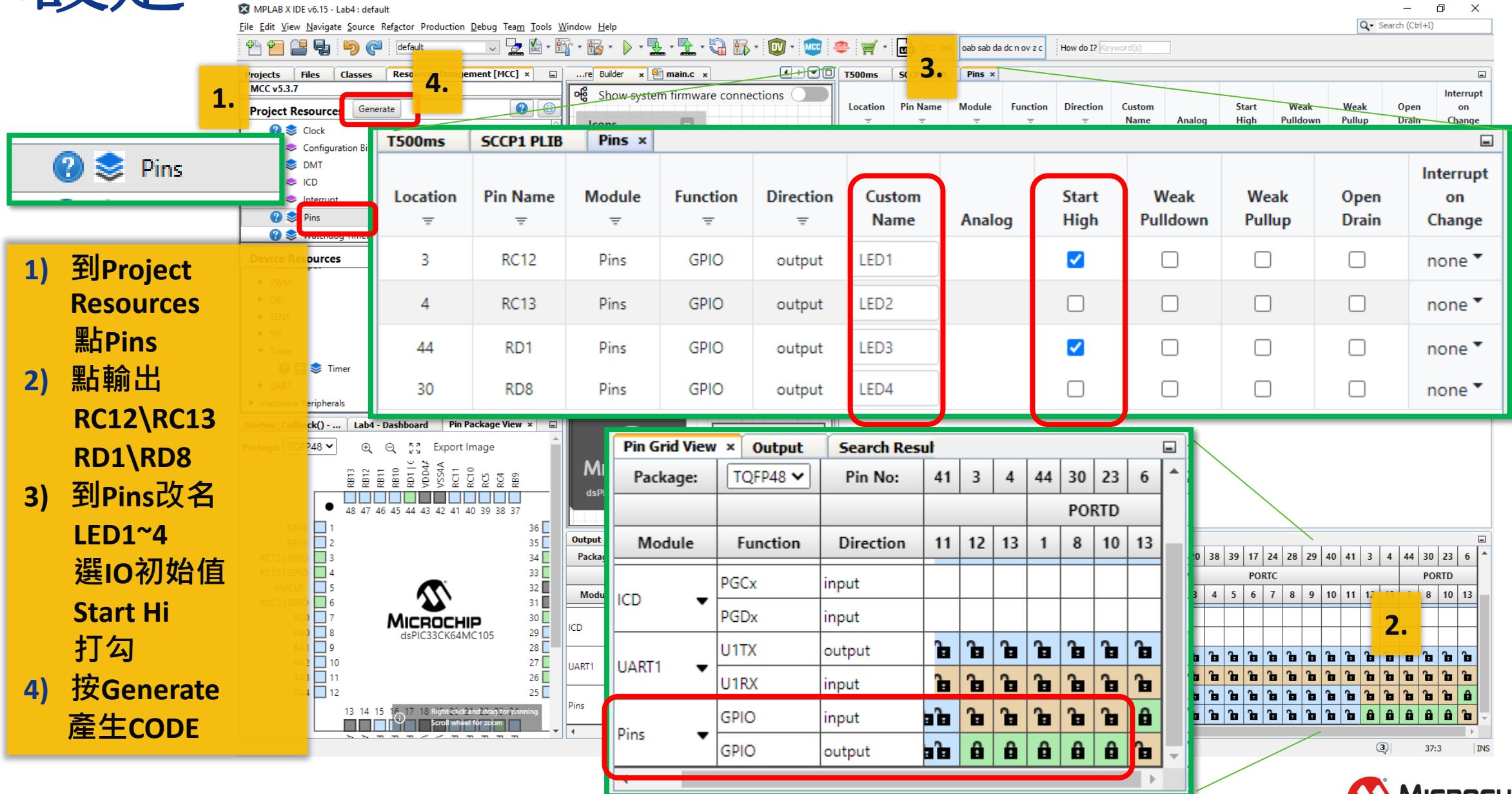
# 3-2. LED架構圖

LED電路 (APP\_CuriosityNano2Arduino\_V20230315.pdf \ dsPIC33CK64MC105\_Curiosity\_Nano\_Schematics )



# 4. 設定 LED

- 1) 到Project Resources  
點 Pins
- 2) 點輸出  
RC12\RC13  
RD1\RD8
- 3) 到 Pins 改名  
LED1~4  
選 IO 初始值  
Start Hi  
打勾
- 4) 按 Generate  
產生 CODE



# 5. 寫CODE

## sccp1.h

1) 在main.c

2) 開頭加入

#include "mcc\_generated\_files/timer/sccp1.h"

PS, 如果要讓printf(); 警告取消

加入#include <stdio.h>

```
Kit Window x Packs x Start Page x MPLAB X Store x main.c x Builder x
Source History | [File] [Edit] [Search] [Build] [Run] [Project] [Help]
14 KIND WHATSOEVER RELATED TO THE SOFTWARE, HOWEVER CAUS
15 MICROCHIP HAS BEEN ADVISED OF THE POSSIBILITY OR THE
16 LIABILITY THEREABLE. TO THE FULLEST EXTENT ALLOWED BY LAW, MI
17 TOTAL LIABILITY ON ALL CLAIMS RELATED TO THE SOFTWARE
18 IS AN AMOUNT OF FEES, IF ANY, YOU PAID DIRECTLY TO M
19 THIS SOFTWARE.
20
21 #include "mcc_generated_files/system/system.h"
22 #include "mcc_generated_files/system/pins.h"
23 #include "mcc_generated_files/timer/delay.h"
24 #include "mcc_generated_files/timer/tmr1.h"
25 #include "mcc_generated_files/timer/sccp1.h"  
26
27 -#include <stdio.h>  
28
29 /* Main application
30 */
31
```

```
66
67
68
```

```
printf("Lab4-1 \r\n");
```

# 5-1. 寫Code

- ## 1) 繼續在 main.c

## 2) 加入

T500ms TimeoutCallbackRegister(T500ms CallBack);

3) 改 printf("dsPIC33: Lab4\r\n");

## 4) 加入

```
void T500ms_CallBack( void )  
{  
    LED1_Toggle();  
    LED2_Toggle();  
    LED3_Toggle();  
    LED4_Toggle();  
}
```

5) 燒錄

1. main.c

```
Kit Window x Packs x Start Page x MPLAB X Store x Builder x
Source History              
```

```
34     DELAY_milliseconds(100);
35     LED0_SetHigh();
36 }
37 }

38 void T500ms_CallBack( void )
39 {
40     LED1_Toggle();
41     LED2_Toggle();
42     LED3_Toggle();
43     LED4_Toggle();
44 }

45 }

46

47 int main(void)
48 {
49     SYSTEM_Initialize();
50
51     OneSec_TimeoutCallbackRegister(OneSec_Callback);
52     T500ms_TimeoutCallbackRegister(T500ms_CallBack);
53
54     printf("dsPIC33: Lab4\r\n");
55
56     while(1)
57     {
58         //          TMR1_Tasks();
59     }
60 }
```

2.

3.

4.

# 6.結果

## Lab4

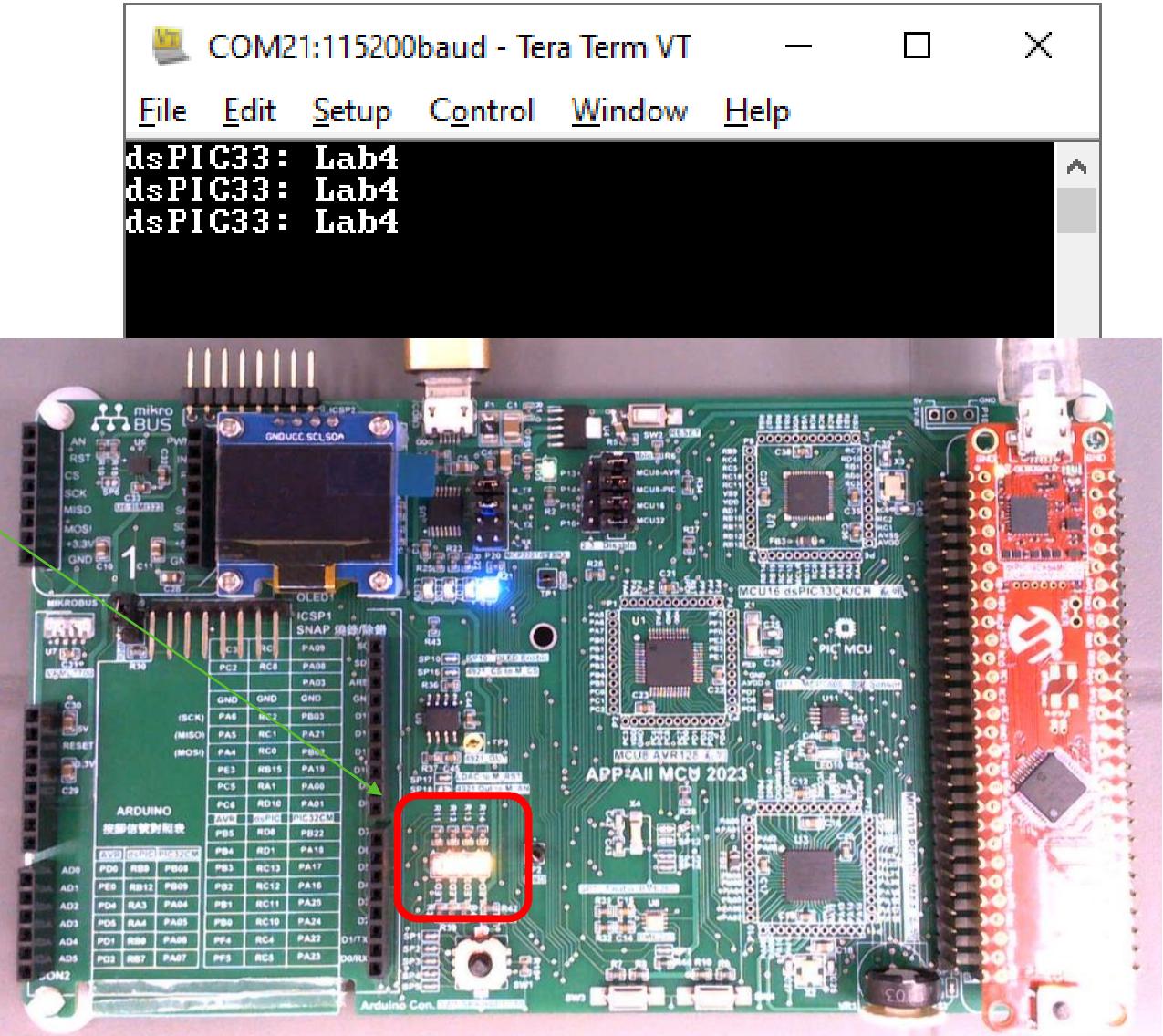
### 1) 燒錄測試

### 2) 成果

綠板上LED1~4交互閃爍

PC顯示 **dsPIC33: Lab4**

LED0 持續一秒閃一下



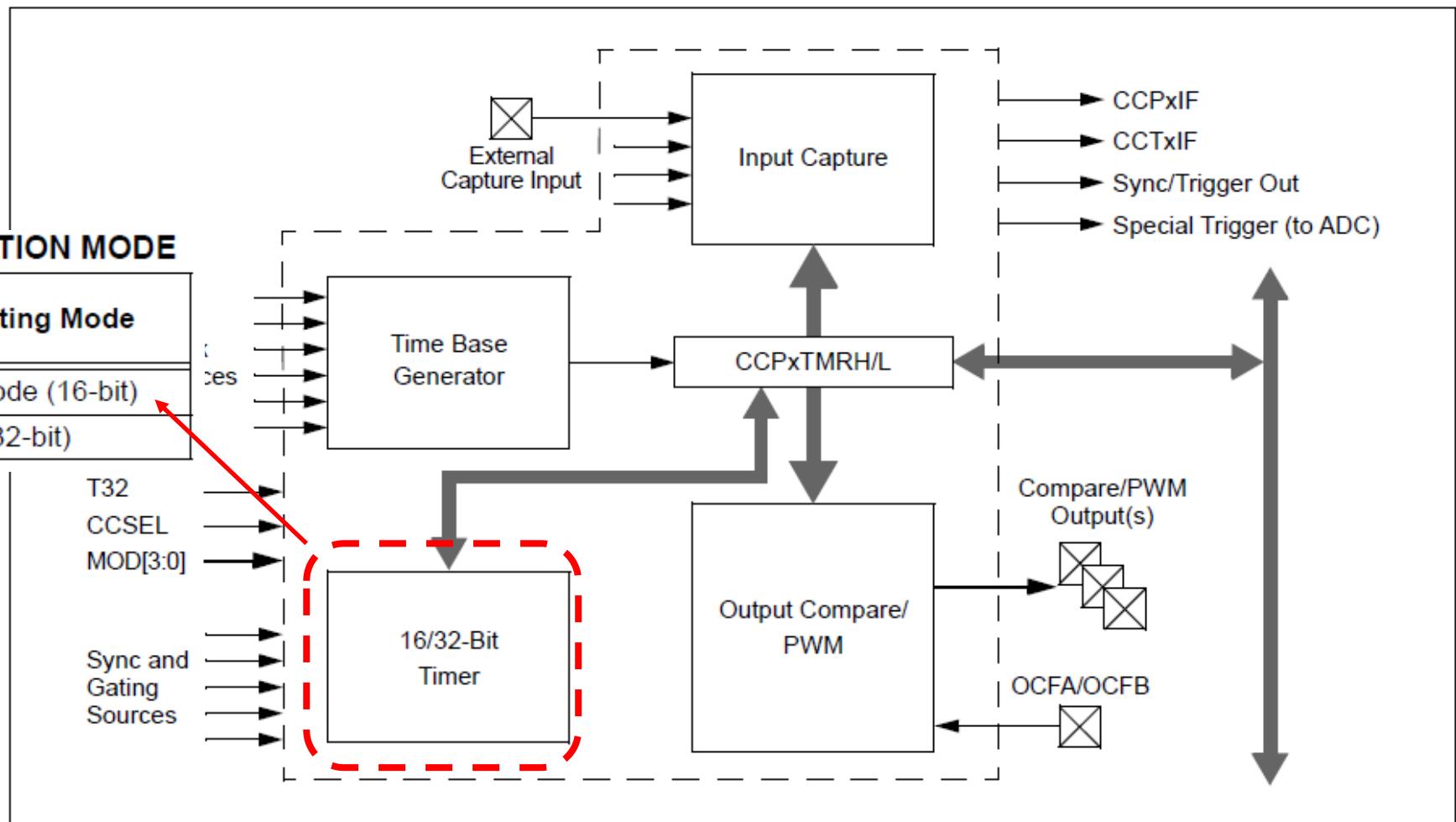
# 7. 改成Timer x 2

SCCP(Single Output Capture/Compare/PWM/Timer modules)

FIGURE 20-1: SCCPx CONCEPTUAL BLOCK DIAGRAM

TABLE 20-1: TIMER OPERATION MODE

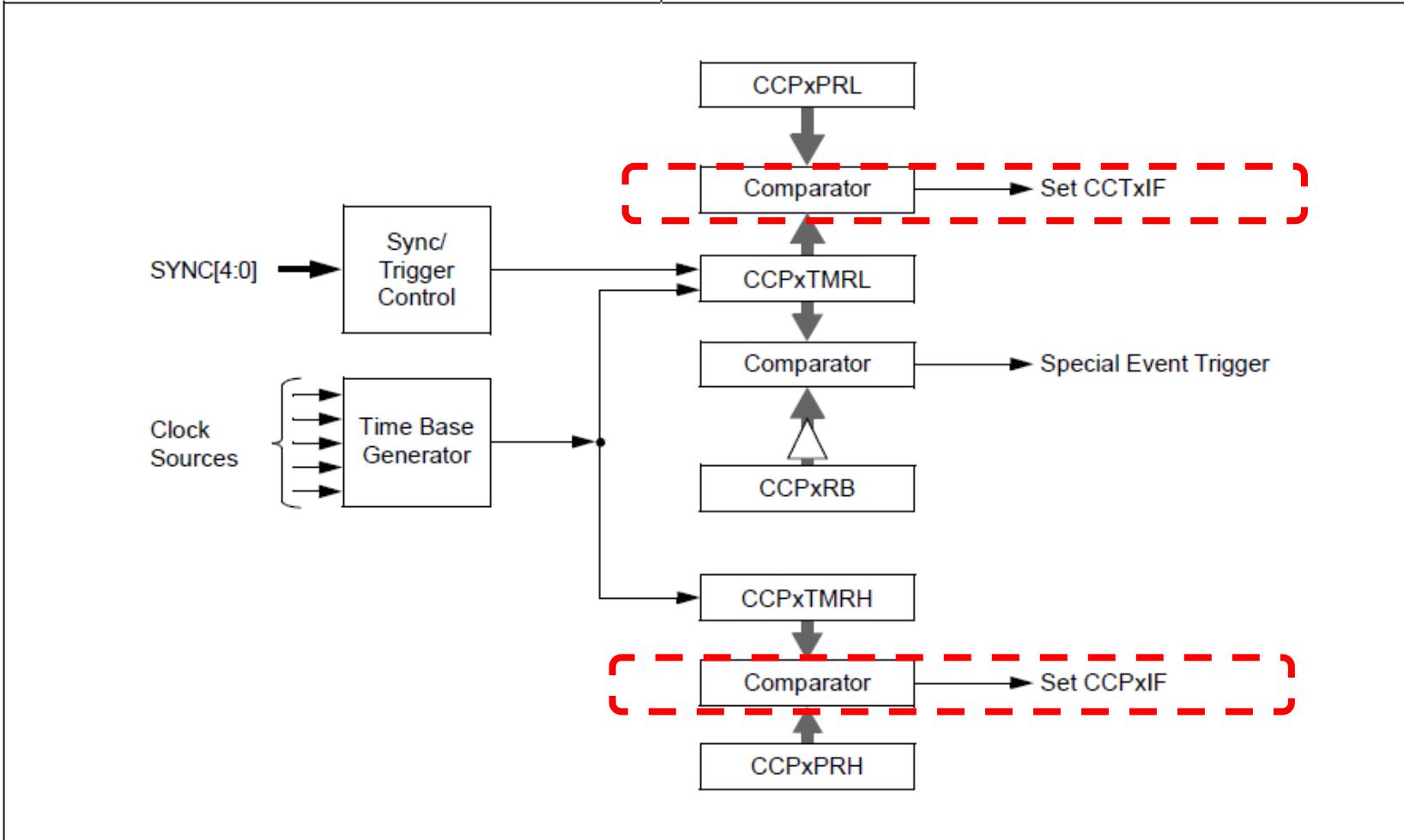
T32 (CCPxCON1L[5])	Operating Mode
0	Dual Timer Mode (16-bit)
1	Timer Mode (32-bit)



# 7-1. 改成 Timer x 2

## SCCP設定成：兩個16-bit 計時器

FIGURE 20-3: DUAL 16-BIT TIMER MODE



# 8. 設定第二組Timer – 125ms

## 改暫存器

1) 到main.c

2) 修改void T500ms\_CallBack( void )  
讓出兩個LED剩

```
LED1_Toggle();  
LED2_Toggle();
```

3) 到SYSTEM\_Initialize();後  
根據啟動第二組Timer

```
SCCP1_Timer_Stop();  
CCP1CON1Lbits.T32 = 0;  
CCP1PRH = (0x7A11>>2);  
IFS0bits.CCP1IF = 0;  
IEC0bits.CCP1IE = 0;  
SCCP1_Timer_Start();
```

4) 改printf("dsPIC33: Lab4-1\r\n");

5) 到while(1){ }中  
if(IFSObits.CCP1IF==1)  
{  
 IFS0bits.CCP1IF = 0;  
 LED3\_Toggle();  
 LED4\_Toggle();  
}

6) 燒錄 



The screenshot shows the MPLAB X IDE interface with the main.c file open. The code is as follows:

```
...re Builder x main.c x p1.c x system.c x sccp1.h x p33CK  
Source History   
39  
40     void T500ms_CallBack( void )  
41     {  
42         LED1_Toggle();  
43         LED2_Toggle();  
44     }  
45  
46     int main(void)  
47     {  
48         SYSTEM_Initialize();  
49  
50         SCCP1_Timer_Stop();  
51  
52         CCP1CON1Lbits.T32 = 0;  
53         CCP1PRH = (0x7A11>>2);  
54         IFS0bits.CCP1IF = 0;  
55         IEC0bits.CCP1IE = 0;  
56  
57         SCCP1_Timer_Start();  
58  
59         OneSec_TimeoutCallbackRegister(OneSec_Callback);  
60         T500ms_TimeoutCallbackRegister(T500ms_CallBack);  
61  
62         printf("dsPIC33: Lab4-1\r\n");  
63  
64         while(1)  
65         {  
66             if(IFSObits.CCP1IF==1)  
67             {  
68                 IFS0bits.CCP1IF = 0;  
69                 LED3_Toggle();  
70                 LED4_Toggle();  
71             }  
72         }  
73     }
```

Callouts numbered 1 through 5 point to specific lines of code:

- 1. Line 40: `void T500ms_CallBack( void )`
- 2. Line 43: `LED2_Toggle();`
- 3. Line 53: `CCP1PRH = (0x7A11>>2);`
- 4. Line 62: `printf("dsPIC33: Lab4-1\r\n");`
- 5. Line 68: `LED4_Toggle();`

# 9. 結果

# Lab4-1

## 1) 燒錄測試

## 2) 結果

小板上

# LEDO閃爍 1Hz

大板上

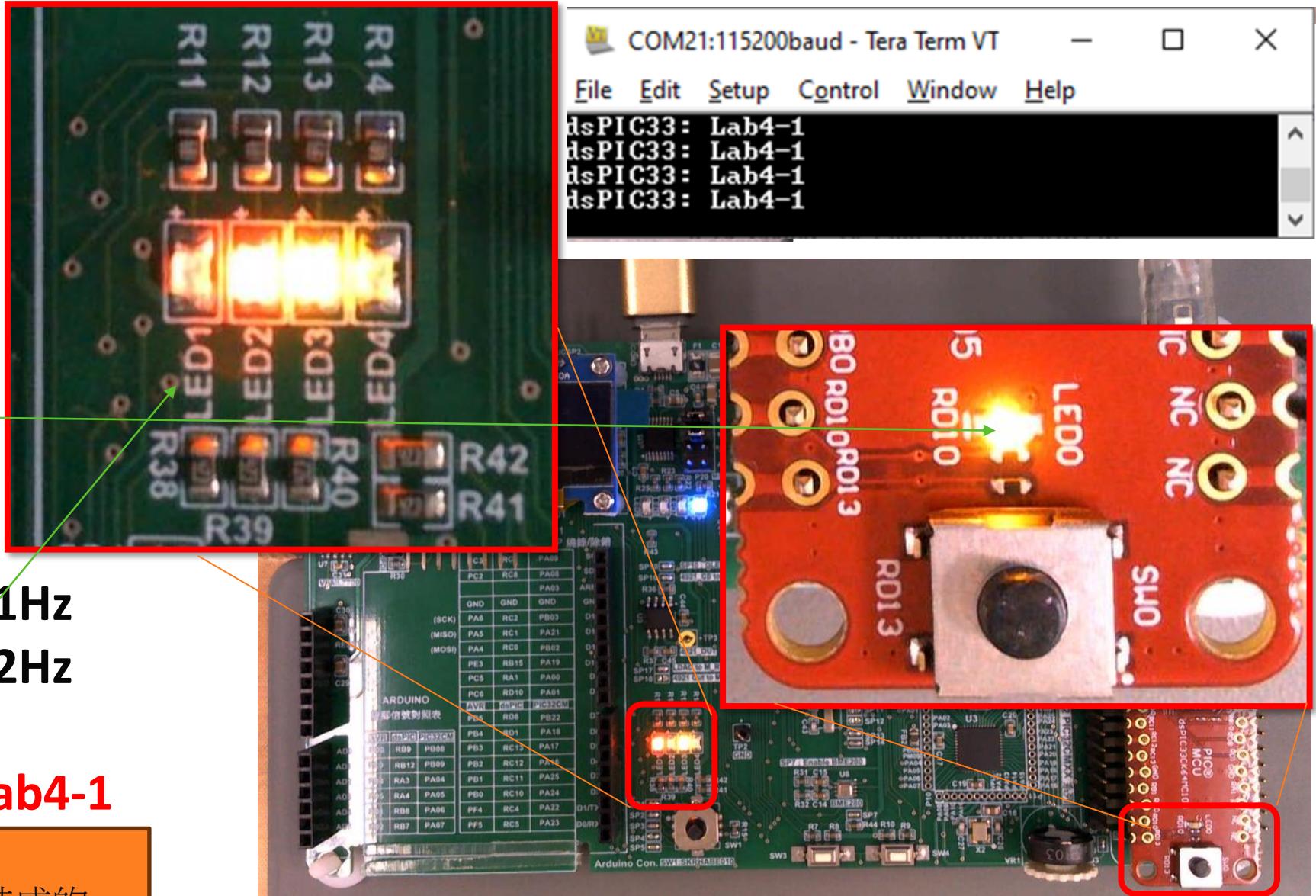
**LED1~2交互慢閃 1Hz**

# LED3~4交互快閃 2Hz

# PC顯示 dsPIC33: Lab4-1

## LED1 會頓一下？

是因為LED0 delay 100ms造成的



# 10. 刪100ms Delay

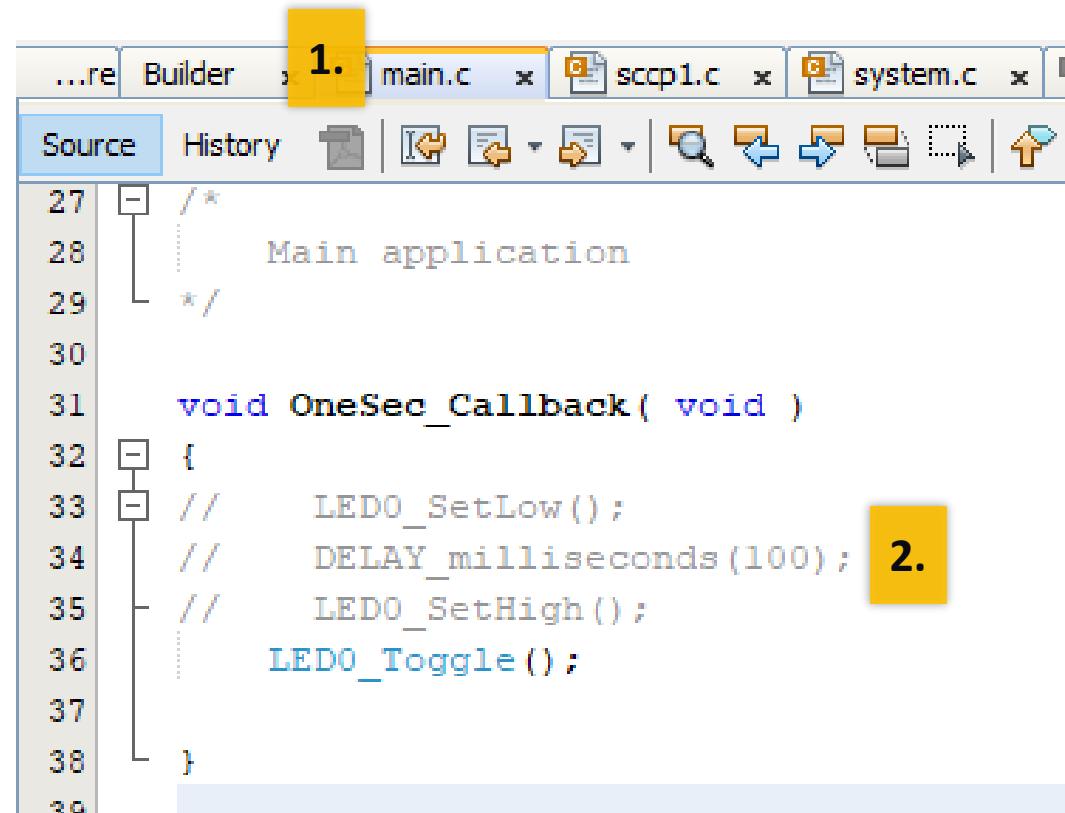
再看一次結果

1) 到main.c

2) 修改

```
void OneSec_Callback( void )
{
    // LED0_SetLow();
    // DELAY_milliseconds(100);
    // LED0_SetHigh();
    LED0_Toggle();
}
```

1.



```
...re Builder 1. main.c x scop1.c x system.c x
Source History
27  /* Main application
28  */
29  */
30
31  void OneSec_Callback( void )
32  {
33  // LED0_SetLow();
34  // DELAY_milliseconds(100); 2.
35  // LED0_SetHigh();
36  LED0_Toggle();
37
38 }
```

# 實驗五

---

Clock

# 內建硬體程式開發

## 實驗五：Clock

- 本實驗目的：
  - 了解Clock架構
    - 如何改變System Clock 設定
    - 了解Clock 對 Timer及UART影響
    - 在不同的Clock設定下，達到所需功能
- 結果呈現：
  - UART 115200-8-N-1
  - LED0 亮1 Hz
  - LED1,2 亮1 Hz
  - LED3,4 亮2 Hz

# 背景知識

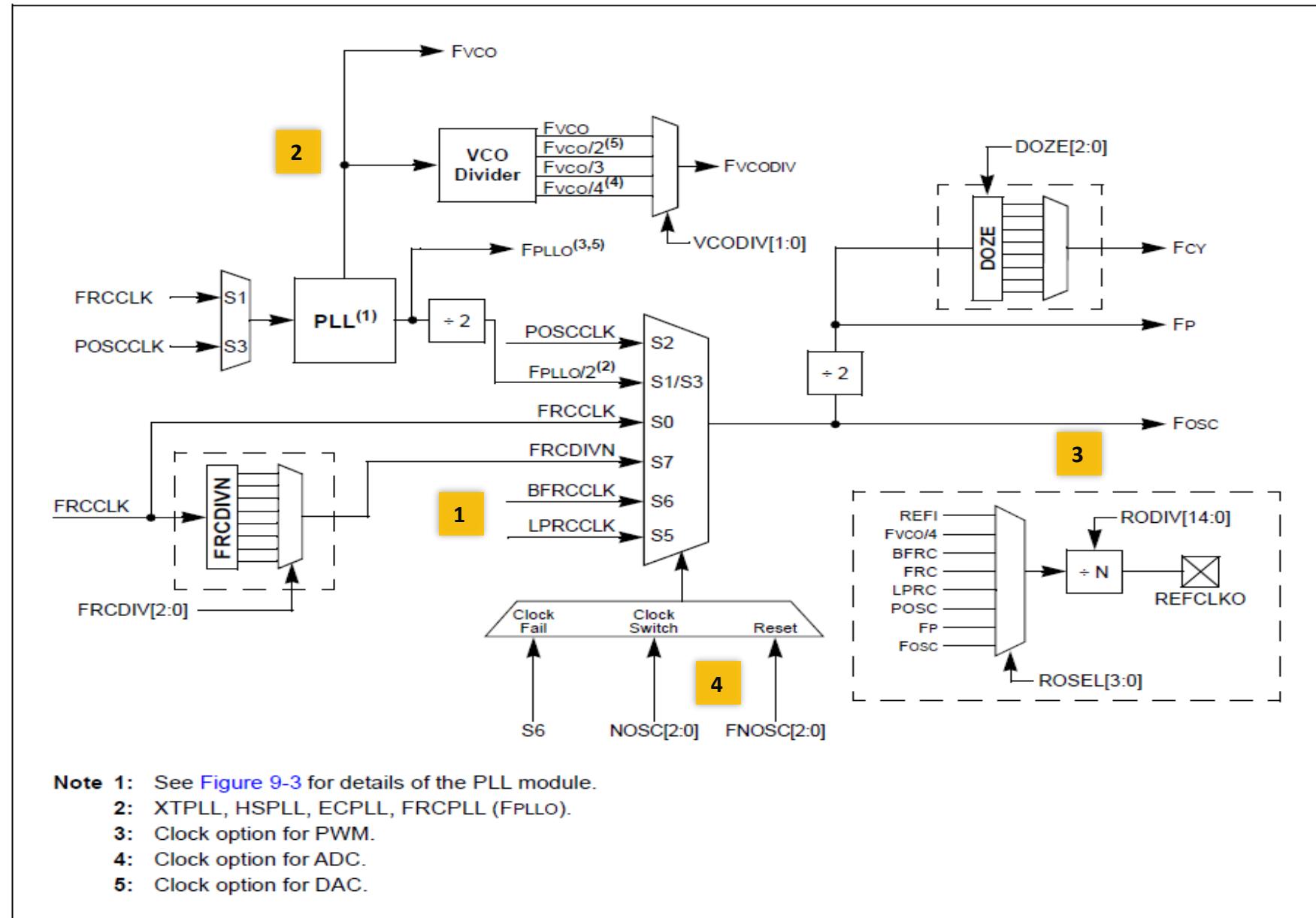
---

dsPIC33CK datasheet

# Clocks架構

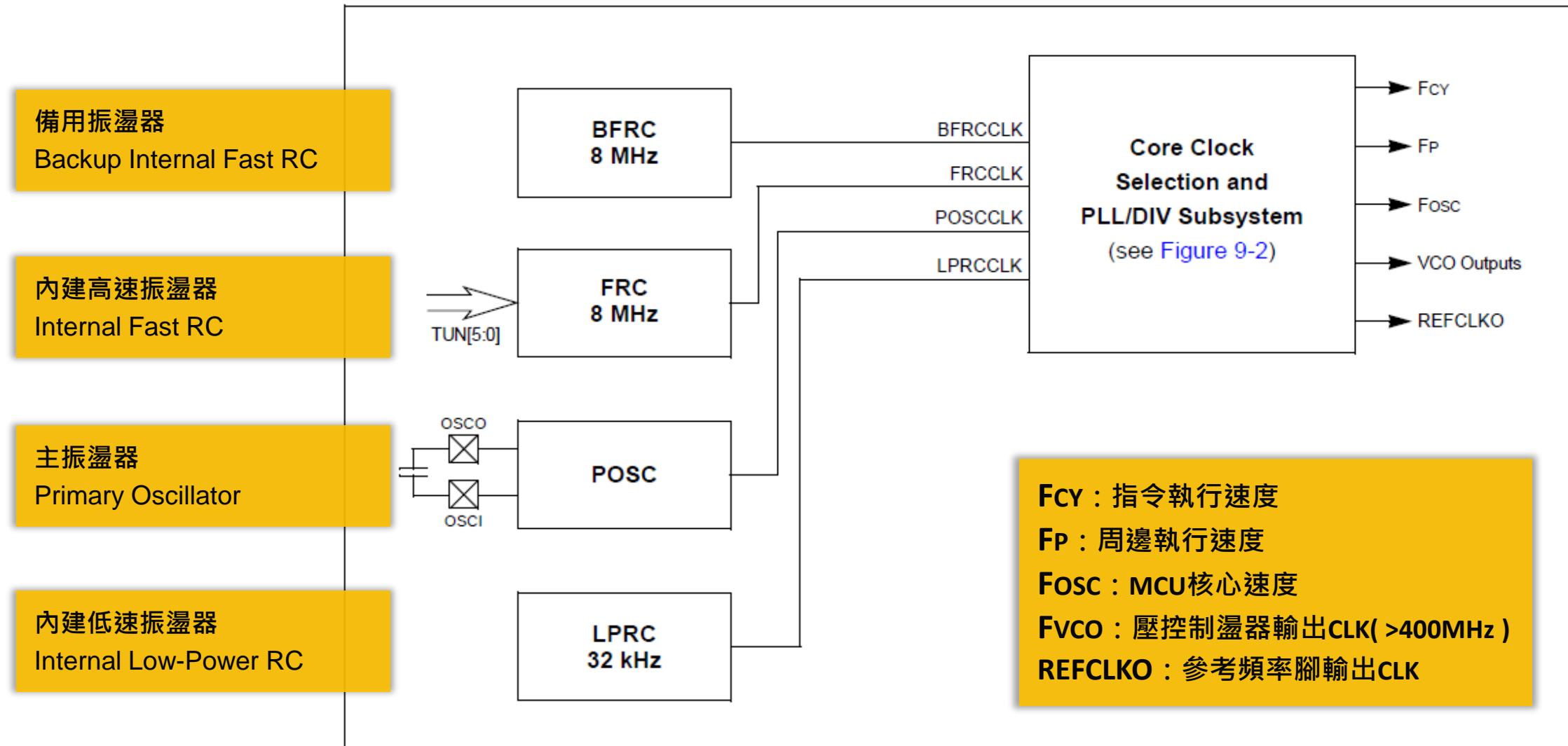
1. 具有多種不同輸入
2. 內含PLL電路  
用來除頻及倍頻
3. 硬體模組  
(Timer,PWM...)  
可選不同時脈來源
4. 軟體運行中  
可以切換Clock

FIGURE 9-2: dsPIC33CK64MC105 CORE OSCILLATOR SUBSYSTEM

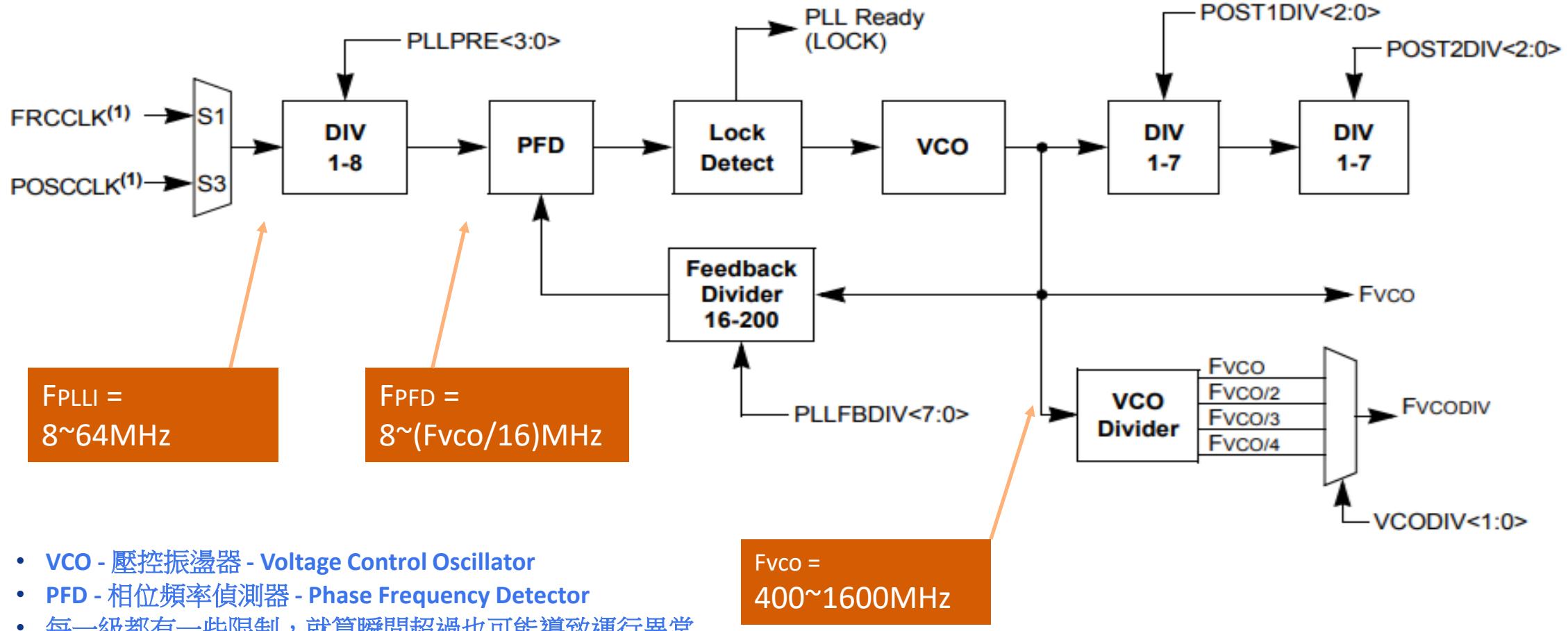


# Clock 來源

FIGURE 9-1: dsPIC33CK64MC105 CORE CLOCK SOURCES BLOCK DIAGRAM



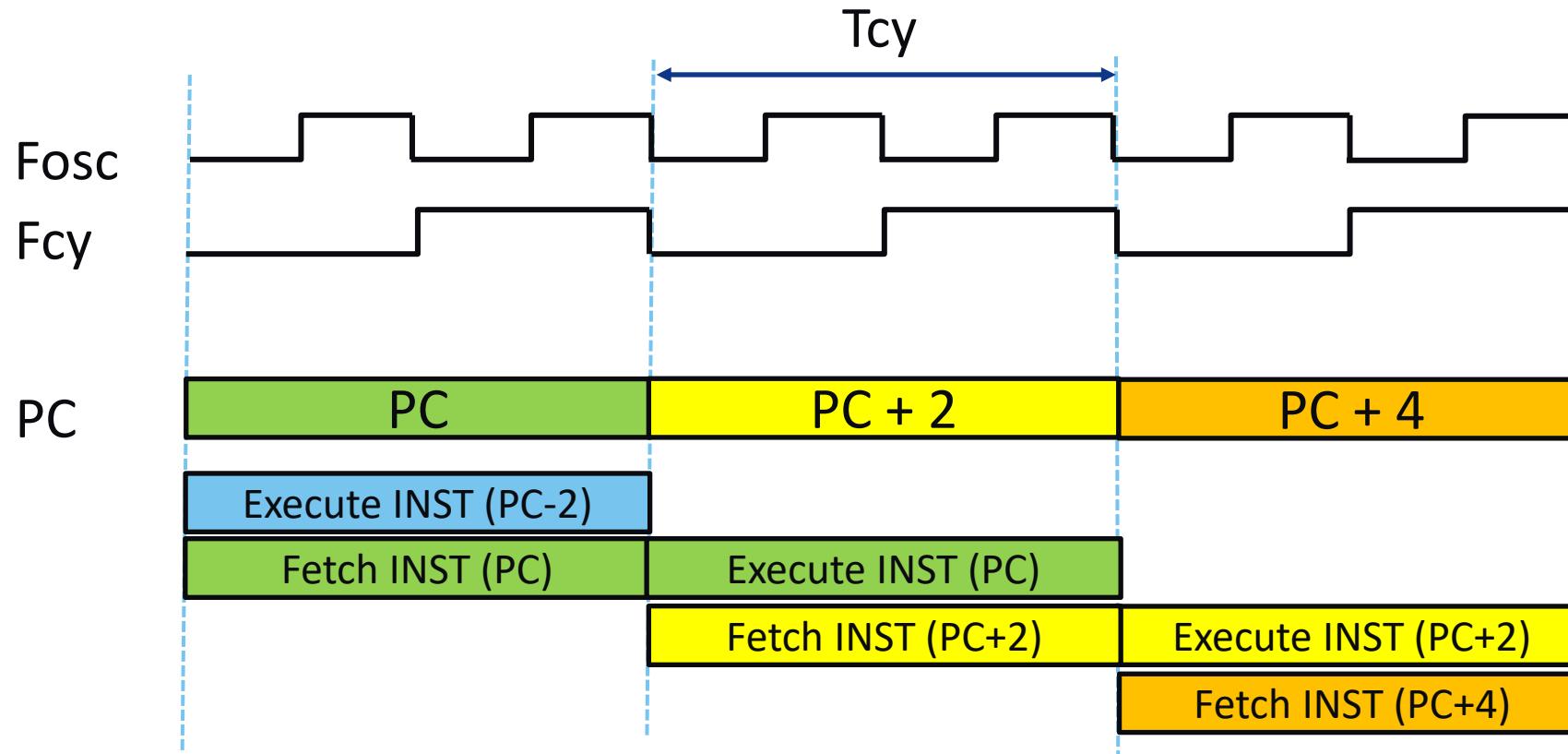
# 鎖相迴路(PLL)方塊圖



- VCO - 壓控振盪器 - Voltage Control Oscillator
- PFD - 相位頻率偵測器 - Phase Frequency Detector
- 每一級都有一些限制，就算瞬間超過也可能導致運行異常

# dsPIC33C 指令執行流程

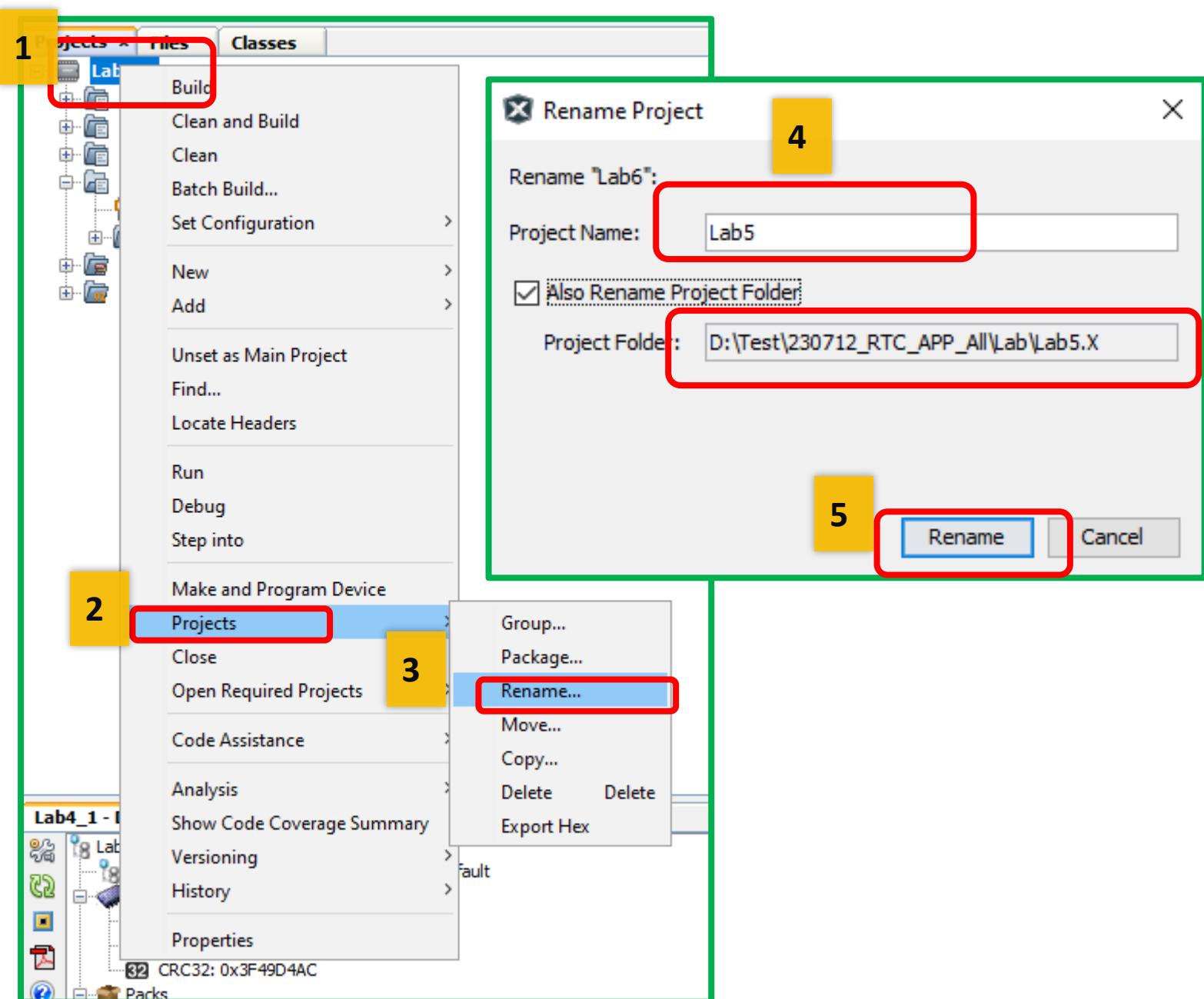
兩個震盪器的時脈 完成一個指令週期



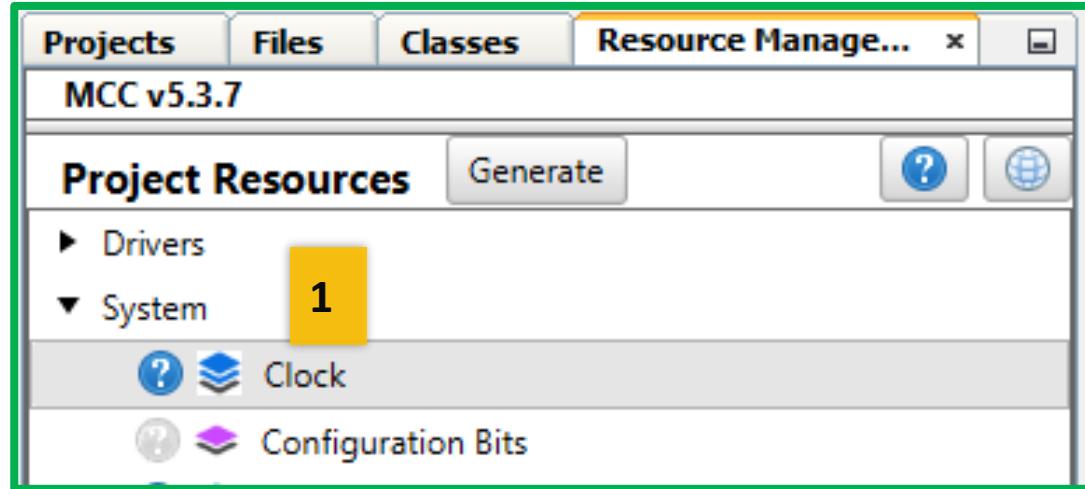
# 1. 建立Lab4

## 將Lab 4改名成Lab5

- 1) 到Projects 在Lab4上  
滑鼠點右鍵
- 2) 找到Projects
- 3) 找到Rename
- 4) 勾選順便改資料夾名
- 5) 按 Rename - 完成名稱修改



## 2. 開啟MCC 觀察預設值= FRC , 8MHz



- 1) 到Project Resources  
找System ,找Clock ,點選
- 2) 到Clock的 Easy View

The screenshot shows the MCC software's Clock Easy View configuration window. The top navigation bar includes Watchdog Timer, Clock (highlighted with a yellow box and labeled '2'), Interrupt, and DMT. The main area is titled 'Easy View' and contains two sections: 'System Clock' and 'Reference Clock'.  
**System Clock:**

- System Clock Source: FRC Oscillator
- Set System(FOSC) Frequency to Maximum: Toggle switch
- Calculated System Frequency(FOSC): 8.00 MHz (highlighted with a yellow box)
- Calculated Peripheral Frequency(FOSC/2): 4.00 MHz (highlighted with a yellow box)
- PLL Output Frequency(FPLO): 1200.00 MHz
- VCO Frequency(FVCO): 1200.00 MHz
- FVCO Divider: 4
- VCO Divider Frequency(FVCODIV): 300.00 MHz

**Reference Clock:**

- Reference Clock Enable: Toggle switch (highlighted with a yellow box)
- REFO Clock Source: FOSC
- Requested REFO Frequency(in Hz): 8000000 (highlighted with a yellow box)
- Calculated REFO Frequency: 0.00 kHz (highlighted with a yellow box)

# 3. 修改Fosc到最快 FRC , 200MHz

- 1) System Clock Source  
選內部震盪 FRC +升頻 PLL
- 2) 請MCC根據此Clock來源  
設到Fosc跑最快
- 3) 設REFO輸出頻率，填500MHz  
根據實際輸出顯示只有100MHz
- 4) 產生CODE

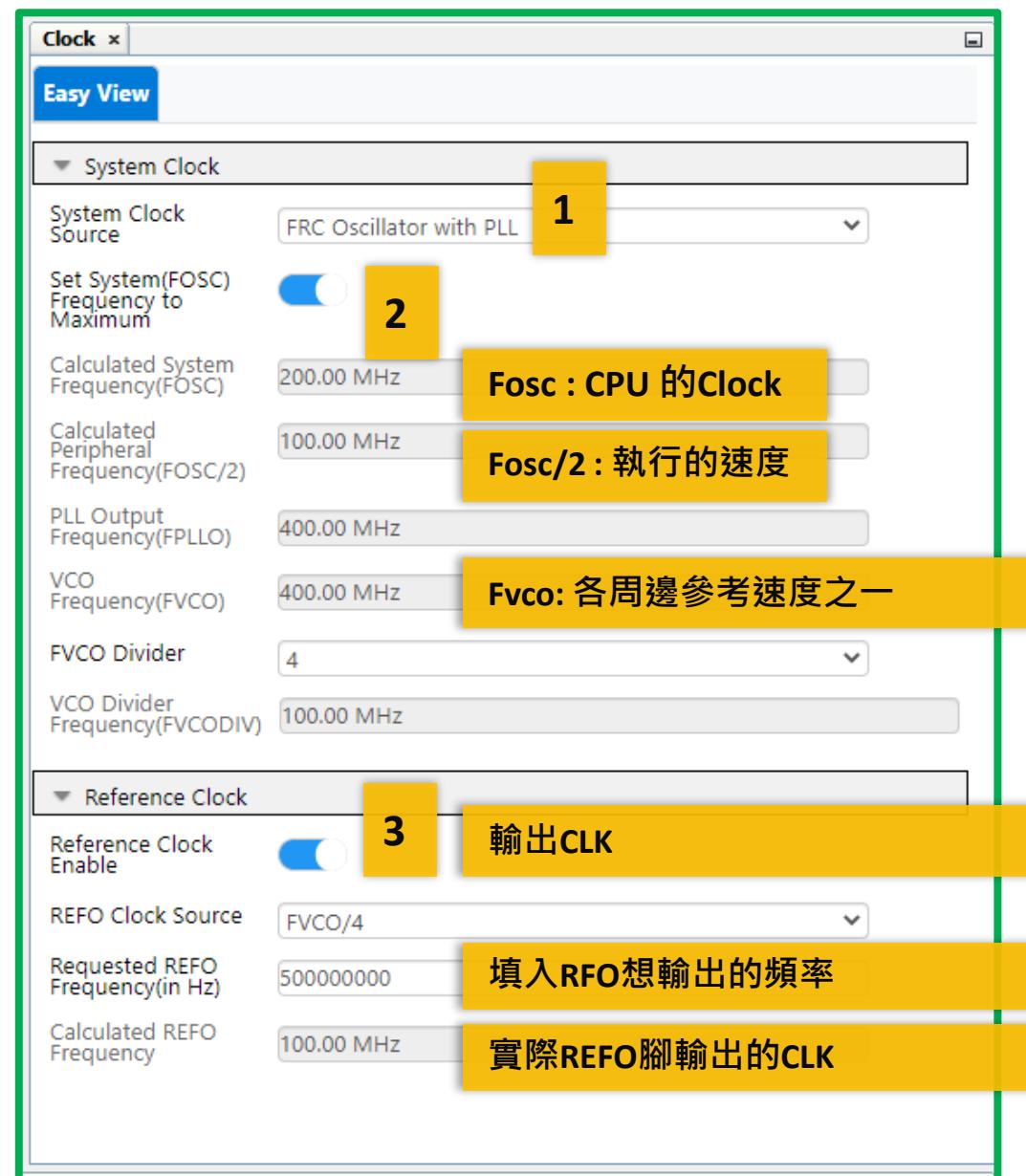
## 分析

上一步跟新設定後MCC內容

Fosc 8 MHz -> 200 MHz

Fvco 1200 MHz -> 400 MHz

REFO 0 MHz -> 100 MHz



# 4.結果

## Lab5

### 1) 燒錄測試

### 2) 結果

小板上

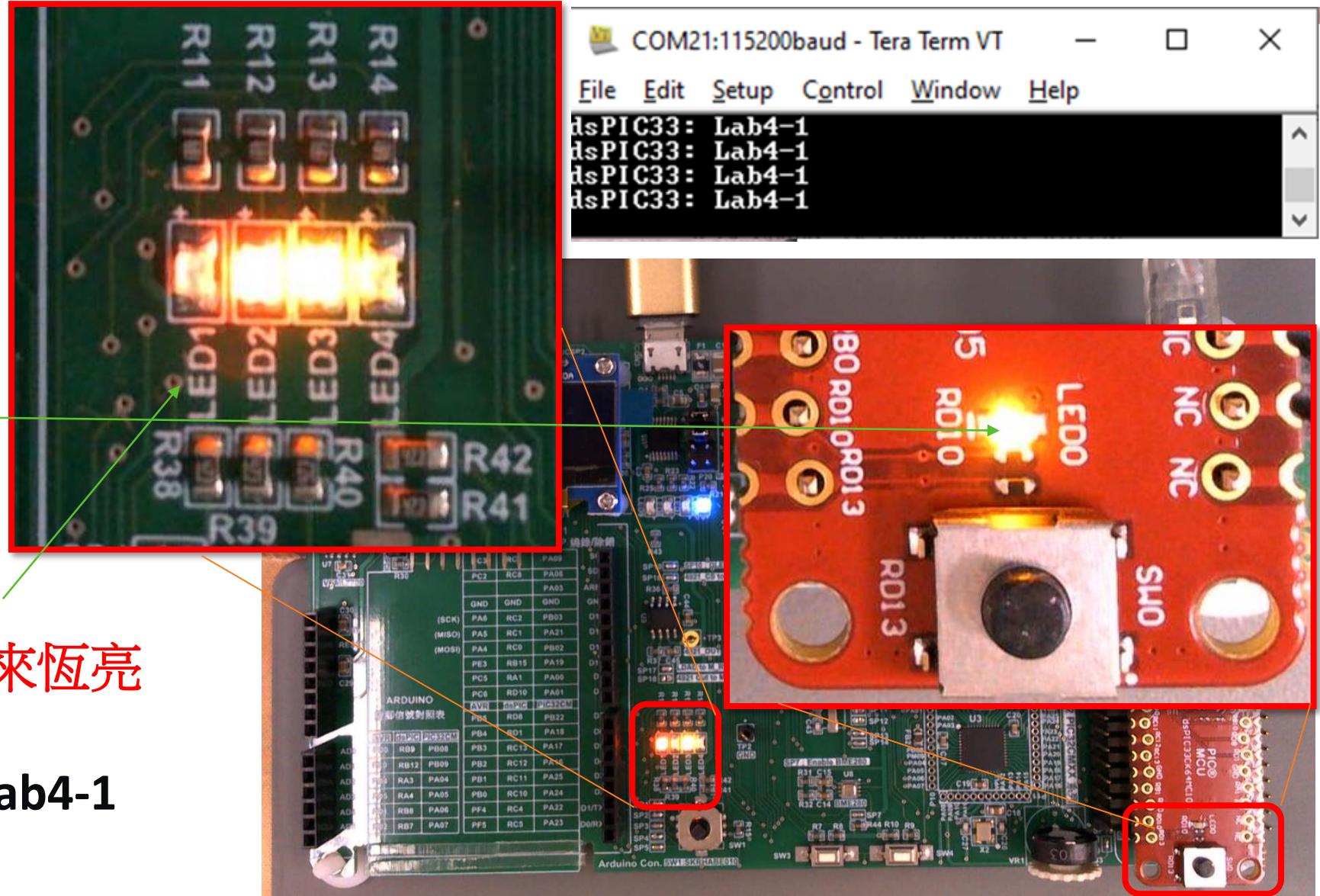
LED0看起來恆亮

大板上

LED1~2交互快閃

LED3~4交互看起來恆亮

PC顯示 dsPIC33: Lab4-1



# 5. 修正LED0 因MCU時脈變快造成

## 1) 查看OneSec設定

發現出現警告並告知**實際 0ms**

## 2) 開啟TMR1 PLIB

改變時脈來源

$FOSC/2 = 100 \text{ MHz} \rightarrow FRC 8 \text{ MHz}$

## 3) 查看OneSec變化

2

Easy View	Register Initialization
<b>Clock Settings</b>	<b>Clock Settings</b>
Clock Source: FOSC/2	Clock Source: FRC
Clock Source Frequency (Hz): 100000000	Clock Source Frequency (Hz): 8000000
Configure Clock Prescaler: On	Configure Clock Prescaler: On
Timer_PeriodSet() API Range (ms): [0.00002 - 0.65]	Timer_PeriodSet() API Range (ms): [0.064 - 2097.152]

1

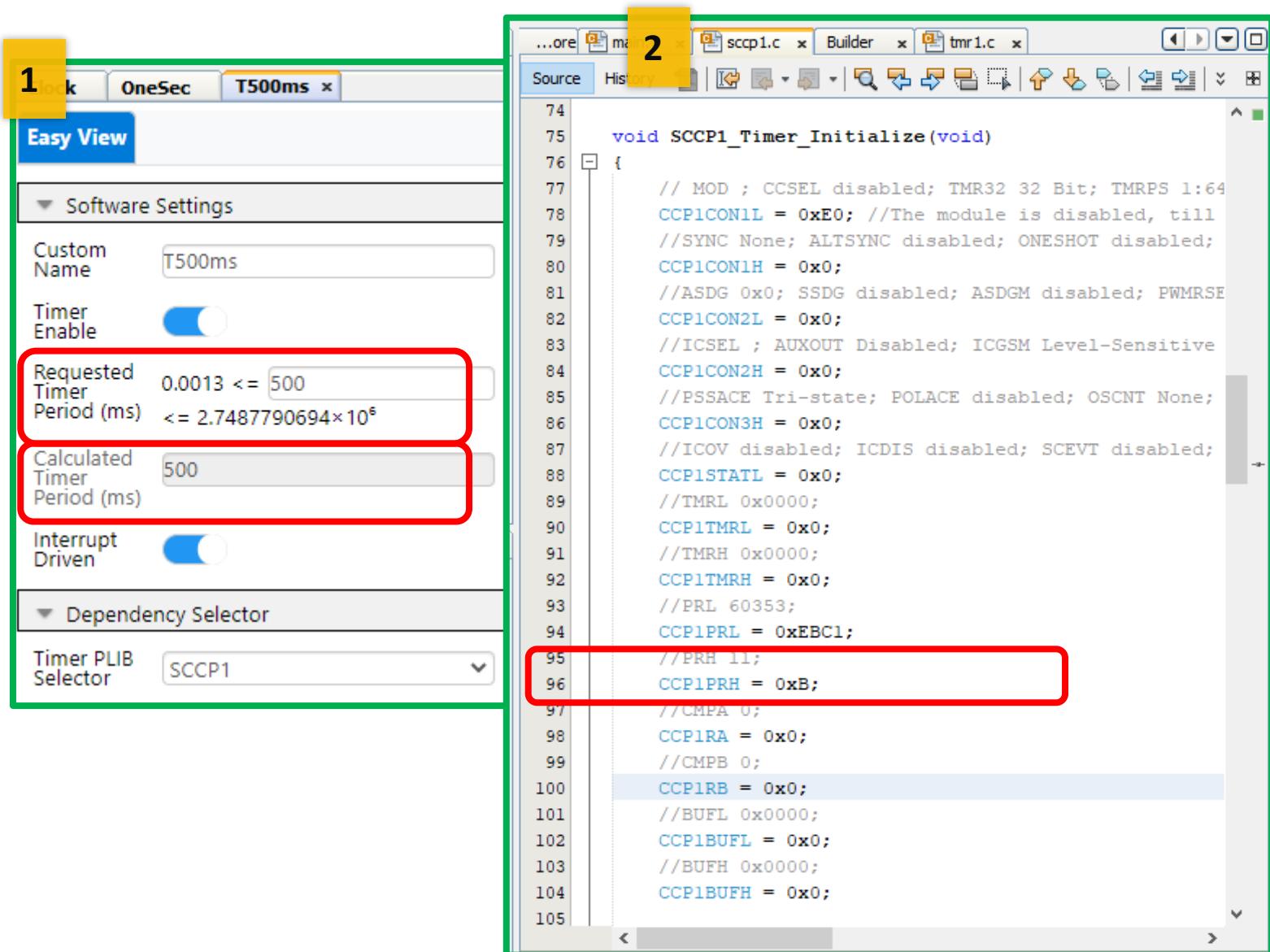
3

Easy View	SCCP1 PLIB
<b>Software Settings</b>	<b>Software Settings</b>
Custom Name: OneSec	Custom Name: OneSec
Timer Enable: On	Timer Enable: On
Requested Timer Period (ms): 0 <= 1000 <= 167.7722 should be <= 167.7722	Requested Timer Period (ms): 0.0003 <= 1000 <= 2097.152
Calculated Timer Period (ms): 0	Calculated Timer Period (ms): 1000
Interrupt Driven: On	Interrupt Driven: On
<b>Dependency Selector</b>	<b>Dependency Selector</b>
Timer PLIB Selector: TMR1	Timer PLIB Selector: TMR1

## 6. 修正LED1~4

T500ms

- 1) 查看T500ms設定  
發現沒有警告
  - 2) 開啟sccp1.c程式  
 $CCP1PRH = 0xB$ ; 不是零  
所以不能用16-bit Timer模式



# 6-1. 修正LED1~4

T500ms

- 1) 開啟SCCP1 PLIB 修改頻率來源成REFO
- 2) 到Clock改REFO為4MHz
- 3) 再產生一次CODE
- 4) 觀看sccp1.c  
CCP1PRL = 0x7A11;  
CCP1PRH = 0x0;

```
...re main.c sccp1.c Builder tmr
Source History
93 //PRL 31249;
94 CCP1PRL = 0x7A11;
95 //PRH 0;
96 CCP1PRH = 0x0;
97 //CMPA 0;
98 CCP1RA = 0x0;
```

1 SCCP1 PLIB x Easy View Register Initialization

Time Base Generator Settings

Clock Source: REFO (selected)

Calculated System Frequency(FOSC): 200.00 MHz

Calculated Peripheral Frequency(FOSC/2): 100.00 MHz

PLL Output Frequency(FPLLO): 400.00 MHz

VCO Frequency(FVCO): 400.00 MHz

FVCO Divider: 4

VCO Divider Frequency(FVCODIV): 100.00 MHz

Auxiliary Output Settings

Auxiliary Output Selection: Disabled

MCC v5.3.7

Project Resources

Generate

2 Clock x OneSec T500ms

Easy View

System Clock

System Clock Source: FRC Oscillator with PLL

Set System(FOSC) Frequency to Maximum: On

Calculated System Frequency(FOSC): 200.00 MHz

Calculated Peripheral Frequency(FOSC/2): 100.00 MHz

PLL Output Frequency(FPLLO): 400.00 MHz

VCO Frequency(FVCO): 400.00 MHz

FVCO Divider: 4

VCO Divider Frequency(FVCODIV): 100.00 MHz

Reference Clock

Reference Clock Enable: On

REFO Clock Source: FRC Oscillato

Requested REFO Frequency(in Hz): 4000000

Calculated REFO Frequency: 4.00 MHz

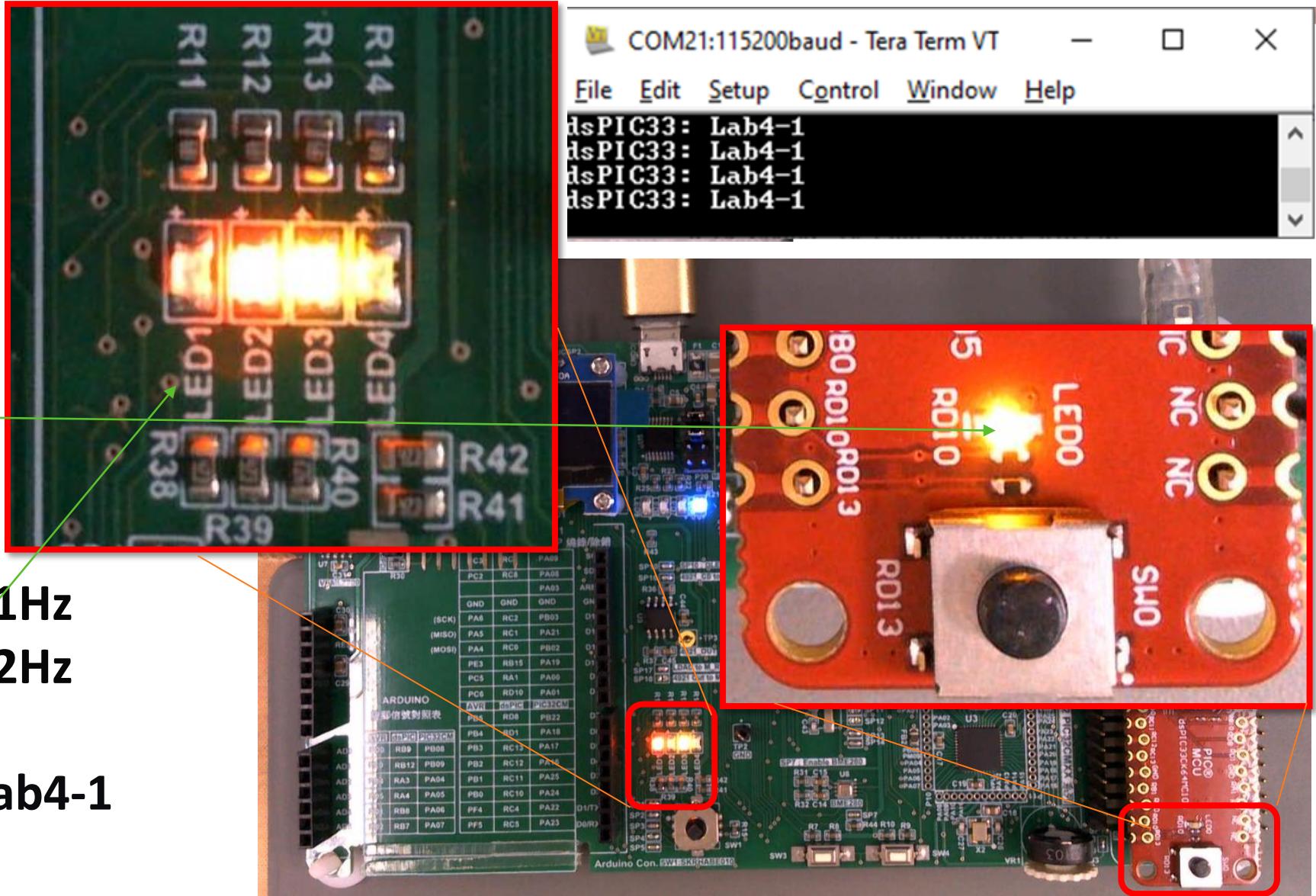
# 7.結果 回復原來樣貌

## 1) 燒錄測試

2) 結果  
小板上  
LED0閃爍 1Hz

大板上  
LED1~2交互慢閃 1Hz  
LED3~4交互快閃 2Hz

PC顯示 dsPIC33: Lab4-1



# 實驗六

---

Config(Special Features)

# 內建硬體程式開發

## 實驗六：Config(Special Features)

- 本實驗目的：
  - 了解Special Features有哪些設定
  - 會影響那些動作
  - 詳細內容哪裡找
  - 測試看門狗WDT
- 結果呈現：
  - LED0 亮1 Hz
  - LED1,2 亮1 Hz
  - LED3,4 亮2 Hz

# 背景知識

---

dsPIC33CK datasheet

# Config 在設什麼

- Config : IC的特殊功能(Special Features)

## 軟體執行前， 對IC的設定

例如：  
時脈來源選定、看  
門狗(WDT)是否開  
啟、Flash內資料是  
否可透過燒錄器被  
讀取(Code Protection Enable)  
等

# dsPIC33CK64MC105 FAMILY

## 28.0 SPECIAL FEATURES

**Note:** This data sheet summarizes the features of the dsPIC33CK64MC105 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip website ([www.microchip.com](http://www.microchip.com)).

The dsPIC33CK64MC105 family devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard™ Security
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming™ (ICSP™)
- In-Circuit Emulation
- Brown-out Reset (BOR)

## 28.1 Configuration Bits

In dsPIC33CK64MC105 family devices, the Configuration Words are implemented as volatile memory. This means that configuration data will get loaded to volatile memory (from the Flash Configuration Words) each time the device is powered up. Configuration data are stored at the end of the on-chip program memory space, known as the Flash Configuration Words. Their specific locations are shown in Table 28-1. The configuration data are automatically loaded from the Flash Configuration Words to the proper Configuration Shadow registers during device Resets.

**Note:** Configuration data are reloaded on all types of device Resets.

When creating applications for these devices, users should always specifically allocate the location of the Flash Configuration Words for configuration data in their code for the compiler. This is to make certain that program code is not stored in this address when the code is compiled. Program code executing out of configuration space will cause a device Reset.

**Note:** Performing a page erase operation on the last page of program memory clears the Flash Configuration Words.

# 資料存放相關位置

## 記憶體安排

TABLE 28-1: dsPIC33CKXXMCX0X CONFIGURATION ADDRESSES

Register Name	64k	32k
FSEC	0x00AF00	0x005F00
FBSLIM	0x00AF10	0x005F10
FSIGN	0x00AF14	0x005F14
FOSCSEL	0x00AF18	0x005F18
FOSC	0x00AF1C	0x005F1C
FWDT	0x00AF20	0x005F20
FPOR	0x00AF24	0x005F24
FICD	0x00AF28	0x005F28
FDMTIVTL	0x00AF2C	0x005F2C
FDMTIVTH	0x00AF30	0x005F30
FDMTCNTL	0x00AF34	0x005F34
FDMTCNTH	0x00AF38	0x005F38
FDMT	0x00AF3C	0x005F3C
FDEVOPT	0x00AF40	0x005F40
FALTREG	0x00AF44	0x005F44

# 詳細內容

## Datasheet中有各個bit說明

TABLE 28-2: CONFIGURATION REGISTERS MAP

Register Name	Bits 23-16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FSEC	—	AIVTDIS	—	—	—	CSS[2:0]		CWRP	GSS[1:0]	GWRP	—	BSEN	BSS[1:0]	BWRP			
FBSLIM	—	—	—	—						BSLIM[12:0]							
FSIGN	—	r <sup>(2)</sup>	—	—	—	—	—	—	—	—	—	—	—	—	—	—	
FOSCSEL	—	—	—	—	—	—	—	—	—	IESO	—	—	—	—	—	FNOSC[2:0]	
FOSC	—	—	—	—	XTBST	XTCFG[1:0]		PLLKEN	FCKSM[1:0]	—	—	—	OSCIOFNC	POSCMD[1:0]			
FWDT	—	FWDTEN	SWDTPS[4:0]					WDTWIN[1:0]	WINDIS	RCLKSEL[1:0]	RWDTAPS[4:0]						
FPOR	—	—	—	—	—	—	r <sup>(1)</sup>	—	—	BISTDIS	r <sup>(1)</sup>	r <sup>(1)</sup>	—	—	—	—	
FICD	—	—	—	—	—	—	—	—	r <sup>(1)</sup>	—	JTAGEN	—	—	—	—	ICS[1:0]	
FDMTIVTL	—	DMTIVT[15:0]															
FDMTIVTH	—	DMTIVT[31:16]															
FDMTCNTL	—	DMTCNT[15:0]															
FDMTCNTH	—	DMTCNT[31:16]															
FDMT	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	DMTDIS	
FDEVOPT	—	—	—	SPI2PIN	—	—	SMB3EN	r <sup>(2)</sup>	r <sup>(2)</sup>	r <sup>(1)</sup>	—	—	—	ALTI2C1	r <sup>(1)</sup>	—	
FALTREG	—	—	CTX4[2:0]			—	CTX3[2:0]			—	CTX2[2:0]			—	CTX1[2:0]		

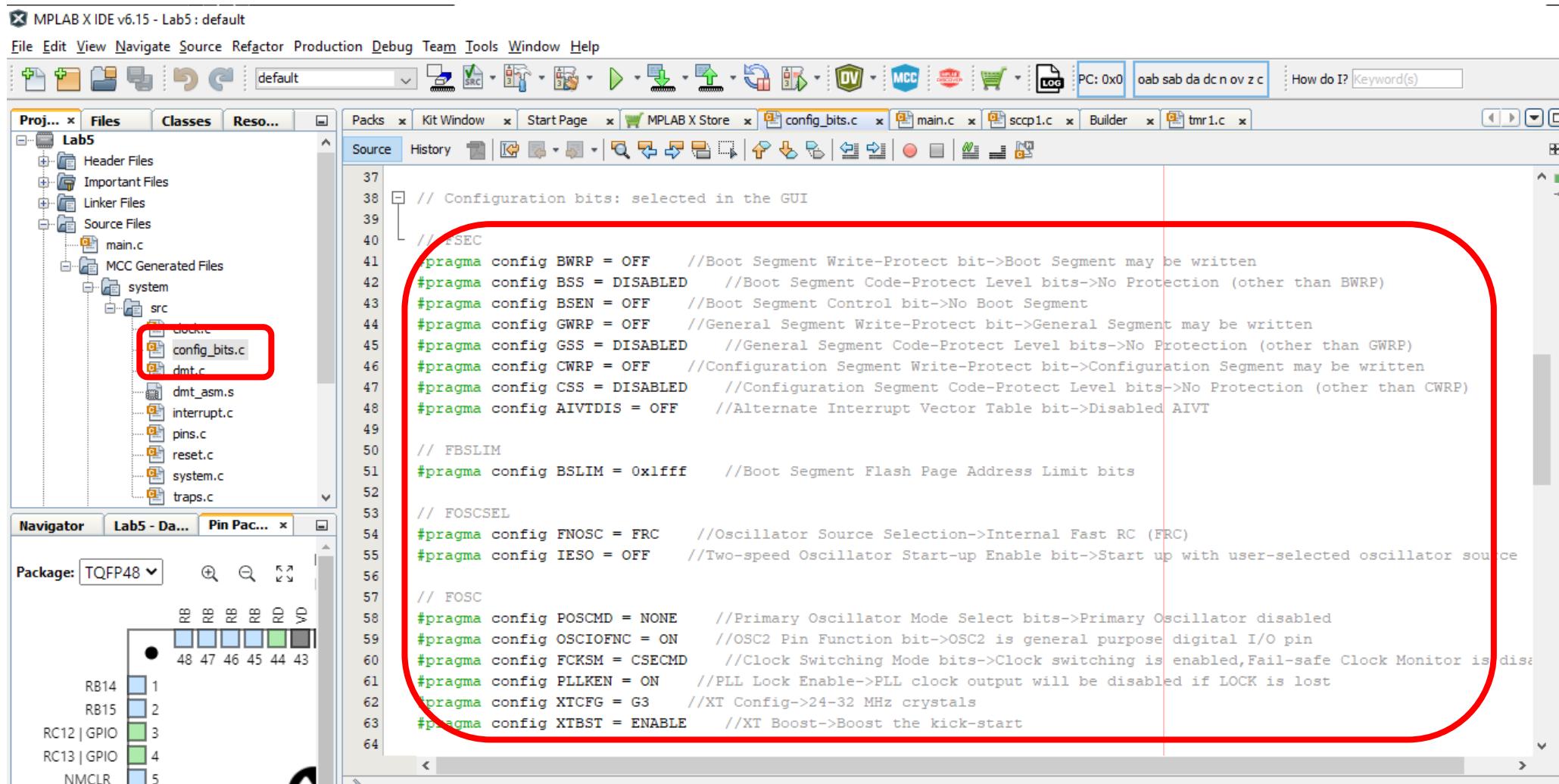
Legend: — = unimplemented bit, read as '1'; r = reserved bit.

Note 1: Bit reserved, maintain as '1'.

2: Bit reserved, maintain as '0'.

# 程式存放位置

xxx\Lab\Lab5.X\mcc\_generated\_files\system\src\config\_bits.c



The screenshot shows the MPLAB X IDE interface with the project 'Lab5' open. The 'Files' tab is selected in the toolbar. The left sidebar displays the project structure under 'Source Files', including 'main.c', 'MCC Generated Files', 'system', and 'src'. Inside 'src', the files 'clock.c', 'config\_bits.c', 'dmt.c', 'dmt\_asm.s', 'interrupt.c', 'pins.c', 'reset.c', 'system.c', and 'traps.c' are listed. The file 'config\_bits.c' is highlighted with a red box. The main editor window shows the code for 'config\_bits.c', which contains various #pragma config statements for configuration bits. A large red box highlights the entire code block in the editor.

```
37
38 // Configuration bits: selected in the GUI
39
40 // FSEC
41 #pragma config BWRP = OFF      //Boot Segment Write-Protect bit->Boot Segment may be written
42 #pragma config BSS = DISABLED  //Boot Segment Code-Protect Level bits->No Protection (other than BWRP)
43 #pragma config BSEN = OFF      //Boot Segment Control bit->No Boot Segment
44 #pragma config GWRP = OFF      //General Segment Write-Protect bit->General Segment may be written
45 #pragma config GSS = DISABLED  //General Segment Code-Protect Level bits->No Protection (other than GWRP)
46 #pragma config CWRP = OFF      //Configuration Segment Write-Protect bit->Configuration Segment may be written
47 #pragma config CSS = DISABLED  //Configuration Segment Code-Protect Level bits->No Protection (other than CWRP)
48 #pragma config AIVTDIS = OFF    //Alternate Interrupt Vector Table bit->Disabled AIWT
49
50 // FBSLIM
51 #pragma config BSLIM = 0x1fff  //Boot Segment Flash Page Address Limit bits
52
53 // FOSCSEL
54 #pragma config FNOSC = FRC     //Oscillator Source Selection->Internal Fast RC (FRC)
55 #pragma config IESO = OFF       //Two-speed Oscillator Start-up Enable bit->Start up with user-selected oscillator source
56
57 // FOSC
58 #pragma config POSCMD = NONE   //Primary Oscillator Mode Select bits->Primary Oscillator disabled
59 #pragma config OSCIOFNC = ON    //OSC2 Pin Function bit->OSC2 is general purpose digital I/O pin
60 #pragma config FCKSM = CSECMOD //Clock Switching Mode bits->Clock switching is enabled,Fail-safe Clock Monitor is disabled
61 #pragma config PLLKEN = ON      //PLL Lock Enable->PLL clock output will be disabled if LOCK is lost
62 #pragma config XTCFG = G3       //XT Config->24-32 MHz crystals
63 #pragma config XTbst = ENABLE   //XT Boost->Boost the kick-start
64
```

# Config設定

## 常見問題

- 時脈來源( **FNOSC** )

- 須搭陪外部電路，例如選外部Oscillator卻沒接，將無法運行

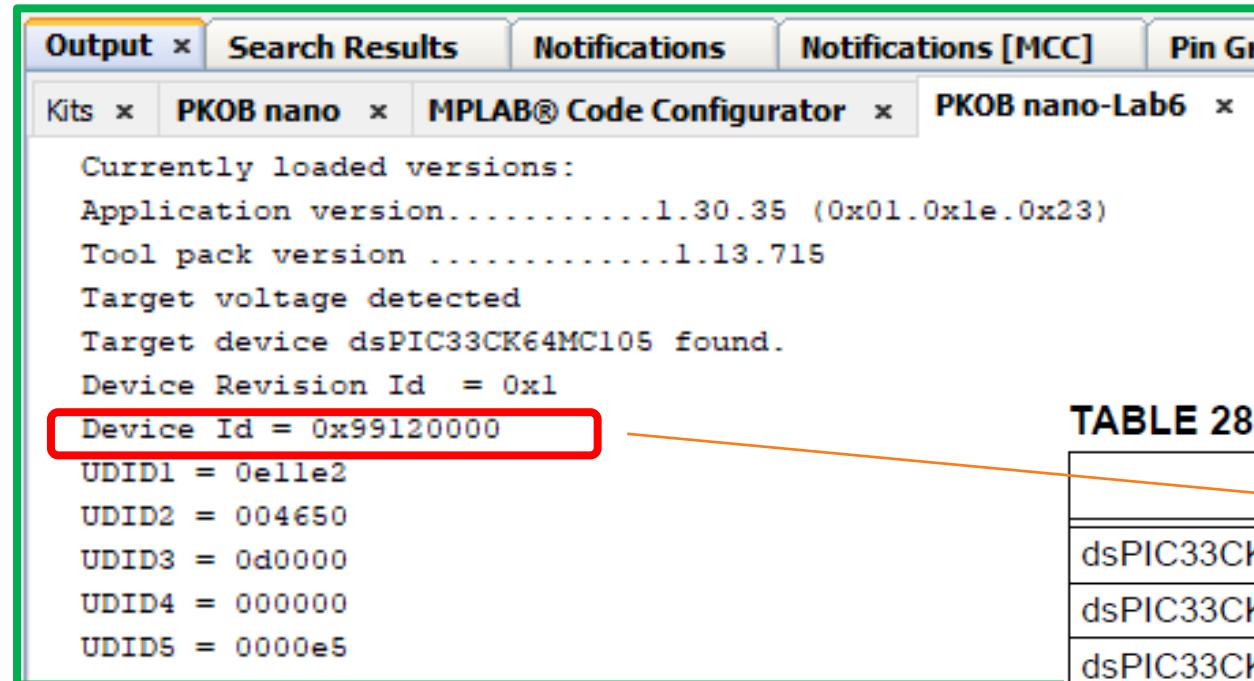
- Crystal驅動(**XTCFG**)

- 不同石英需搭配不同驅動器、耗電也不同，選錯振不起來
  - 例如4~8 MHz Gain值選0

- 啟動看門狗(**FWDTEN**、**WDTCON**)

- 須搭陪軟體，啟動後軟體沒定時復歸，MCU會一值**RESET**

# IC型號 辨別同一家族IC



Output x Search Results Notifications Notifications [MCC] Pin Gr  
Kits x PKOB nano x MPLAB® Code Configurator x PKOB nano-Lab6 x  
Currently loaded versions:  
Application version.....1.30.35 (0x01.0x1e.0x23)  
Tool pack version .....1.13.715  
Target voltage detected  
Target device dsPIC33CK64MC105 found.  
Device Revision Id = 0x1  
Device Id = 0x99120000  
UDID1 = 0elle2  
UDID2 = 004650  
UDID3 = 0d0000  
UDID4 = 000000  
UDID5 = 0000e5

TABLE 28-3: DEVICE IDs FOR THE dsPIC33CK64MC105 FAMILY

Device	DEVID
dsPIC33CK64MC105	0x9912
dsPIC33CK64MC103	0x9911
dsPIC33CK64MC102	0x9910
dsPIC33CK32MC105	0x9902
dsPIC33CK32MC103	0x9901
dsPIC33CK32MC102	0x9900

# 其他內建功能

## OTP、VREG、BOR

- **User OTP Memory**

- 內建64 bit OTP 記憶體
- 此區只可寫一次，可用於存工廠資訊，防止出貨後被變動

- **On-Chip Voltage Regulator(VREGCON)**

- 可讓PLL電路跑在1.2V，達到省電，但此時系統也不能跑太快<8MHz

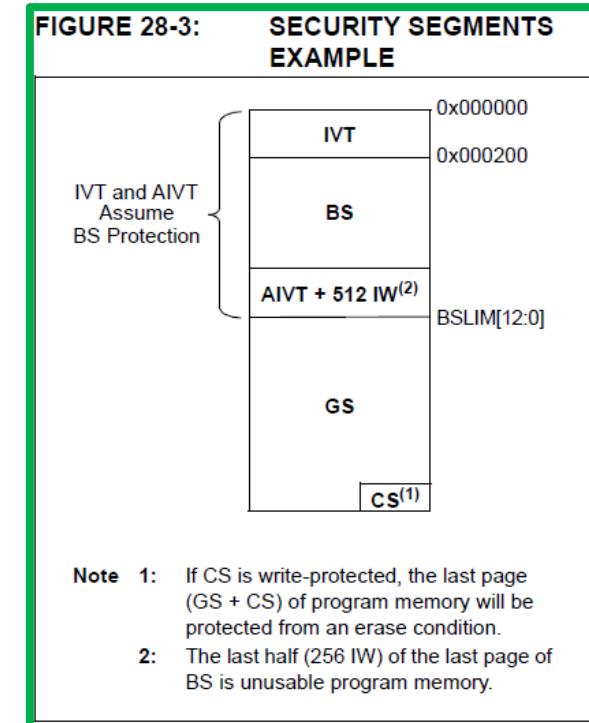
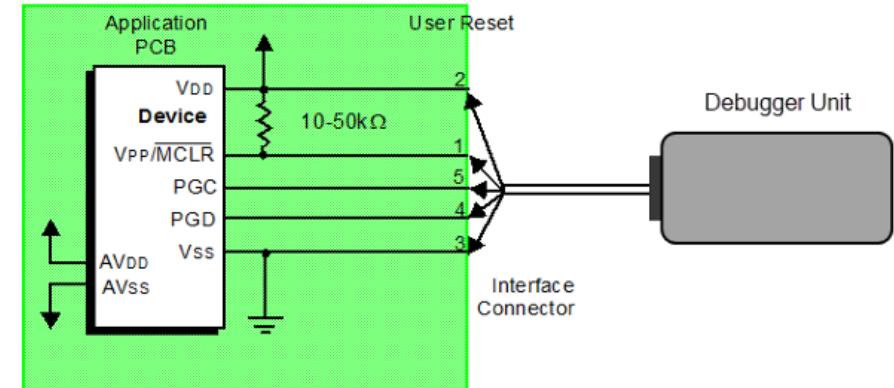
- **Brown-out Reset (BOR)**

- 避免系統電壓不穩誤動作，穩定前MCU處於RESET狀態

# 其他內建功能

## JTAG、Code Protection

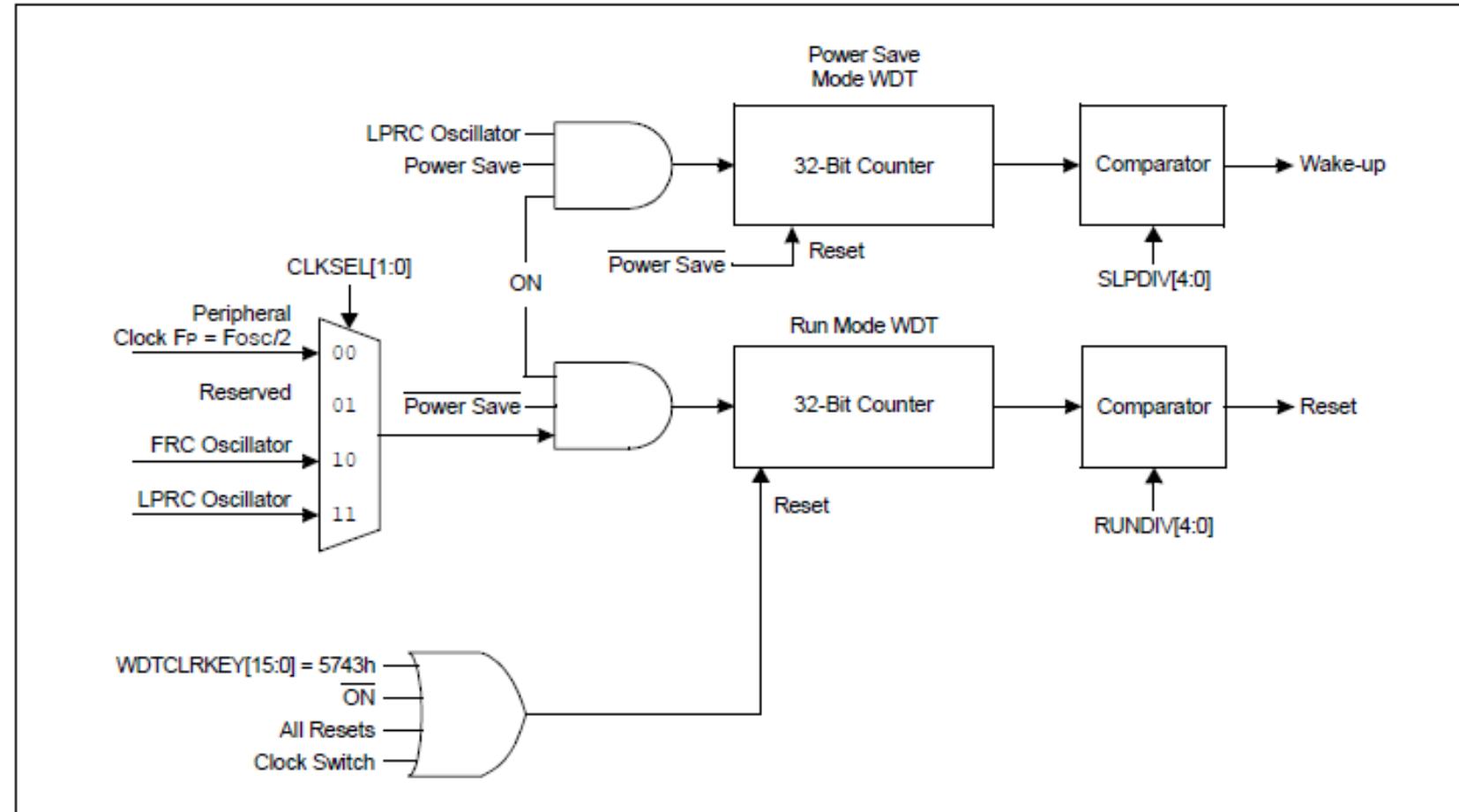
- In-Circuit Serial Programming™(ICSP™)
- In-Circuit Debugger
  - Microchip MCU的燒錄及除錯介面
  - 此IC有多組PGC及PGD，選一組連接到燒錄器(ICD、PICKit等...)
  - 需搭配設定，**選錯**debug時無法進入debug模式
- Code Protection 及 CodeGuard™ Security
  - 不同區，可做不同設定(No, Standard, Enhanced, High Security)
  - 開機區：Boot Segment (BS)
  - 應用程式區：General Segment(GS)
  - 硬體設定區：Configuration Segment (CS)
- IVT：中斷向量表 (Interrupt Vector Table)
- AIVT：備用中斷向量表 (Alternate Interrupt Vector Table)



# Watchdog架構圖

- 可以用Config或軟體啟動
- WDT也有多個CLK來源
- 一般用跟主系統不同
- 常見32KHz  
所以Timer精細度比較差

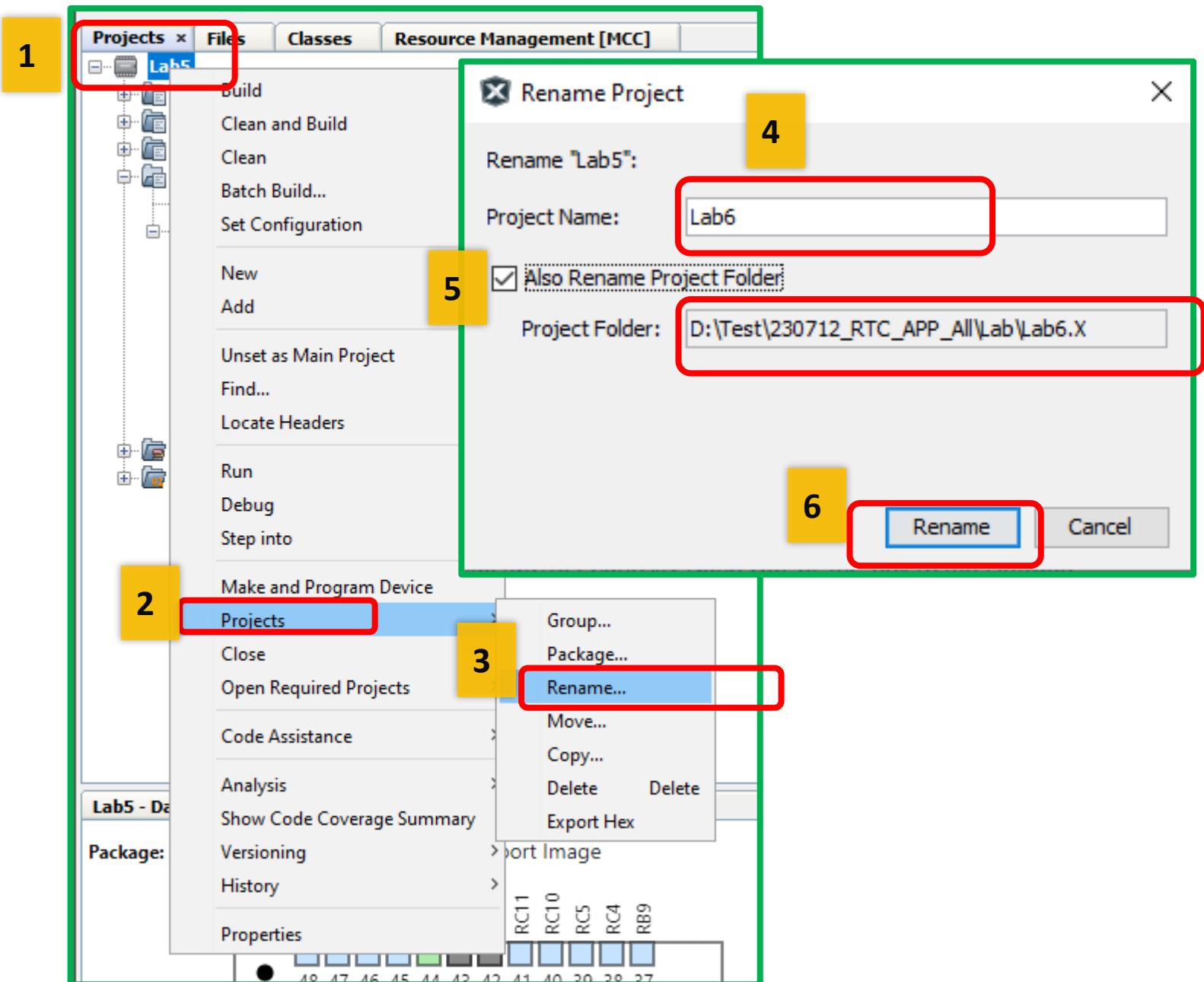
FIGURE 28-2: WATCHDOG TIMER BLOCK DIAGRAM



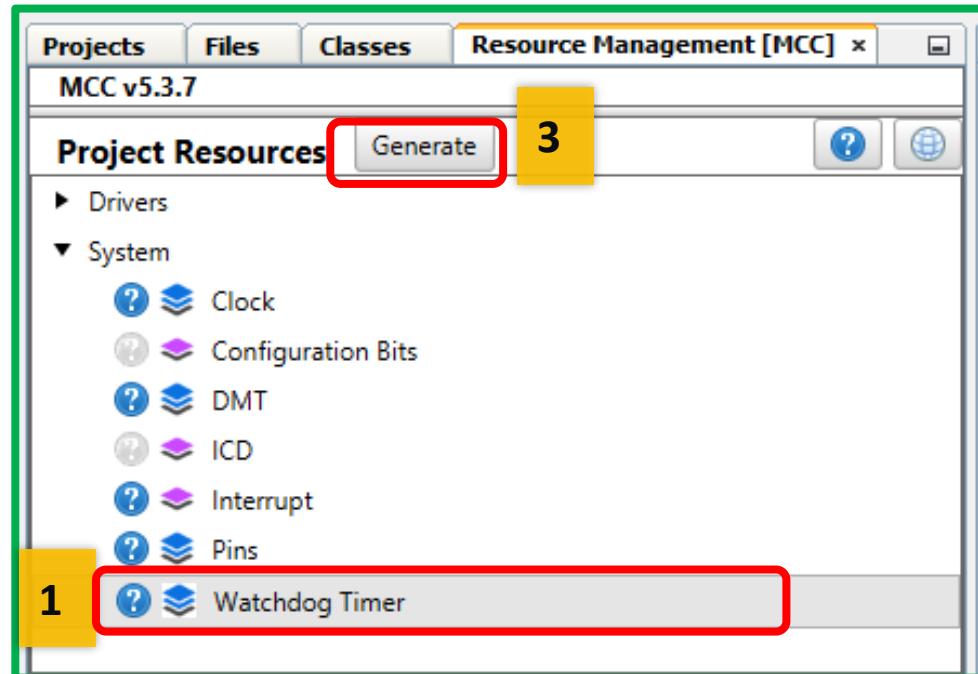
# 1. 建立Lab5

## 將Lab 5改名成Lab6

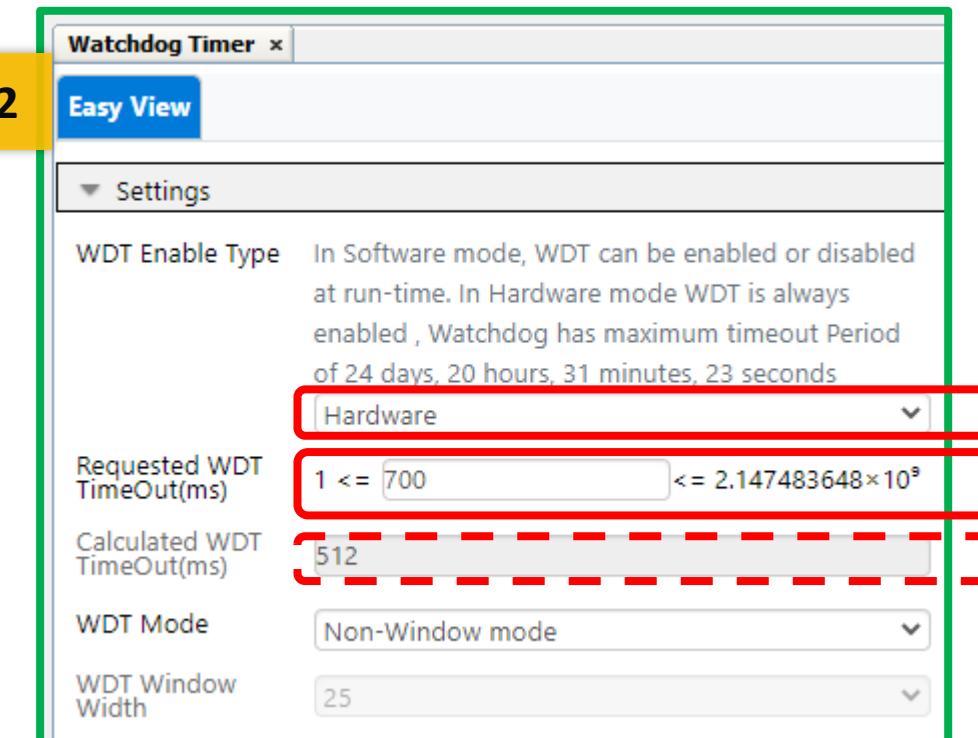
- 1) 到Projects 在Lab4上  
滑鼠點右鍵
- 2) 找到Projects
- 3) 找到Rename
- 4) 修改成Lab6
- 5) 勾選順便改資料夾名
- 6) 按 Rename - 完成名稱修改



## 2. 開啟MCC 設定Watchdog



- 1) 到Project Resources  
找System ,找Watchdog Timer,點選
- 2) 到Watchdog Timer的 Easy View  
選Hardware啟動  
改700ms 實際 512ms
- 3) 產生Code



# 3.結果

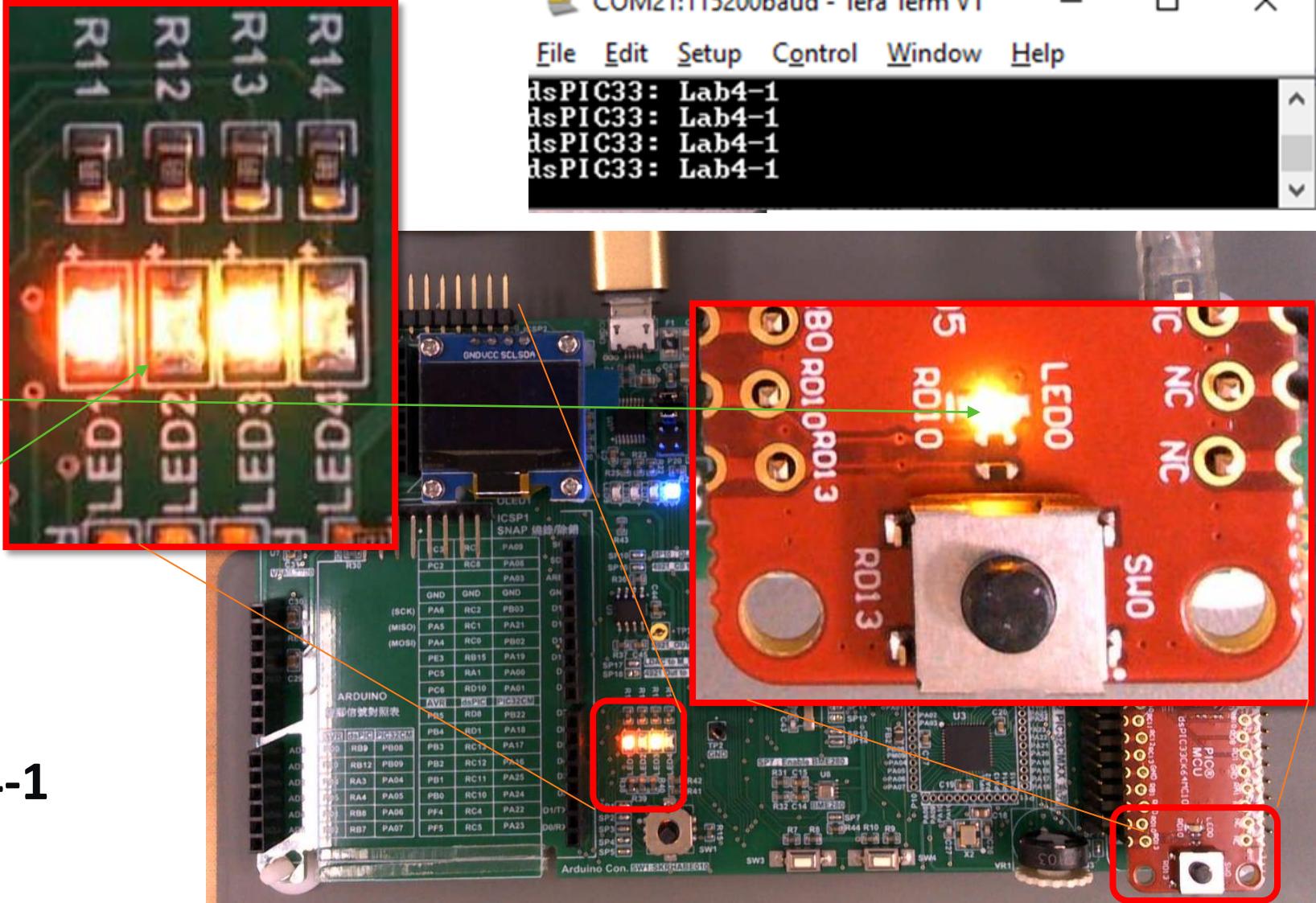
## Lab6

1) 燒錄測試

2) 結果  
小板上  
LED0 看起來恆亮

大板上  
LED1 看起來恆亮  
LED2 小閃一下  
LED3~4交互快閃

PC顯示 dsPIC33: Lab4-1



# 4. 修正 加入Clear WDT

- 1) 開啟main.c
  - 2) 到while(1){}
  - 3) 加入WATCHDOG\_TimerClear();
  - 4) 函式來源 watchdog.h
  - 5) 燒錄

...ow Packs x Start Page watchdog.h x main.c x MPLAB X Store x Builder x clock.c x

Source History

```
70 }  
71  
72 /**/  
73 * @ingroup watchdogdriver  
74 * @brief This inline function is used to clear the Watchdog Timer (WDT)  
75 * @param none  
76 * @return none  
77 */  
78 inline static void WATCHDOG_TimerClear(void)  
79 {  
80     WDTCONH = WATCHDOG_CLR_KEY;  
81 }  
82  
83 #endif /* WATCHDOG_H */  
84 /**/  
85 End of File  
86 */
```

The screenshot shows the MPLAB X IDE interface with the following details:

- Title Bar:** The title bar displays "main.c" as the active file, highlighted with a red box.
- Source Tab:** The "Source" tab is selected in the tabs at the top left.
- Code Area:** The main window contains C code for a dsPIC33 microcontroller. A yellow box labeled "1" highlights the line "printf("dsPIC33: Lab4-1\r\n");".
- Line Number 64:** A yellow box labeled "2" highlights the line "WATCHDOG\_TimerClear();". This line is enclosed in a red box.
- Code Content:** The code includes function registrations for timers and a main loop with watchdog clearing and CCP1IF handling.

```
Kit Window x Packs x Start Page x main.c x MPLAB X Store x Builder x
Source History |              
59     OneSec_TimeoutCallbackRegister(OneSec_Callback);
60     T500ms_TimeoutCallbackRegister(T500ms_CallBack);
61
62     printf("dsPIC33: Lab4-1\r\n");
63
64     while(1)
65     {
66         WATCHDOG_TimerClear();
67
68         if(IFSObits.CCP1IF==1)
69         {
70             IFS0bits.CCP1IF = 0;
71             LED3_Toggle();
72             LED4_Toggle();
73         }
74     }
75 }
```

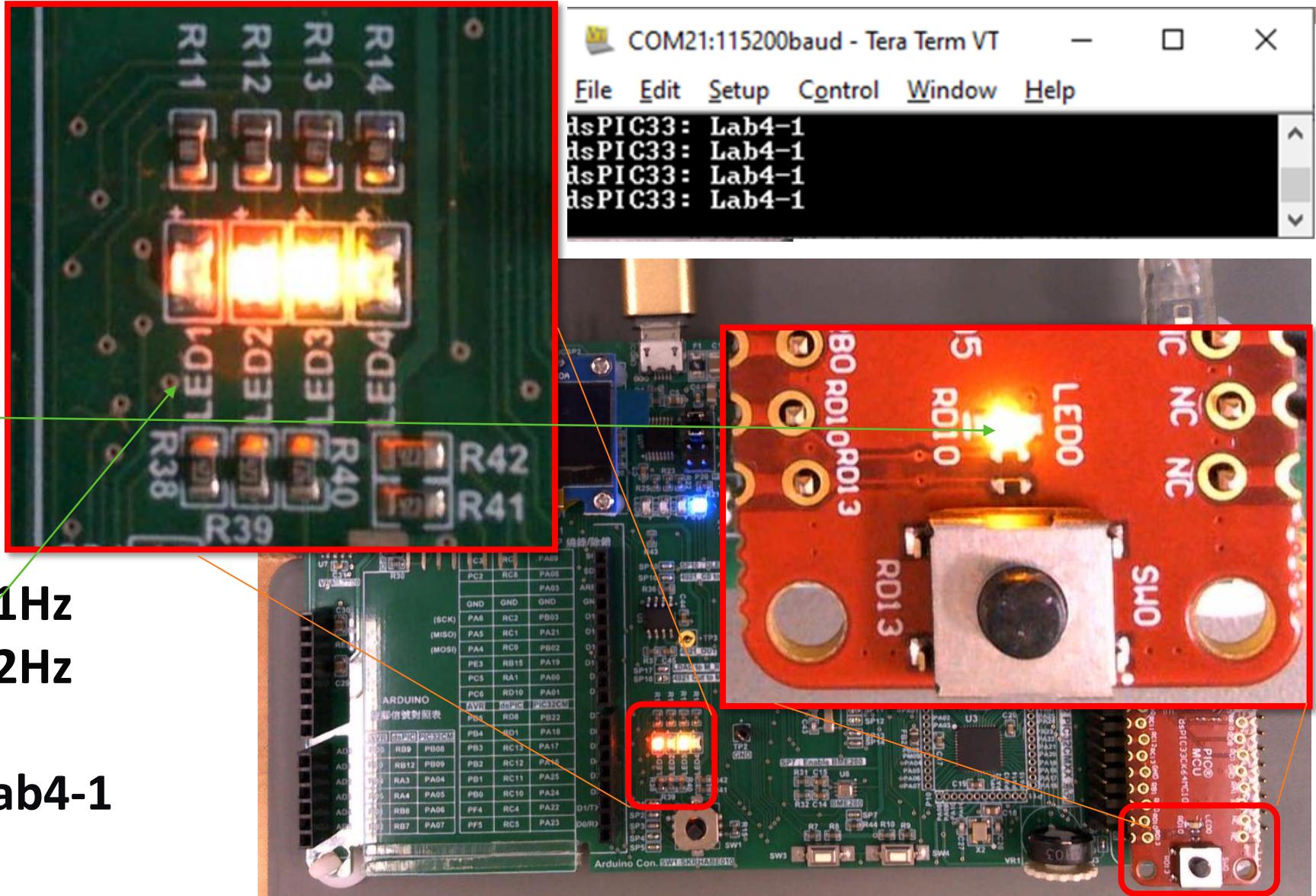
# 5.結果 回復原來樣貌

1) 燒錄測試

2) 結果  
小板上  
LED0閃爍 1Hz

大板上  
LED1~2交互慢閃 1Hz  
LED3~4交互快閃 2Hz

PC顯示 dsPIC33: Lab4-1



感謝各位的參與

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# 參考文件

- **Oscillator Module with High-Speed PLL**

- <https://ww1.microchip.com/downloads/en/DeviceDoc/dsPIC33-PIC24-FRM-Oscillator-Module-with-High-Speed-PLL-70005255b.pdf>

- **Dual Watchdog Timer**

- <https://ww1.microchip.com/downloads/aemDocuments/documents/MCU16/ProductDocuments/ReferenceManuals/dsPIC33-PIC24-FRM-Dual-Watchdog-Timer-DS70005250.pdf>

- **CodeGuard™ Intermediate Security**

- <https://ww1.microchip.com/downloads/aemDocuments/documents/OTH/ProductDocuments/ReferenceManuals/70005182a.pdf>